

Universality of the ESD for a fixed matrix plus small random noise: A stability approach¹

Philip Matchett Wood

Department of Mathematics, University of Wisconsin-Madison, 480 Lincoln Dr., Madison, WI 53706, USA. E-mail: pmwood@math.wisc.edu

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Abstract. We study the empirical spectral distribution (ESD) in the limit where $n \rightarrow \infty$ of a fixed n by n matrix M_n plus small random noise of the form $f(n)X_n$, where X_n has iid mean 0, variance $1/n$ entries and $f(n) \rightarrow 0$. It is known for certain M_n , in the case where X_n is iid complex Gaussian, that the limiting distribution of the ESD of $M_n + f(n)X_n$ can be dramatically different from that for M_n . We prove a general universality result showing, with some conditions on M_n and $f(n)$, that the limiting distribution of the ESD does not depend on the type of distribution used for the random entries of X_n . We use the universality result to exactly compute the limiting ESD for two families where it was not previously known. The proof of the main result incorporates the Tao–Vu replacement principle and a version of the Lindeberg replacement strategy, along with the newly-defined notion of stability of sets of rows of a matrix.

Résumé. Nous étudions la distribution spectrale empirique (DSE) dans la limite $n \rightarrow \infty$ d'une matrice M_n , de taille n par n , plus un petit bruit aléatoire de la forme $f(n)X_n$, où X_n a des entrées iid centrées, avec variance $1/n$, et $f(n) \rightarrow 0$. Il est connu que pour certaines matrices M_n , dans le cas où X_n a des entrées complexes gaussiennes iid, alors la distribution limite de la DSE de $M_n + f(n)X_n$ peut être radicalement différente de celle de M_n . Nous prouvons un résultat général d'universalité en montrant, sous quelques conditions sur M_n et $f(n)$, que la distribution limite de la DSE ne dépend pas du type de la distribution des entrées aléatoires de X_n . Nous utilisons ce résultat d'universalité pour calculer exactement la limite de la DSE pour deux familles pour lesquelles le résultat n'était pas connu auparavant. La preuve du résultat principal incorpore le principe de remplacement de Tao–Vu et une version de la stratégie de remplacement de Lindeberg, avec une notion nouvelle de stabilité d'ensembles de lignes d'une matrice.

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1. Introduction

Given an n by n complex matrix A , we define the *empirical spectral distribution* (which we will abbreviate *ESD*), to be the following discrete probability measure on $\mathbb{C}$:

$$\mu_A(z) := \frac{1}{n} \sum_{j=1}^n \delta_{\lambda_j},$$

where $\lambda_1, \lambda_2, \dots, \lambda_n$ are the eigenvalues of A with multiplicity and δ_x is the Dirac measure centered at x . For a sequence of random matrices A_n , we say that μ_{A_n} *converges in probability* to another probability measure μ if for

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every smooth, compactly supported test function $g : \mathbb{C} \rightarrow \mathbb{C}$ we have that $\int_{\mathbb{C}} g d\mu_{A_n}$ converges in probability to $\int_{\mathbb{C}} g d\mu$.

Questions about the limiting distribution of the ESD of random matrices started in the 1950s and have generated much recent interest. The circular law states that the ESD of a random n by n matrix X_n with iid mean 0, variance $1/n$ entries converges to the uniform measure on the unit disk. The circular law was proven following a long line of work including Mehta [17] (complex Gaussian case), Girko [11,12] (introducing the Hermitization approach), Edelman [8] (real Gaussian case), Bai [2] and Bai–Silverstein [1] (continuous case with bounded $(2 + \delta)$ th moment, for $\delta > 0$), Götze–Tikhomirov [13] (sub-Gaussian case) and [14] (bounded $(2 + \delta)$ th moment, for $\delta > 0$), Pan–Zhao [18] (bounded 4th moment), and Tao–Vu [23] (bounded $(2 + \delta)$ th moment, for $\delta > 0$), with the circular law as stated above proved by Tao and Vu in [25]. (For more, see the surveys [5,20] and references therein.) Low rank perturbations of random matrices with iid entries do not change the limiting bulk ESD, even for perturbations up to rank $o(n)$ (see [25, Corollary 1.12], [6], and [4]); however, such perturbations can produce outlier eigenvalues – see [21,22].

Limiting distributions of ESDs of an entirely different type of random matrix – based on uniform Haar measure – have also generated much interest, including the recent work [15] proving the Single Ring Theorem (there is an interesting outlier phenomenon for the Single Ring Theorem as well, see [3]). It is shown in [15, Proposition 4] that adding polynomially small iid complex Gaussian noise expands the class of random matrices to which the Single Ring Theorem applies, essentially removing a hypothesis about the smallest singular value. This fact inspired further work [16] studying how adding polynomially small iid complex Gaussian noise can change the limiting ESD – in some cases quite dramatically – of a sequence of fixed matrices, and that it turn lead the current paper to study the effects on the ESD of adding small iid *non*-Gaussian random noise.

We will consider the case where M_n is a fixed sequence of n by n complex matrices, to which we will add small random noise to get $A_n = M_n + f(n)X_n$, where X_n is a random complex n by n matrix with iid mean 0, variance $1/n$ entries, and $f(n) \rightarrow 0$ as $n \rightarrow \infty$. We will refer to the case where $f(n) = n^{-\gamma}$ for some $\gamma > 0$ as *polynomially small random noise*, and we will refer to the general case as *random noise scaled by $f(n)$* . The initial motivation for this paper is the fact that, in some natural cases, the ESDs of the perturbed matrix A_n and fixed matrix M_n are very different, even when the random perturbation is very small, e.g. $f(n) = n^{-100}$. For example, the n by n nilpotent matrix

$$T_n = \begin{pmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & 0 \\ 0 & \ddots & \ddots & 0 & 1 \\ 0 & \ddots & \ddots & \ddots & 0 \end{pmatrix} \quad (1)$$

has only zero as an eigenvalue, with multiplicity n . However, if one sets $f(n) = n^{-\gamma}$ for some $\gamma > 0$ and X_n has iid complex Gaussian entries scaled by $1/n$, then the ESD of $A_n = M_n + f(n)X_n$ converges in probability to the uniform distribution on the unit circle $\{z : |z| = 1\}$ (proven in [16]; see also [19]). Figure 1 plots the eigenvalues for $\gamma = 10$ and $n = 50, 500$, and 5000 .

Interestingly, the ESD of T_n remains unstable even after polynomially small noise is added, in the sense that a low-rank perturbation (namely rank $o(n)$) of $T_n + n^{-\gamma}X_n$ can change the limiting ESD – see [16, Corollary 8]. This contrasts with low-rank perturbations of the circular law, in which case any rank $o(n)$ perturbation added to the random matrix X_n still has ESD that converges to uniform on the unit disk (see [25, Corollary 1.12], [6], and [4]).

The matrix T_n shows that the ESD can be very sensitive to small perturbations (this has been noted before; see [16,19]). In this paper, we approach the related universality question: “Is the ESD of a fixed matrix sensitive to the *type* of randomness in a small perturbation?” For example, in Figure 1, would the ESD plots look the same if the perturbation X_n had iid entries that were Bernoulli $+1/\sqrt{n}$ or $-1/\sqrt{n}$ each with probability $1/2$, rather than complex Gaussian?

The first step towards answering this question was taken in [16, Remark 3], where it is noted (thanks to a comment by R. Vershynin) that in fact the main result of [16] extends to the case where the noise matrix has entries that are iid and possess a bounded density. Of course, the bounded density assumption excludes Bernoulli random matrices. The approach in the current paper will not require entries to have bounded density.

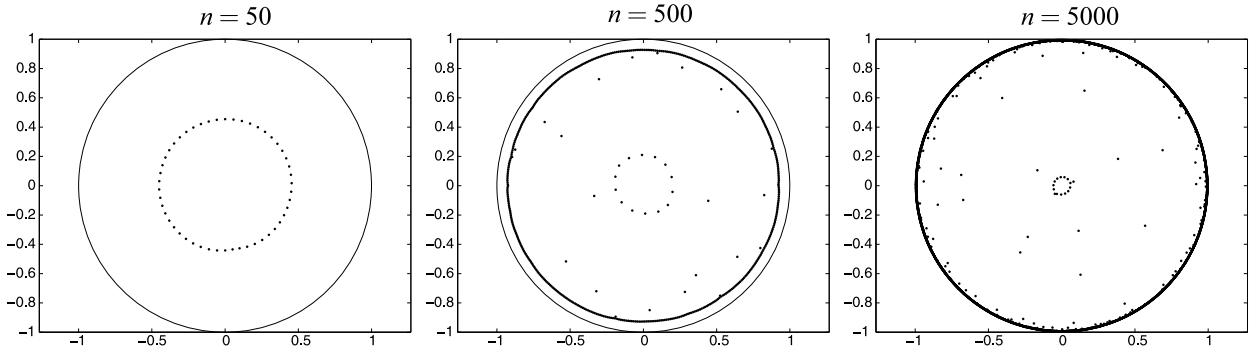


Fig. 1. The eigenvalues of T_n (see Equation (1)) plus $n^{-10}X_n$, where X_n is an n by n random iid Gaussian matrix. A circle is of radius 1 centered at the origin is plotted for comparison (not visible when $n = 5000$). With no perturbation, all eigenvalues of T_n equal zero.

In [25], Tao and Vu (with an appendix by Krishnapur) develop a general replacement principle (Theorem 6 below) that shows convergence of ESDs for random matrix models A_n and B_n if the log-determinants of $A_n + zI_n$ and $B_n + zI_n$ converge for almost every fixed complex number z , where I_n is the n by n identity matrix. This is the framework for the approach in the current paper: if a small perturbation does not change the log-determinant of $A_n + zI_n$, we can use the replacement principle to prove convergence of the ESDs.

Our focus is on matrices $M_n + zI_n$ where some (usually many) of the rows satisfy the following stability condition for almost every complex number z .

Definition 1 (ε -stable). A set of vectors $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is ε -stable if

$$\text{dist}(\mathbf{v}_j, \text{Span}\{\mathbf{v}_i : 1 \leq i \leq k, i \neq j\}) \geq \varepsilon$$

for all $1 \leq j \leq k$. In general, ε will be a function of n and other parameters.

A set of vectors that contains a linear dependence is always ε -stable only for $\varepsilon = 0$, and a set of linearly independent vectors is always ε -stable for some positive (though possibly very small) ε . For example, the n by n matrix

$$M = \begin{pmatrix} 1 & 0 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & & \ddots & & \vdots \\ 0 & 0 & \dots & 0 & 1 & 0 \\ \sqrt{\frac{1-\varepsilon^2}{n-1}} & \sqrt{\frac{1-\varepsilon^2}{n-1}} & \dots & \dots & \sqrt{\frac{1-\varepsilon^2}{n-1}} & \varepsilon \end{pmatrix}$$

has rows that are all length 1, and the set of rows is ε -stable, but is not δ -stable for any $\delta > \varepsilon$; furthermore, ε may be chosen arbitrarily small in this example. One can think of ε as quantifying the linear independence of set of vectors, for example, the last row in the matrix M above is only ε away from being linearly dependent on the first $n - 1$ rows.

The ε -stable property is reasonably general; for example, a random matrix R_n with iid mean zero, variance $1/n$ entries – thus the row vectors each have expected norm one – contains a set of $n(1 - o(1))$ rows that are ε -stable for $\varepsilon \geq n^{-1/12}/2$ (see Proposition 12); this is also true if zI_n is added to the matrix.

The ε -stability property quantifies the smallest amount one vector would have to be perturbed in order to fall into the span of the remaining vectors. Intuitively, one might think that the ESD of a matrix with all rows ε -stable would not change much under a perturbation that was much smaller than ε . For example, the set of all rows of a diagonal matrix D_n plus zI_n is always at least $\Theta(1)$ -stable for almost every $z \in \mathbb{C}$ (note z is a constant); thus, one would expect (correctly) that a small $o(1)$ perturbation of D_n has no effect on the limiting ESD (this follows from the Geršgorin Circle Theorem [10,26], for example).

However, having many ε -stable rows is not the whole story. By inductive computation, the first $n - 1$ rows of the matrix $T_n + zI_n$ are $\Theta(1)$ -stable (see Lemma 20); and yet, a small perturbation results in a dramatic change to the

ESD as shown in Figure 1. The issue is that when $|z|$ is small, the last row of $T_n + zI_n$ is only distance $O(|z|^n)$ from the span of the first $n - 1$ rows, allowing a small perturbation to produce large changes in the ESD.

It turns out that we can use bounds on the smallest singular value from [23] and the replacement principle approach from [25] to ignore a small fraction of the rows (in fact, any number $g(n) = o(n/\log n)$ can be ignored). This allows us to use the ε -stability property on the remaining rows to show that the limiting ESD does not depend on the type of randomness in the perturbation. Our main result (Theorem 2) shows for a large class of matrices M_n and for small perturbations that while the ESDs of $M_n + f(n)X_n$ and M_n may differ, the limiting distribution of the ESD of $M_n + f(n)X_n$ is unchanged if the random noise X_n is replaced by a different random matrix ensemble with iid mean 0, variance 1 entries.

Theorem 2 (Universality of small random noise). *Let M_n be sequence of complex n by n matrices satisfying*

$$\sup_n \frac{1}{n} \|M_n\|_2^2 < \infty. \quad (2)$$

Let x and y be complex random variables with mean 0 and variance 1, and let Φ_n and Ψ_n be n by n matrices having iid entries $x/\sqrt{n}$ and $y/\sqrt{n}$, respectively.

Let $A_n = M_n + n^{-\gamma}\Phi_n$ and let $B_n = M_n + n^{-\gamma}\Psi_n$, where $\gamma > 1.5$ is a constant. Assume for almost every $z \in \mathbb{C}$ that there is a set S of at least $n - n/\log^{1.1} n$ rows of $M_n + zI$ that is ε -stable, where

$$\frac{n^{3/4-\gamma/2} \log n}{\varepsilon} \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

Then $\mu_{A_n} - \mu_{B_n}$ converges in probability to zero as $n \rightarrow \infty$.

The function $n/\log^{1.1} n$ above can be replaced by any function that is $o(n/\log n)$ without changing the proof. Also, while the constraint $\gamma > 1.5$ is needed here, it is likely an artifact.

In Section 2 we will use Theorem 2 to compute the exact limiting ESD for two families of fixed matrices M_n ; both results are new. The two families are block-diagonal matrices M_n , where the diagonal blocks each equal T_k for some value k . In Theorem 3, when the diagonal blocks are small ($k \ll \log n$), all the rows in the matrix M_n are ε -stable with ε large enough that the limiting ESD is equal to the limiting ESD of the original matrix M_n (namely all zeros). In Theorem 5, when the diagonal blocks are large ($k \gg \log n$), Theorem 2 shows that the limiting ESD M_n plus any polynomial small random noise is equal to the limiting ESD of T_n plus complex Gaussian polynomially small random noise (which is uniform on the unit circle $\{z : |z| = 1\}$ by [16], see also [19]). These families of block-diagonal matrices were introduced in [16], where the case $k = c \log n$ for c a positive constant was also studied. In [16], it was shown that the limiting spectral radius when $k = c \log n$ of the block diagonal matrix M_n plus random noise scaled by $n^{-\gamma}$ with $\gamma > 5/2$ is strictly less than 1, with probability approaching 1 as $n \rightarrow \infty$. The same families of fixed matrices are studied by Feldheim, Paquette and Zeitouni [9] in the case of iid Gaussian small random noise using a different approach than that used in the current paper. Feldheim, Paquette and Zeitouni [9] prove a theorem generalizing Theorem 3 and Theorem 5 in the Gaussian case, while also allowing the block size to vary. For the iid Gaussian noise case, Feldheim, Paquette and Zeitouni [9] also determine the limiting ESD explicitly, including in the case where $k = c \log n$ for constant c , which is especially interesting since the limiting ESD depends on γ for polynomially small Gaussian noise scaled by $n^{-\gamma}$. (Note that the methods of the current paper do not directly apply when $k = c \log n$, since then there too many rows (namely $n/(c \log n)$) that must be excluded from the ε -stable set in order for ε to be large enough.)

In [19], it is shown that there exists a scaling t_n of iid complex Gaussian noise (with $t_n \rightarrow 0$) such that ESD of the matrix M_n plus the t_n -scaled Gaussian noise converges almost surely to the Brown measure. No bounds on t_n are given, however. In [16] it is shown that polynomially small noise is a sufficient: the distribution of the ESD of a matrix M_n plus polynomially small iid complex Gaussian noise converges in probability to the Brown measure of the matrix M_n , so long as the matrix M_n and the Brown measure each satisfy a certain regularity property. Theorem 2 shows that, if M_n satisfies (2) and the ε -stability condition and random noise is polynomially small, then the requirement that the perturbation Φ_n be complex Gaussian may be removed: in fact, any Φ_n with iid mean zero, variance one entries will suffice. Theorem 2 has an additional benefit in that it applies to cases where the ESD does *not* converge to the Brown

measure; in fact Theorem 3 is an example of just such a situation. The proof of Theorem 2 uses an approach that does not use the free probability machinery that features in [16, 19].

Topics are organized as follows. We can apply Theorem 2 to our motivating question, proving that the limiting ESD of T_n plus polynomially small random noise is always uniform on the unit circle; see Section 2. In Section 2 we also discuss the block-diagonal class of matrices generalizing T_n (introduced in [16]) and use Theorem 2 to compute the limiting ESD in two cases where it was previously unknown. In Section 3, we will discuss the replacement principle approach to proving universality developed by Tao and Vu [25] (see also [27]). In Section 5, we will prove that small perturbations of ε -stable sets of vectors remain $(\varepsilon/2)$ -stable, and we will show how this relates to the tools in Section 3. The proof of Theorem 2 is in Section 4.

No effort is made to optimize constants, and we will often choose explicit constants to make computations clearer. All logarithms are natural unless otherwise noted. Also, we will use $\|A\|_2 = \text{tr}(A^*A)^{1/2}$ to denote the Hilbert–Schmidt norm (also called the Frobenius norm).

2. Application to a class of non-normal matrices

In this section, we will give sketches of how the main theorem (Theorem 2) can be applied to a class of nilpotent matrices generalizing T_n that has interesting behaviors when small random noise is added. The ESDs of these matrices plus small random noise were studied in [16] (see also [19]) and also in [9].

Let b be a positive integer, and define $T_{b,n}$ to be an n by n block diagonal matrix with each $b+1$ by $b+1$ block on the diagonal equal to T_{b+1} (as defined above in Equation (1)). If $b+1$ does not divide n evenly, an additional block equal to T_k where $k \leq b$ is inserted at bottom of the diagonal (in particular, $k = n - \lfloor \frac{n}{b+1} \rfloor (b+1)$, and if $k = 0$, then no additional block is needed). Thus, every entry of $T_{b,n}$ is zero except for entries on the superdiagonal (the superdiagonal is the list of entries with coordinates $(i, i+1)$ for $1 \leq i \leq n-1$), and the superdiagonal of $T_{b,n}$ is equal to

$$(\underbrace{1, 1, \dots, 1}_b, 0, \underbrace{1, 1, \dots, 1}_b, 0, \dots, \underbrace{1, 1, \dots, 1}_b, \underbrace{0, 1, 1, \dots, 1}_{\leq b}).$$

(Note that $T_{b,n}$ was defined slightly differently in [16], in that the last (possibly non-existent) diagonal block contained all zeros.) Recall that the spectral radius of a matrix is the maximum absolute value of the eigenvalues. In [16], it was proven that the distribution of the ESD of T_n plus polynomially small Gaussian noise converges in probability to uniform on the unit circle, and it was shown for $\gamma > 5/2$ that the spectral radius of $T_{\log n, n}$, plus random noise scaled by $n^{-\gamma}$ is strictly less than 1, with probability approaching 1 as $n \rightarrow \infty$.

The matrix $T_{b,n} + zI$ has a large set of rows that are ε -stable for constant ε (depending on z), namely the set of all rows of the form $(0, \dots, 0, z, 1, 0, \dots, 0)$, a set having size at least $n - \lfloor n/(b+1) \rfloor$ (see Lemma 20). However, the ε -stability of the set of *all* rows of $T_{b,n} + zI$ is much smaller, having size $\Theta(|z|^{b+1})$ for small z , which is exponentially small when $b = \Theta(n)$ (see Lemma 21).

We can apply our main theorem to prove the following two results about the limiting ESD of $T_{b,n}$ plus polynomially small random noise, for different sizes of b .

Theorem 3 (Small blocks). *Let $T_{b,n}$ be as defined above, with $b = o(\log n)$, and let Φ_n be a random matrix with iid mean 0 variance $1/n$ entries.*

Then, the distribution of the ESD of $T_{b,n} + n^{-\gamma} \Phi_n$, where $\gamma > 1.5$, converges in probability to the Dirac measure δ_0 , with mass 1 at the origin.

Sketch. Blocks of size $b = o(\log n)$ are small enough that the ε -stability of *all* the rows of the matrix is reasonably high, namely $\varepsilon > \Omega(n^{o(1)})$ (see Lemma 21). We can apply the proof approach for the main result (Theorem 2) to show that the distribution of the ESD of $T_{b,n} + n^{-\gamma} \Phi_n$ converges in probability to the ESD of $T_{b,n}$, which has all eigenvalues equal to zero. The full details appear in Section 6. $\square$

In the case where $b_n \rightarrow \infty$ (e.g., $b_n = \log \log n$), Sniady's result [19] shows that the distribution of the ESD of the perturbation of $T_{b,n}$ converges almost surely to uniform on the unit circle $\{z : |z| = 1\}$ (matching the Brown measure),

if one perturbs with random iid complex Gaussian noise scaled by some particular t_n , where $t_n \rightarrow 0$. Theorem 3 shows that, for polynomially small random noise, the distribution of the ESD of the perturbed matrix does *not* converge to the Brown measure, but rather converges in probability to the limiting ESD of $T_{b,n}$ without perturbation (namely, the Dirac measure δ_0). Two interesting questions one might ask are what is the scaling t_n so that the ESD converges to uniform on the unit circle, and whether universality holds for that scaling t_n .

Remark 4. One could conceive of a of Theorem 2 where the random noise was scaled by an arbitrary function $f(n)$ with $f(n) \rightarrow 0$ as $n \rightarrow \infty$, rather than by $n^{-\gamma}$. The singular value bound (from [23], which is restated in Theorem 9) hold in a useful form if $f(n) \geq n^{-\gamma}$ (e.g. $f(n) = 1/\log n$), but it would not be useful for exponentially small $f(n)$. Conversely, the ε -stability condition would likely be fine for $f(n) \leq n^{-\gamma}$ (including $f(n)$ exponentially small) but is likely to be problematic when $f(n) \gg n^{-\gamma}$ (e.g. $f(n) = 1/\log n$), requiring in the latter case that ε is much larger than practical. Nonetheless, in principle, we expect – supported by some computer experimentation – that universality of the form in Theorem 2 is very robust and should hold without conditions on the size of the random noise.

Theorem 5 (Large blocks). Let $T_{b,n}$ be as defined above with $b \gg \log n$ (i.e., $b/\log n \rightarrow \infty$ as $n \rightarrow \infty$), and let Φ_n be a complex iid random matrix where each entry has mean 0 and variance $1/n$.

Then, the distribution of the ESD of $T_{b,n} + n^{-\gamma} \Phi_n$, where $\gamma > 1.5$, converges in probability to the uniform measure on the unit circle $\{z : |z| = 1\}$. In particular, by setting $b = n - 1$, we have that the distribution of the ESD of $T_n + n^{-\gamma} \Phi_n$, where $\gamma > 1.5$, converges in probability to the uniform measure on the unit circle.

Sketch. In this case, there are only $o(n/\log n)$ rows of $T_{b,n}$ that differ from the corresponding rows of T_n . We can ignore these rows using the replacement principle approach from [25] (see Section 3), thus showing that the distribution of the ESD of $T_{b,n} + n^{-\gamma} \Phi_n$ converges in probability to the distribution of the ESD of $T_n + n^{-\gamma} \Phi_n$.

Next, we can apply Theorem 2, noting that if the last row is excluded, the remaining rows are ε -stable for constant ε (Lemma 20), to show that the ESD of $T_n + n^{-\gamma} \Phi_n$ converges in probability to the ESD of $T_n + n^{-\gamma} \Psi_n$, where Ψ_n has iid complex Gaussian entries with mean 0 and variance $1/n$. This ESD in turn converges in probability to uniform on the unit circle by [16]. $\square$

3. The replacement principle approach to proving universality

In [25], Tao and Vu (with an appendix by Krishnapur) prove a general result giving sufficient conditions for the ESDs of two matrices to become close to each other.

Theorem 6 ([25]). Suppose for each n that $A_n, B_n \in \mathbb{M}_n(\mathbb{C})$ are ensembles of random matrices. Assume that

(i) The expression

$$\frac{1}{n} \|A_n\|_2^2 + \frac{1}{n} \|B_n\|_2^2$$

is bounded in probability (resp. almost surely).

(ii) For almost all complex numbers z ,

$$\frac{1}{n} \log |\det(A_n + zI)| - \frac{1}{n} \log |\det(B_n + zI)|$$

converges in probability (resp. almost surely) to zero. In particular, for each fixed z , these determinants are non-zero with probability $1 - o(1)$ for all n (resp. almost surely non-zero for all but finitely many n).

Then, $\mu_{A_n} - \mu_{B_n}$ converges in probability (resp. almost surely) to zero.

Note that Theorem 6 makes no assumption about the type of randomness in A_n and B_n , or even whether the entries are independent. We will eventually require independence of the entries in order to use bounds on the smallest singular value.

Lemma 7. For $\gamma > 0$ and Φ_n and M_n as in Theorem 2, the matrix $A_n = M_n + n^{-\gamma} \Phi_n$ satisfies $\frac{1}{n} \|A_n\|_2^2$ is almost surely bounded, and the same statement holds with A_n replaced by $B_n = M_n + n^{-\gamma} \Psi_n$.

Proof. Paraphrasing [25, Lemma 1.9], the result follows by combining (2) with the triangle inequality, and using the law of large numbers along with the fact the second moments of the entries in $\sqrt{n} \Phi_n$ are finite. $\square$

As noted in [25], one fact that makes Theorem 6 particularly useful is that there are a number of different ways to express $|\det(A)|$. For example, for an n by n matrix A

$$|\det(A)| = \prod_{i=1}^n |\lambda_i| = \prod_{i=1}^n \sigma(A) = \prod_{i=1}^n d_i(A), \quad (3)$$

where $\lambda_1, \dots, \lambda_n$ are the eigenvalues of A (with multiplicity), where $\sigma_1(A) \geq \sigma_2(A) \geq \dots \geq \sigma_n(A) \geq 0$ are the singular values of A , and where $d_i(A)$ is the distance from the i th row of A to the span of the first $i-1$ rows. Combining Equation (3) with a result such as Lemma 7 reduces proving universality of the ESD to a question about the distance from a perturbed vector to a span of perturbed vectors. In particular, one can prove Theorem 2 using Lemma 7, Theorem 6, and the following proposition:

Proposition 8. Let X_i be the rows of $A_n + zI$ and let Y_i be the rows of $B_n + zI$, where A_n and B_n are as in Theorem 2. For almost all complex numbers z ,

$$\frac{1}{n} \sum_{i=1}^n \log \text{dist}(X_i, \text{Span}\{X_1, \dots, X_{i-1}\}) - \log \text{dist}(Y_i, \text{Span}\{Y_1, \dots, Y_{i-1}\}) \quad (4)$$

converges in probability to zero.

Proving Proposition 8 is the goal of Section 3.1, Section 4 and Section 5.

3.1. Singular values for polynomially small random noise

As shown in [25], a bound on the singular values allows one to bound the highest-dimensional distances in (4).

For an n by n matrix M_n , let $\|M_n\|$ denote the spectral norm of M_n (which is also the largest singular value of M_n), namely

$$\|M_n\| = \sup_{|\mathbf{v}|=1} |M_n \mathbf{v}|.$$

For a matrix M , let the singular values be denoted

$$\sigma_1(M) \geq \sigma_2(M) \geq \dots \geq \sigma_n(M) \geq 0.$$

Theorem 9 (Least singular value bound, [23]). Let A, B, γ be positive constants, and let x be a complex-valued random variable with non-zero finite variance (in particular, the second moment is finite). Then there are positive constants C_1 and C_2 such that the following holds: if X_n is the random n by n matrix whose entries are iid copies of x , and M_n is a deterministic n by n matrix with spectral norm $\|M_n\| \leq n^{B-\gamma}$, then,

$$\mathbf{P}(\sigma_n(M_n + n^{-\gamma} X_n) \leq n^{-C_1-\gamma}) \leq C_2 n^{-A}.$$

The above is a restatement of [23, Theorem 2.1] using the fact that $\sigma_n(M_n + n^{-\gamma} X_n) \leq n^{-C_1 - \gamma}$ is equivalent to $\sigma_n(n^\gamma M_n + X_n) \leq n^{-C_1}$. Applying Theorem 9 to the matrices A_n and B_n from the statement of Theorem 2, we have with probability 1 that

$$\sigma_n(A_n), \sigma_n(B_n) \geq n^{-O(1)}, \quad (5)$$

for all but finitely many n . As pointed out in [25], a polynomial upper bound

$$\sigma_n(A_n), \sigma_n(B_n) \leq n^{O(1)} \quad (6)$$

holds with probability 1 for all but finitely many n . (The upper bound follows from (2), the bounded second moments of x and y , and the Borel–Cantelli lemma.)

Lemma 10. *Let X_i be the rows of $A_n + zI$ and let Y_i be the rows of $B_n + zI$, where A_n and B_n are as in Theorem 2. For almost all complex numbers z and with probability 1,*

$$|\log \text{dist}(X_i, \text{Span}\{X_1, \dots, X_{i-1}\})| \leq O(\log n)$$

and

$$|\log \text{dist}(Y_i, \text{Span}\{Y_1, \dots, Y_{i-1}\})| \leq O(\log n)$$

for all but finitely many n .

The above lemma follows from (5), (6) and [25, Lemma A.4]. When bounding a sum such as (4), Lemma 10 allows one to ignore up to $o(n/\log n)$ rows, since a sum of $o(n/\log n)$ numbers that are each at most $O(\log n)$ is at most $o(n)$, which converges to zero when scaled by $1/n$.

4. Proof of Proposition 8

We will now prove Proposition 8, thereby completing the proof of Theorem 2. In the proof, we will use tools described above along with Proposition 11 below which we will prove in Section 5 as Proposition 19.

Note that Proposition 8 can be restated in terms of determinants (see (3)), and thus Proposition 8 is equivalent to the same statement with the rows and corresponding columns of the matrices reordered in the same way (since reordering rows and columns has no effect on the determinant). Recall that $A_n + zI = M_n + n^{-\gamma} \Phi_n + zI$ and $B_n + zI = M_n + n^{-\gamma} \Psi_n + zI$, and note that reordering rows and columns of Φ_n and Ψ_n has no effect since the entries are iid. Thus, in proving Proposition 8, we may reorder the rows and corresponding columns as is convenient. In particular, we may reorder so that $Z_1, \dots, Z_m$ are the first m rows of $M_n + zI$ and are ε -stable with the same ε from the assumption in Theorem 2. We may further require that the reordering satisfies $\|Z_1\|_2 \geq \|Z_2\|_2 \geq \dots \geq \|Z_m\|_2$.

Proposition 11. *Let $M_n + zI$ be an n by n matrix, let Φ_n and Ψ_n be n by n complex matrices with each row a random complex vector with mean 0 and variance 1, and let $Z_1, \dots, Z_m$ be the first m rows of $M_n + zI$, where $m = \lfloor n - \frac{2n}{\log^{1.1} n} \rfloor$. Assume that $\|Z_1\|_2 \geq \|Z_2\|_2 \geq \dots \geq \|Z_m\|_2$. If $\{Z_1, \dots, Z_m\}$ is ε -stable and there exists a constant $\gamma > 1.5$ so that*

$$\delta_{n,\varepsilon} := \frac{n^{-\gamma/2+3/4} \log^{1/4}(n) \sqrt{\max_{1 \leq i \leq m} \{1, \|Z_i\|_2\}}}{\varepsilon} \rightarrow 0 \quad \text{as } n \rightarrow \infty,$$

then with probability at least $1 - 1/\log n$ we have,

$$\left| \frac{1}{n} \sum_{i=1}^m \log d_i(M_n + zI + n^{-\gamma} \Phi) - \log d_i(M_n + zI + n^{-\gamma} \Psi) \right| \leq 20\delta_{n,\varepsilon}$$

for all sufficiently large n , where $d_i(A)$ is the distance from the i th row of a matrix A to the span of rows $1, 2, \dots, i-1$.

The proof approach of Proposition 11 is to add up the errors from perturbing each row with polynomially small random noise. If the set of rows is ε -stable with ε enough larger than the polynomially small random noise, then the sum of all the errors can be shown to be small. See Section 5 and Proposition 19 (which is a restatement of Proposition 11) for details.

To prove Proposition 8, we will first exclude rows from $\{Z_1, \dots, Z_m\}$ that are large. From the assumption (2) that $\sup_n \frac{1}{n} \|M_n\|_2^2 < \infty$, we know that all but at most $\frac{n}{\log^{1.1} n}$ rows of $M_n + zI$ satisfy $\|Z_i\|_2 > O(\log^{0.55} n)$. We will exclude the first $\frac{n}{\log^{1.1} n}$ rows from the stable set, focusing instead on the set $\{Z_i : \frac{n}{\log^{1.1} n} < i \leq m\}$ which is ε -stable and satisfies

$$\|Z_i\|_2 \leq O(\log^{0.55} n), \quad \text{for } \frac{n}{\log^{1.1} n} \leq i \leq m.$$

Next, we will reorder the rows and corresponding columns so that the set $\{Z_i : \frac{n}{\log^{1.1} n} < i \leq m\}$ is the first $m' = \lfloor m - \frac{n}{\log^{1.1} n} \rfloor = \lfloor n - \frac{2n}{\log^{1.1} n} \rfloor$ rows of the reordered matrix.

Recall that to prove Proposition 8 we must show for almost every $z \in \mathbb{C}$ that

$$\frac{1}{n} \sum_{i=1}^n \log d_i(M_n + zI + n^{-\gamma} \Phi) - \log d_i(M_n + zI + n^{-\gamma} \Psi) \quad (7)$$

converges to zero in probability, where $d_i(A)$ is the distance from the i th row of matrix A to the span of the first $i - 1$ rows.

Lemma 10 shows that the portion of the sum in (7) for $m' < i \leq n$ converges to zero in probability, and Proposition 11 proves that portion of the sum in (7) for $1 \leq i \leq m' = \lfloor n - 2n/\log^{1.1} n \rfloor$ also converges to zero in probability (note that $\delta_{n,\varepsilon} < \frac{n^{3/4-\gamma/2} \log n}{\varepsilon} \rightarrow 0$ as $n \rightarrow \infty$ by assumption).

5. The stability approach for small random noise

Using Theorem 6, we see that one way to prove universality is to control quantities of the form

$$\text{dist}(Z_i + f(n)\varphi_n, \text{Span}\{Z_1 + f(n)\varphi_1, \dots, Z_{i-1} + f(n)\varphi_{i-1}\}),$$

where Z_j is a row of M_n and φ_j is a random n -dimensional vector with iid mean zero, variance $1/n$ entries.

As a warm-up, we show in the proposition below that most matrices satisfy the ε -stable condition given in Theorem 2 when one takes $\gamma > 5/3$.

Proposition 12. *Let R_n be a random matrix where the entries are iid copies of $x/\sqrt{n}$, where x is a mean zero, variance 1 complex random variable. Then, with probability one, R_n contains a set of $n - n^{5/6}$ rows that is $(n^{-1/12}/2)$ -stable, for all but finitely many n . Furthermore, the same result holds for $R_n + zI_n$ where z is a fixed complex number and I_n is the n by n identity matrix.*

Proof. Since we may take $z = 0$, it suffices to prove the result for $R_n + zI_n$. We will show that the first m rows of $R_n + zI_n$ form a stable set. Let $d_{i,m}(R_n + zI_n)$ be the distance from the i th row to span of the first m rows not including row i . Assuming that $m \leq n - n^{5/6}$, we can apply [27, Proposition 4.2] (see also [25, Proposition 5.1]) to get

$$\mathbb{P}(d_{i,m}(R_n + zI_n) \leq n^{-1/12}/2) \leq 6 \exp(-n^{1/2}),$$

for each $1 \leq i \leq m$, for all sufficiently large n . By the union bound, the probability that any of the $m = n - n^{5/6}$ rows in the stable set satisfy $d_{i,m}(R_n + zI_n) \leq n^{-1/12}/2$ is at most $6m \exp(-n^{1/2}) \leq 6n \exp(-n^{1/2})$. This probability is summable in n , and so the Borel–Cantelli lemma completes the proof. $\square$

5.1. Small perturbations of one row

Lemma 13. Let $Z_1, \dots, Z_i$ and φ_i be n -dimensional complex vectors, and let $f_i(n)$ be a non-negative real function of n . Then

$$|\text{dist}(Z_i, \text{Span}\{Z_1, \dots, Z_{i-1}\}) - \text{dist}(Z_i + f_i(n)\varphi_i, \text{Span}\{Z_1, \dots, Z_{i-1}\})| \leq f_i(n)\|\varphi_i\|_2.$$

Proof. The result follows from the triangle inequality. $\square$

Lemma 14. Let $Z_1, \dots, Z_i$ and φ_1 be n -dimensional complex vectors, and let $f_1(n)$ be a non-negative real function of n . Assume that

$$d_1 := \text{dist}(Z_1, \text{Span}\{Z_2, \dots, Z_{i-1}\}) > f_1(n)\|\varphi_1\|_2.$$

Then

$$\begin{aligned} & |\text{dist}(Z_i, \text{Span}\{Z_1, \dots, Z_{i-1}\}) - \text{dist}(Z_i, \text{Span}\{Z_1 + f_1(n)\varphi_1, Z_2, \dots, Z_{i-1}\})| \\ & \leq \|Z_i\|_2 f_1(n)\|\varphi_1\|_2 \left(\frac{4d_1 + 2f_1(n)\|\varphi_1\|_2}{(d_1 - f_1(n)\|\varphi_1\|_2)^2} \right). \end{aligned}$$

Furthermore, if one assumes that $d_1 \geq \varepsilon > 2f_1(n)\|\varphi_1\|_2$, then one can simplify the upper bound noting that

$$\left(\frac{4d_1 + 2f_1(n)\|\varphi_1\|_2}{(d_1 - f_1(n)\|\varphi_1\|_2)^2} \right) \leq \frac{20}{\varepsilon}.$$

Proof. Let $u_2, \dots, u_{i-1}$ be an orthonormal basis for $Z_2, \dots, Z_{i-1}$, let

$$u_1 = Z_1 - \sum_{j=2}^{i-1} u_j \langle Z_1, u_j \rangle,$$

where $\langle \cdot, \cdot \rangle$ is the standard complex inner product (so $\|u_1\|_2 = d_1$). Also, let

$$\tilde{u}_1 = Z_1 + f_1(n)\varphi_1 - \sum_{j=2}^{i-1} u_j \langle Z_1 + f_1(n)\varphi_1, u_j \rangle.$$

Note that

$$\begin{aligned} & |\text{dist}(Z_i, \text{Span}\{Z_1, \dots, Z_{i-1}\}) - \text{dist}(Z_i, \text{Span}\{Z_1 + f_1(n)\varphi_1, Z_2, \dots, Z_{i-1}\})| \\ & \leq \left\| \frac{u_1}{\|u_1\|_2^2} \langle Z_i, u_1 \rangle - \frac{\tilde{u}_1}{\|\tilde{u}_1\|_2^2} \langle Z_i, \tilde{u}_1 \rangle \right\|_2, \end{aligned}$$

and thus the current lemma can be proven by studying u_1 , $\tilde{u}_1$, and Z_i . Let $e = \tilde{u}_1 - u_1 = f_1(n)(\varphi_1 - \sum_{j=2}^{i-1} u_j \langle \varphi_1, u_j \rangle)$, and note that $\|e\|_2 \leq f_1(n)\|\varphi_1\|_2$.

We may write

$$\begin{aligned} & \frac{\tilde{u}_1}{\|\tilde{u}_1\|_2^2} \langle Z_i, \tilde{u}_1 \rangle - \frac{u_1}{\|u_1\|_2^2} \langle Z_i, u_1 \rangle \\ & = u_1 \frac{\langle Z_i, u_1 \rangle}{\|u_1 + e\|_2^2} + e \frac{\langle Z_i, u_1 + e \rangle}{\|u_1 + e\|_2^2} + u_1 \frac{\langle Z_i, e \rangle}{\|u_1 + e\|_2^2} - \frac{u_1}{\|u_1\|_2^2} \langle Z_i, u_1 \rangle \\ & = \frac{u_1}{\|u_1\|_2^2} \langle Z_i, u_1 \rangle \left(\frac{\|u_1\|_2^2}{\|u_1 + e\|_2^2} - 1 \right) + \frac{e \langle Z_i, u_1 + e \rangle + u_1 \langle Z_i, e \rangle}{\|u_1 + e\|_2^2}. \end{aligned}$$

Using Cauchy–Schwartz, the triangle inequality, and the fact that $\|u_1 + e\|_2 = \|u_1\|_2 + c_0\|e\|_2$ for some constant $-1 \leq c_0 \leq 1$, we can compute that the above vector has length at most

$$\begin{aligned} & \|Z_i\|_2 \left(\left| \frac{\|u_1\|_2^2 - \|u_1 + e\|_2^2}{\|u_1 + e\|_2^2} \right| + \frac{\|e\|_2}{\|u_1 + e\|_2} + \frac{\|u_1\|_2\|e\|_2}{\|u_1 + e\|_2^2} \right) \\ &= \frac{\|Z_i\|_2}{(\|u_1\|_2 + c_0\|e\|_2)^2} (|-2c_0\|u_1\|_2\|e\|_2 - c_0^2\|e\|_2^2| + \|e\|_2(\|u_1\|_2 + c_0\|e\|_2) + \|u_1\|_2\|e\|_2) \\ &\leq \frac{\|Z_i\|_2}{(\|u_1\|_2 + c_0\|e\|_2)^2} ((2|c_0| + 2)\|u_1\|_2\|e\|_2 + \|e\|_2^2(c_0^2 + c_0)). \end{aligned}$$

Using the assumption that $\|u_1\|_2 = d_1 > f_1(n)\|\varphi_1\|_2$ and the facts that $-1 \leq c_0 \leq 1$ and $\|e\|_2 \leq f_1(n)\|\varphi_1\|_2$, the above distance is at most

$$\|Z_i\|_2 \frac{(4\|u_1\|_2 f_1(n)\|\varphi_1\|_2 + 2f_1(n)^2\|\varphi_1\|_2^2)}{(\|u_1\|_2 - f_1(n)\|\varphi_1\|_2)^2},$$

which completes the proof. $\square$

5.2. Stability and its changes in the presence of small random noise

Lemma 15. Let $Z_1, \dots, Z_k$ and φ_1 be n -dimensional complex vectors, and let $f_1(n)$ be a non-negative real function of n . Assume that $\{Z_1, \dots, Z_k\}$ is ε -stable and that $\varepsilon > 2f_1(n)\|\varphi_1\|_2$.

Then $\{Z_1 + f_1(n)\varphi_1, Z_2, \dots, Z_k\}$ is

$$\left(\varepsilon - f_1(n)\|\varphi_1\|_2 \max_{2 \leq i \leq k} \left\{ 1, \|Z_i\|_2 \left(\frac{20}{\varepsilon} \right) \right\} \right)\text{-stable}.$$

Proof. By Lemma 13, we know that

$$|\text{dist}(Z_1, \text{Span}\{Z_2, \dots, Z_k\}) - \text{dist}(Z_1 + f_1(n)\varphi_1, \text{Span}\{Z_2, \dots, Z_k\})| \leq f_1(n)\|\varphi_1\|_2.$$

For $2 \leq i \leq k$, let $Z_2, \dots, \widehat{Z}_i, \dots, Z_k$ denote the set $\{Z_j : 2 \leq j \leq k, j \neq i\}$. By Lemma 14 we know that

$$\begin{aligned} & |\text{dist}(Z_i, \text{Span}\{Z_1, Z_2, \dots, \widehat{Z}_i, \dots, Z_k\}) - \text{dist}(Z_i, \text{Span}\{Z_1 + f_1(n)\varphi_1, Z_2, \dots, \widehat{Z}_i, \dots, Z_k\})| \\ &\leq \|Z_i\|_2 f_1(n)\|\varphi_1\|_2 \left(\frac{4d_1 + 2f_1(n)\|\varphi_1\|_2}{(d_1 - f_1(n)\|\varphi_1\|_2)^2} \right), \end{aligned} \quad (8)$$

where $d_1 = \text{dist}(Z_1, \text{Span}\{Z_2, \dots, \widehat{Z}_i, \dots, Z_k\})$. By the ε -stable assumption, $d_1 \geq \varepsilon > 2f_1(n)\|\varphi_1\|_2$, so the bound in (8) is at most $\|Z_i\|_2 f_1(n)\|\varphi_1\|_2 (20/\varepsilon)$. $\square$

Lemma 16 (Continued stability). Let $Z_1, \dots, Z_k$ and $\varphi_1, \dots, \varphi_k$ be n -dimensional complex vectors, and let $f_1(n), \dots, f_k(n)$ be non-negative real functions of n . Assume that $\{Z_1, \dots, Z_k\}$ is ε -stable and that

$$20 \geq \varepsilon > \sqrt{40k \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\} \left(\max_{1 \leq i \leq k} \{1, \|Z_i\|_2\} + \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\} \right)}.$$

Then, for each $1 \leq j \leq k$, we have that

$$\{\widetilde{Z}_1, \widetilde{Z}_2, \dots, \widetilde{Z}_j, Z_{j+1}, Z_{j+2}, \dots, Z_k\}$$

is $(\varepsilon/2)$ -stable, where $\widetilde{Z}_i = Z_i + f_1(n)\varphi_i$.

Proof. We will prove the following stronger statement by induction on j :

$$\{\tilde{Z}_1, \tilde{Z}_2, \dots, \tilde{Z}_j, Z_{j+1}, Z_{j+2}, \dots, Z_k\} \text{ is } \left(\varepsilon - \frac{j\varepsilon}{2k}\right)\text{-stable,}$$

for $j = 0, 1, \dots, k$.

For the base case of $j = 0$, the set of vectors $\{Z_1, \dots, Z_k\}$ is ε -stable by assumption.

For the induction step, assume that

$$\{\tilde{Z}_1, \tilde{Z}_2, \dots, \tilde{Z}_j, Z_{j+1}, Z_{j+2}, \dots, Z_k\} \text{ is } \left(\varepsilon - \frac{j\varepsilon}{2k}\right)\text{-stable.}$$

By Lemma 15, we have that

$$\{\tilde{Z}_1, \tilde{Z}_2, \dots, \tilde{Z}_{j+1}, Z_{j+2}, Z_{j+3}, \dots, Z_k\}$$

is

$$\left(\varepsilon - \frac{j\varepsilon}{2k} - f_{j+1}(n)\|\varphi_{j+1}\|_2 \left(\frac{20}{\varepsilon}\right) \max\{\varepsilon/20, \|\tilde{Z}_1\|_2, \dots, \|\tilde{Z}_j\|_2, \|Z_{j+1}\|_2, \dots, \|Z_{j+1}\|_2\}\right)\text{-stable.}$$

By the assumed lower bound on ε , we have that

$$\begin{aligned} & \varepsilon - \frac{j\varepsilon}{2k} - f_{j+1}(n)\|\varphi_{j+1}\|_2 \left(\frac{20}{\varepsilon}\right) \max\{\varepsilon/20, \|\tilde{Z}_1\|_2, \dots, \|\tilde{Z}_j\|_2, \|Z_{j+1}\|_2, \dots, \|Z_{j+1}\|_2\} \\ & \geq \varepsilon - \frac{j\varepsilon}{2k} - \left(\frac{20}{\varepsilon}\right) \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\} \left(\max_{1 \leq i \leq k} \{\varepsilon/20, \|Z_i\|_2\} + \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\}\right) \\ & \geq \varepsilon - \frac{j\varepsilon}{2k} - \frac{\varepsilon}{2k} = \varepsilon - \frac{(j+1)\varepsilon}{2k}. \end{aligned}$$

□

Proposition 17. Let $v, Z_1, \dots, Z_k$ and $\varphi_1, \dots, \varphi_k$ be n -dimensional complex vectors, let $f_1(n), \dots, f_k(n)$ be non-negative real functions of n , and let $\tilde{Z}_i = Z_i + f_i(n)\varphi_i$ for each $1 \leq i \leq k$. If $\{Z_1, \dots, Z_k\}$ is ε -stable and

$$20 \geq \varepsilon/2 > \sqrt{40k \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\} \left(\max_{1 \leq i \leq k} \{1, \|Z_i\|_2\} + \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\}\right)} \quad (9)$$

then

$$\begin{aligned} & |\text{dist}(v, \text{Span}\{Z_1, \dots, Z_k\}) - \text{dist}(v, \text{Span}\{\tilde{Z}_1, \tilde{Z}_2, \dots, \tilde{Z}_k\})| \\ & \leq \left(\frac{40}{\varepsilon}\right) k \|v\|_2 \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\} \\ & \leq \|v\|_2 \sqrt{\frac{10k \max_{1 \leq i \leq k} \{f_i(n)\|\varphi_i\|_2\}}{\max_{1 \leq i \leq k} \{1, \|Z_i\|_2\}}}. \end{aligned}$$

Proof. The proposition follows from adding the perturbations one at a time (similar versions of the Lindeberg trick have been of recent use in random matrix theory, see for example [7,24,25]). We will use Lemmas 16 and 14 to bound the successive differences, showing that the sum of the successive differences is at most the desired bound.

By Lemma 16, we know that for each $0 \leq j \leq k$ that

$$\{\tilde{Z}_1, \tilde{Z}_2, \dots, \tilde{Z}_j, Z_{j+1}, \dots, Z_k\}$$

is $(\varepsilon/2)$ -stable. Our plan is now to apply Lemma 14 repeatedly, noting that $\varepsilon/2 > 2f_i(n)\|\varphi_i\|_2$ follows assumption (9).

Let

$$h(0) = \text{dist}(v, \text{Span}\{Z_1, \dots, Z_k\}),$$

$$h(i) = \text{dist}(v, \text{Span}\{\tilde{Z}_1, \dots, \tilde{Z}_i, Z_{i+1}, \dots, Z_k\}),$$

$$h(k) = \text{dist}(v, \text{Span}\{\tilde{Z}_1, \dots, \tilde{Z}_k\}).$$

To prove the proposition we must bound $|h(0) - h(k)|$.

We note that

$$\begin{aligned} |h(0) - h(k)| &\leq \sum_{i=1}^k |h(i-1) - h(i)| \\ &\leq \sum_{i=1}^k \frac{40}{\varepsilon} f_i(n) \|v\|_2 \|\varphi_i\|_2 \quad (\text{by Lemma 14}) \\ &\leq k \left(\frac{40}{\varepsilon} \right) \|v\|_2 \max_{1 \leq i \leq k} \{f_i(n) \|\varphi_i\|_2\} \\ &\leq \|v\|_2 \sqrt{\frac{10k \max_{1 \leq i \leq k} \{f_i(n) \|\varphi_i\|_2\}}{\max_{1 \leq i \leq k} \{1, \|Z_i\|_2\}}} \quad (\text{using (9)}) \end{aligned}$$

completing the proof. $\square$

Corollary 18. Let $v, Z_1, \dots, Z_k$ be n -dimensional complex vectors, let $\varphi_1, \dots, \varphi_k$ be random complex vectors with mean zero and variance 1, and let $\tilde{Z}_i = Z_i + n^{-\gamma} \varphi_i$ for each $1 \leq i \leq k$. If $\{Z_1, \dots, Z_k\}$ is ε -stable where

$$20 \geq \varepsilon/2 > \sqrt{40kn^{-\gamma} \sqrt{k \log n} \left(\max_{1 \leq i \leq k} \{1, \|Z_i\|_2\} + n^{-\gamma} \sqrt{k \log n} \right)}$$

then with probability at least $1 - 1/\log n$ we have

$$\begin{aligned} &|\text{dist}(v, \text{Span}\{Z_1, \dots, Z_k\}) - \text{dist}(v, \text{Span}\{\tilde{Z}_1, \tilde{Z}_2, \dots, \tilde{Z}_k\})| \\ &\leq \|v\|_2 \sqrt{\frac{10kn^{-\gamma} \sqrt{k \log n}}{\max_{1 \leq i \leq k} \{1, \|Z_i\|_2\}}}. \end{aligned}$$

Proof. Combine Proposition 17 with the fact that $\max_{1 \leq i \leq k} \|\varphi_i\|_2 \leq \sqrt{k \log n}$ with probability at least $1 - 1/\log n$ (from Chebyshev's inequality and the union bound). $\square$

In applying the small noise results such as Corollary 18 or Proposition 19 (below) to determine the limiting ESD, reordering the rows and corresponding columns has no effect on the eigenvalues. This allows assumptions such as the rows being ordered by decreasing norm to be easily met. Recall that Proposition 11 was a key part in proving Theorem 2. Before proving Proposition 11 below, will restate the result as Proposition 19. For notational simplicity, we will absorb the zI term in Proposition 11 into M_n in the proposition below, which also lets us state the proposition in a self-contained way without referencing z .

Proposition 19 (Same statement as Proposition 11). Let M_n be an n by n matrix, let Φ_n and Ψ_n be n by n complex matrices with each row a random complex vector with mean 0 and variance 1, and let $Z_1, \dots, Z_m$ be the first m rows of M_n , where $m = \lfloor n - \frac{2n}{\log^{1.1} n} \rfloor$. Assume that $\|Z_1\|_2 \geq \|Z_2\|_2 \geq \dots \geq \|Z_m\|_2$. If $\{Z_1, \dots, Z_m\}$ is ε -stable and there exists a constant $\gamma > 1.5$ so that

$$\delta_{n,\varepsilon} := \frac{n^{-\gamma/2+3/4} \log^{1/4}(n) \sqrt{\max_{1 \leq i \leq m} \{1, \|Z_i\|_2\}}}{\varepsilon} \rightarrow 0 \quad \text{as } n \rightarrow \infty,$$

then with probability at least $1 - 1/\log n$ we have,

$$\left| \frac{1}{n} \sum_{i=1}^m \log d_i(M_n + n^{-\gamma} \Phi) - \log d_i(M_n + n^{-\gamma} \Psi) \right| \leq 20\delta_{n,\varepsilon}$$

for all sufficiently large n , where $d_i(A)$ is the distance from the i th row of a matrix A to the span of rows $1, 2, \dots, i-1$.

Proof. The main tool here is repeated application of Corollary 18. Throughout, we will use the fact (as in the proof of Corollary 18) that $\max_{1 \leq i \leq m} \|\varphi_i\|_2 \leq \sqrt{n \log n}$ with probability at least $1 - 1/\log n$.

To start, let $d_i(M_n + n^{-\gamma} \Phi) = d_i(M_n) + \alpha_i$ and $d_i(M_n + n^{-\gamma} \Psi) = d_i(M_n) + \mathfrak{b}_i$, where α_i and $\mathfrak{b}_i$ are error terms. We can use Corollary 18 and Lemma 13 to bound these error terms:

$$\begin{aligned} |\alpha_i|, |\mathfrak{b}_i| &\leq \frac{\|Z_i\|_2}{\sqrt{\max_{1 \leq j \leq i} \{1, \|Z_j\|_2\}}} \sqrt{10} n^{-\gamma/2+3/4} \log^{1/4} n + n^{-\gamma+1/2} \log^{1/2} n \\ &\leq \|Z_i\|_2^{1/2} 4n^{-\gamma/2+3/4} \log^{1/4} n, \end{aligned}$$

where the second inequality holds for sufficiently large n .

We note that

$$|\log d_i(M_n + n^{-\gamma} \Phi) - \log d_i(M_n + n^{-\gamma} \Psi)| = \log \left(1 + \frac{\alpha_i - \mathfrak{b}_i}{d_i(M) + \mathfrak{b}_i} \right),$$

and, furthermore, that the fraction $\frac{\alpha_i - \mathfrak{b}_i}{d_i(M) + \mathfrak{b}_i}$ tends to zero. In particular

$$\begin{aligned} \left| \frac{\alpha_i - \mathfrak{b}_i}{d_i(M) + \mathfrak{b}_i} \right| &\leq \frac{\|Z_i\|_2^{1/2} 8n^{-\gamma/2+3/4} \log^{1/4} n}{\varepsilon - \|Z_i\|_2^{1/2} 4n^{-\gamma/2+3/4} \log^{1/4} n} \\ &\leq \frac{\|Z_i\|_2^{1/2} 8\delta_{n,\varepsilon}}{\sqrt{\max_{1 \leq i \leq m} \{1, \|Z_i\|_2\}} - \|Z_i\|_2^{1/2} 4\delta_{n,\varepsilon}} \\ &\leq \frac{8\delta_{n,\varepsilon}}{1 - 4\delta_{n,\varepsilon}} \rightarrow 0 \end{aligned}$$

as $n \rightarrow \infty$, by the assumption on $\delta_{n,\varepsilon}$. Thus, we can use the approximation $\log(1+x) \leq 2|x|$, which holds for $-0.797 \leq x$, to write

$$|\log d_i(M_n + n^{-\gamma} \Phi) - \log d_i(M_n + n^{-\gamma} \Psi)| = \log \left(1 + \frac{\alpha_i - \mathfrak{b}_i}{d_i(M) + \mathfrak{b}_i} \right) \leq 2 \left| \frac{8\delta_{n,\varepsilon}}{1 - 4\delta_{n,\varepsilon}} \right| < 20\delta_{n,\varepsilon},$$

for sufficiently large n .

Using the triangle inequality and the above approximation, we have

$$\left| \frac{1}{n} \sum_{i=1}^m \log d_i(M_n + n^{-\gamma} \Phi) - \log d_i(M_n + n^{-\gamma} \Psi) \right| \leq \frac{m}{n} 20\delta_{n,\varepsilon} \leq 20\delta_{n,\varepsilon}.$$

□

6. Proofs of applications

We first state two lemmas describing the ε -stability of subsets of the rows of $T_{b,n} + zI$ and then give the proofs of Theorems 3 and 5 in Section 6.1 and Section 6.2 below.

Lemma 20. Let e_i denote the standard basis vector in $\mathbb{C}^n$ with a 1 in position i and zeros elsewhere. Let $m \leq n - 1$, let J be a subset of $\{1, 2, \dots, m\}$, and consider the set $S = \{ze_i + e_{i+1} : i \in J\}$, where $z \in \mathbb{C}$ and $|z| \neq 1$. Then

$$S \text{ is } \min\{1, |1 - |z|^2|^{1/2}\}\text{-stable.}$$

Sketch. One proceeds by finding an orthogonal basis for S and then minimizing over the distance from one vector in S to the rest. Details appear in Section 6.3. $\square$

Lemma 21. Let $S = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ be the set of the rows of $T_{b,n} + zI$, where $z \in \mathbb{C}$. Then

$$S \text{ is } \begin{cases} ||z|^2 - 1|^{1/2}\text{-stable} & \text{if } |z| > 1, \\ |z|^{b+1}|1 - |z|^2|^{1/2}\text{-stable} & \text{if } |z| < 1. \end{cases}$$

Sketch. The proof uses a similar approach to Lemma 20, with the change that rows of form ze_i make orthogonalizing much simpler, resulting in parts of the orthogonal basis being equal to a rescaling of the standard basis. Details appear in Section 6.4. $\square$

6.1. Proof of Theorem 3

By Lemma 21, for each constant $|z| \neq 1$, we know that the set of all rows of $T_{b,n} + zI$ is ε -stable for a constant ε when $|z| > 1$, and we know that the set of all rows is ε -stable for some $\varepsilon > \Omega(n^{o(1)})$ where $o(1) \rightarrow 0$ as $n \rightarrow \infty$ when $|z| < 1$. Thus, by Proposition 11,

$$\left| \frac{1}{n} \sum_{i=1}^n \log d_i(T_{b,n} + n^{-\gamma} \Phi) - \log d_i(T_{b,n}) \right| \leq \delta_{n,\varepsilon},$$

where $\delta_{n,\varepsilon} \leq O(n^{1.5-\gamma-o(1)}) \rightarrow 0$ as $n \rightarrow \infty$. The above shows that $A_n = T_{b,n}$ and $B_n = T_{b,n} + n^{-\gamma} \Phi$ satisfy condition (ii) of Theorem 6, and it can also be shown (similarly to Lemma 7) that the same A_n and B_n satisfy condition (i) of Theorem 6. Thus, the ESD of $T_{b,n} + n^{-\gamma} \Phi$ converges in probability to the ESD of $T_{b,n}$, which is the Dirac delta δ_0 with mass 1 at the origin.

6.2. Proof of Theorem 5

First we show that the ESD of $T_{b,n} + n^{-\gamma} \Phi_n$ is the same as the ESD of $T_n + n^{-\gamma} \Phi_n$. Note that there are less than $n/(b+1) = o(n/\log n)$ rows of $T_{b,n}$ that contain all zeros. Thus, there are at most $o(n/\log n)$ rows of $T_{b,n} + n^{-\gamma} \Phi_n$ that differ from the corresponding rows of $T_n + n^{-\gamma} \Phi_n$. Combining Theorem 6, Proposition 8, and Lemma 10 (reordering rows and columns of the matrices so that the rows that differ are the last rows), we see that the difference of the ESDs of $T_{b,n} + n^{-\gamma} \Phi_n$ and $T_n + n^{-\gamma} \Phi_n$ converges to zero in probability.

Second, we will show that the ESD of $T_n + n^{-\gamma} \Phi_n$ is the same as the ESD of $T_n + n^{-\gamma} G_n$, where $\sqrt{n}G_n$ is an iid Ginibre matrix, so each entry of $\sqrt{n}G_n$ is complex Gaussian with mean zero and variance one. Here we apply Theorem 2, noting that the set of the first $n-1$ rows is ε -stable for a constant ε (where ε depends on z), thus proving that the difference of the ESDs of $T_n + n^{-\gamma} \Phi_n$ and $T_n + n^{-\gamma} G_n$ converges to zero in probability.

Finally, it was proved in [16] (see also [19]) that the ESD of $T_{b,n} + n^{-\gamma} G_n$ converges in probability to uniform on the unit circle, completing the proof.

6.3. Proof of Lemma 20

Note that if S is a subset of T and T is ε -stable, then S is also ε -stable. Thus, it is sufficient to show that $S = \{ze_i + e_{i+1} : 1 \leq i \leq m\}$ is $\varepsilon_{z,m}$ -stable, where $\varepsilon_{z,m} = \min\{1, |1 - |z|^2|^{1/2}\}$.

Fix $\ell \in \{1, 2, \dots, m\}$. We need to show that

$$\text{dist}(ze_\ell + e_{\ell+1}, \text{Span}\{ze_i + e_{i+1} : 1 \leq i \leq m \text{ and } i \neq \ell\}) \geq \varepsilon_{z,m}. \quad (10)$$

We will find orthogonal bases for $\{ze_i + e_{i+1} : 1 \leq i \leq \ell - 1\}$ and for $\{ze_i + e_{i+1} : \ell + 1 \leq i \leq m\}$, noting that together they form an orthogonal basis for $\{ze_i + e_{i+1} : 1 \leq i \leq m \text{ and } i \neq \ell\}$. Then we will use the orthogonal basis to compute the distance in (10) explicitly.

Lemma 22. *The vectors $\{ze_i + e_{i+1} : 1 \leq i \leq \ell - 1\}$ where e_i is the i th standard basis vector, have an orthogonal basis $\{w_1, \dots, w_{\ell-1}\}$ where*

$$\begin{aligned} w_k &= e_{k+1} + \frac{z(|z|^{2(k-1)}e_k + (-z)|z|^{2(k-2)}e_{k-1} + (-z)^2|z|^{2(k-3)}e_{k-2} + \dots + (-z)^{k-1}e_1)}{1 + |z|^2 + |z|^4 + \dots + |z|^{2k-2}} \\ &= e_{k+1} + \frac{z}{\sum_{i=0}^{k-1} |z|^{2i}} \left(\sum_{j=0}^{k-1} (-z)^{k-1-j} |z|^{2j} e_{j+1} \right). \end{aligned}$$

Proof. We proceed by induction on ℓ . For the base case $\ell = 2$, we have that $w_1 = e_2 + ze_1$, as it should.

For the induction step, assume the result for $\ell - 1$ where $\ell \geq 3$, which gives an orthogonal basis $\{w_1, \dots, w_{\ell-2}\}$ with the form above for the set $\{ze_i + e_{i+1} : 1 \leq i \leq \ell - 2\}$. We will now orthogonalize $ze_{\ell-1} + e_\ell$ with respect to $\{w_1, \dots, w_{\ell-2}\}$, showing that the resulting vector equals $w_{\ell-1}$ with the form above.

To orthogonalize $v := ze_{\ell-1} + e_\ell$ we compute $v - \frac{w_{\ell-2}}{\|w_{\ell-2}\|_2} z$ (since $\langle v, w_i \rangle = 0$ for $1 \leq i \leq \ell - 3$ and $\langle v, w_{\ell-2} \rangle = z$). Note that

$$\begin{aligned} \|w_{\ell-2}\|_2^2 &= 1 + \frac{|z|^2}{(\sum_{i=0}^{\ell-3} |z|^{2i})^2} \sum_{j=0}^{\ell-3} |z|^{2(\ell-2)-2j-2} |z|^{4j} \\ &= 1 + \frac{|z|^{2(\ell-2)} \sum_{j=0}^{\ell-3} |z|^{2j}}{(\sum_{i=0}^{\ell-3} |z|^{2i})^2} = 1 + \frac{|z|^{2(\ell-2)}}{\sum_{i=0}^{\ell-3} |z|^{2i}} \\ &= \frac{\sum_{j=0}^{\ell-2} |z|^{2j}}{\sum_{i=0}^{\ell-3} |z|^{2i}}. \end{aligned} \quad (11)$$

Thus the orthogonalization of v with respect to $\{w_1, \dots, w_{\ell-2}\}$ is

$$\begin{aligned} w_{\ell-1} &:= e_\ell + ze_{\ell-1} - z \frac{\sum_{i=0}^{\ell-3} |z|^{2i}}{\sum_{j=0}^{\ell-2} |z|^{2j}} \left(e_{\ell-1} + \frac{z}{\sum_{i=0}^{\ell-3} |z|^{2i}} \left(\sum_{j=0}^{\ell-3} (-z)^{\ell-2-1-j} |z|^{2j} e_{j+1} \right) \right) \\ &= e_\ell + ze_{\ell-1} \left(1 - \frac{\sum_{i=0}^{\ell-3} |z|^{2i}}{\sum_{j=0}^{\ell-2} |z|^{2j}} \right) + \frac{z}{\sum_{i=0}^{\ell-2} |z|^{2i}} \left(\sum_{j=0}^{\ell-3} (-z)^{\ell-2-j} |z|^{2j} e_{j+1} \right) \\ &= e_\ell + \left(\frac{z}{\sum_{j=0}^{\ell-2} |z|^{2j}} \right) |z|^{2(\ell-2)} e_{\ell-1} + \frac{z}{\sum_{i=0}^{\ell-2} |z|^{2i}} \left(\sum_{j=0}^{\ell-3} (-z)^{\ell-2-j} |z|^{2j} e_{j+1} \right) \\ &= e_\ell + \frac{z}{\sum_{i=0}^{\ell-2} |z|^{2i}} \left(\sum_{j=0}^{\ell-2} (-z)^{\ell-2-j} |z|^{2j} e_{j+1} \right). \end{aligned}$$

This is the desired form for $w_{\ell-1}$, completing the proof by induction. $\square$

Lemma 23. The vectors $\{ze_i + e_{i+1} : \ell + 1 \leq i \leq m\}$ where e_i is the i th standard basis vector, have an orthogonal basis $\{w_{\ell+1}, \dots, w_m\}$ where

$$\begin{aligned} w_k &= ze_k + \frac{e_{k+1} - \bar{z}e_{k+2} + \bar{z}^2e_{k+3} + \dots + (-\bar{z})^{m-k}e_{m+1}}{1 + |z|^2 + |z|^4 + \dots + z^{2m-2k}} \\ &= ze_k + \frac{1}{\sum_{i=0}^{m-k} |z|^{2i}} \left(\sum_{j=k+1}^{m+1} (-\bar{z})^{j-k-1} e_j \right). \end{aligned}$$

Proof. We proceed by induction on ℓ . For the base case of $\ell = m - 1$, there is only one vector, thus $w_{\ell+1} = w_m = ze_m + e_{m+1}$, as it should.

For the induction step, we will assume the result for $\ell + 2$ and show that it must also hold for $\ell + 1$. We will orthogonalize $ze_{\ell+1} + e_{\ell+2}$ with respect to $\{w_{\ell+2}, \dots, w_m\}$, assuming $w_{\ell+2}, \dots, w_m$ have the form above. Thus, we have

$$w_{\ell+1} := ze_{\ell+1} + e_{\ell+2} - \langle ze_{\ell+1} + e_{\ell+2}, w_{\ell+2} \rangle \frac{w_{\ell+2}}{\|w_{\ell+2}\|_2^2}.$$

Note that

$$\|w_{\ell+2}\|_2^2 = |z|^2 + \frac{\sum_{j=\ell+3}^{m+1} |z|^{2j-2(\ell+2)-2}}{(\sum_{i=0}^{m-(\ell+2)} |z|^{2i})^2} = |z|^2 + \frac{1}{\sum_{i=0}^{m-(\ell+2)} |z|^{2i}} = \frac{\sum_{i=0}^{m-(\ell+1)} |z|^{2i}}{\sum_{i=0}^{m-(\ell+2)} |z|^{2i}}. \quad (12)$$

Thus

$$\begin{aligned} w_{\ell+1} &= ze_{\ell+1} + e_{\ell+2} - \bar{z} \frac{\sum_{i=0}^{m-(\ell+2)} |z|^{2i}}{\sum_{i=0}^{m-(\ell+1)} |z|^{2i}} \left(ze_{\ell+2} + \frac{1}{\sum_{i=0}^{m-(\ell+2)} |z|^{2i}} \left(\sum_{j=\ell+2+1}^{m+1} (-\bar{z})^{j-(\ell+2)-1} e_j \right) \right) \\ &= ze_{\ell+1} + e_{\ell+2} \frac{1}{\sum_{i=0}^{m-(\ell+1)} |z|^{2i}} + \frac{-\bar{z}}{\sum_{i=0}^{m-(\ell+1)} |z|^{2i}} \left(\sum_{j=\ell+2+1}^{m+1} (-\bar{z})^{j-(\ell+2)-1} e_j \right) \\ &= ze_{\ell+1} + \frac{1}{\sum_{i=0}^{m-(\ell+1)} |z|^{2i}} \left(\sum_{j=\ell+2}^{m+1} (-\bar{z})^{j-(\ell+2)} e_j \right). \end{aligned}$$

Thus $w_{\ell+1}$ has the desired form, completing the proof by induction. $\square$

We will now use Lemmas 22 and 23 to explicitly compute the distance on the left side of (10), which will lead to a proof that $\{ze_i + e_{i+1} : 1 \leq i \leq m\}$ is $(\varepsilon_{z,m})$ -stable. We will consider 3 cases: where $\ell = 1$, where $2 \leq \ell \leq m - 1$, and where $\ell = m$.

For the $\ell = 1$ case, the distance from $ze_1 + e_2$ to $\text{Span}\{ze_i + e_{i+1} : 2 \leq i \leq m\}$ is the length of w_1 using Lemma 23, which is (see (12))

$$\|w_1\|_2 = \left(\frac{\sum_{i=0}^m |z|^{2i}}{\sum_{i=0}^{m-1} |z|^{2i}} \right)^{1/2} = \left(\frac{1 - |z|^{2m+2}}{1 - |z|^{2m}} \right)^{1/2},$$

assuming $|z| \neq 1$. When $|z| < 1$, we have $\|w_1\|_2 \geq 1$; and when $|z| > 1$, we have $\|w_1\|_2 \geq (|z|^{2m+2}/|z|^{2m})^{1/2} = |z| > 1$. Thus, assuming $|z| \neq 1$, the distance on the left side of (10) is at least 1 when $\ell = 1$.

For the $\ell = m$ case, the distance from $ze_m + e_{m+1}$ to $\text{Span}\{ze_i + e_{i+1} : 1 \leq i \leq m - 1\}$ is the length of w_m using Lemma 22, which is (see (11))

$$\|w_m\|_2 = \left(\frac{\sum_{j=0}^m |z|^{2j}}{\sum_{i=0}^{m-1} |z|^{2i}} \right)^{1/2} = \left(\frac{1 - |z|^{2m+2}}{1 - |z|^{2m}} \right)^{1/2},$$

assuming $|z| \neq 1$. When $|z| < 1$, we have $\|w_m\|_2 \geq 1$; and when $|z| > 1$, we have $\|w_m\|_2 \geq (|z|^{2m+2}/|z|^{2m})^{1/2} = |z| > 1$. Thus, assuming $|z| \neq 1$, the distance on the left side of (10) is at least 1 when $\ell = m$.

For the $2 \leq \ell \leq m-1$ case, the distance from $ze_\ell + e_{\ell+1}$ to $\text{Span}\{ze_i + e_{i+1} : 1 \leq i \leq m, i \neq \ell\}$ is more complicated. The orthogonal basis for $\{ze_i + e_{i+1} : 1 \leq i \leq m, i \neq \ell\}$ is $\{w_1, \dots, w_{\ell-1}\} \cup \{w_{\ell+1}, \dots, w_m\}$, where the first $\ell-1$ vectors are orthogonalized using Lemma 22 and the last $m-\ell$ vectors are orthogonalized using Lemma 23. The distance in question is equal to the norm of v where

$$\begin{aligned} v &:= ze_\ell + e_{\ell+1} - \frac{zw_{\ell-1}}{\|w_{\ell-1}\|_2^2} - \frac{\bar{z}w_{\ell+1}}{\|w_{\ell+1}\|_2^2} \\ &= ze_\ell - z \frac{\sum_{i=0}^{\ell-2} |z|^{2i}}{\sum_{j=0}^{\ell-1} |z|^{2j}} \left(e_\ell + \frac{z}{\sum_{i=0}^{\ell-2} |z|^{2i}} \left(\sum_{j=0}^{\ell-2} (-z)^{\ell-2-j} |z|^{2j} e_{j+1} \right) \right) \\ &\quad + e_{\ell+1} - \bar{z} \frac{\sum_{i=0}^{m-(\ell+1)} |z|^{2i}}{\sum_{i=0}^{m-\ell} |z|^{2i}} \left(ze_{\ell+1} + \frac{1}{\sum_{i=0}^{m-(\ell+1)} |z|^{2i}} \left(\sum_{j=\ell+2}^{m+1} (-\bar{z})^{j-(\ell+1)-1} e_j \right) \right) \\ &= \frac{z}{\sum_{i=0}^{\ell-1} |z|^{2i}} \left(\sum_{j=0}^{\ell-1} (-z)^{\ell-1-j} |z|^{2j} e_{j+1} \right) + \frac{1}{\sum_{i=0}^{m-\ell} |z|^{2i}} \left(\sum_{j=\ell+1}^{m+1} (-\bar{z})^{j-(\ell+1)} e_j \right). \end{aligned}$$

The above vector v has norm-squared

$$\begin{aligned} \|v\|_2^2 &= \frac{|z|^{2\ell}}{\sum_{i=0}^{\ell-1} |z|^{2i}} + \frac{1}{\sum_{i=0}^{m-\ell} |z|^{2i}} \\ &= \frac{|z|^{2\ell}(1-|z|^2)}{1-|z|^{2\ell}} + \frac{1-|z|^2}{1-|z|^{2m-2\ell+2}} \\ &= (1-|z|^2) \left(-1 + \frac{1}{1-|z|^{2\ell}} + \frac{1}{1-|z|^{2m-2\ell+2}} \right) \end{aligned}$$

assuming $|z| \neq 1$. If $|z| > 1$, then $\|v\|_2 \geq (|z|^2 - 1)^{1/2}$; and if $|z| < 1$, then $\|v\|_2 \geq (1 - |z|^2)^{1/2}$. Thus, assuming $|z| \neq 1$, the distance on the left side of (10) is at least $|1 - |z|^2|^{1/2}$ when $2 \leq \ell \leq m-1$.

Putting together the three cases above, we have proven (10) with $\varepsilon_{z,m} = \min\{1, |1 - |z|^2|^{1/2}\}$, completing the proof of Lemma 20.

6.4. Proof of Lemma 21

Recall that $T_{b,n} + zI$ is a block diagonal matrix in which $b+1$ by $b+1$ each block has the form

$$\begin{pmatrix} z & 1 & 0 & \dots & 0 \\ 0 & z & 1 & 0 & \vdots \\ \vdots & & \ddots & \ddots & \vdots \\ 0 & \dots & & z & 1 \\ 0 & 0 & \dots & 0 & z \end{pmatrix}.$$

If $b+1$ does not divide n evenly, the last block is a smaller k by k block (where $k \leq b$) also having the form above. The blocks are orthogonal, so to compute the distance from a given row to the span of the other rows in $T_{b,n} + zI$, it is sufficient to compute the distance from the given row to the span of the other rows in the same block. Thus, we will show that

$$\text{dist}(ze_{b+1}, \text{Span}\{ze_i + e_{i+1} : 1 \leq i \leq b\}) \geq \varepsilon_{z,b} \quad (13)$$

and that

$$\text{dist}(ze_\ell + e_{\ell+1}, \text{Span}(\{ze_i + e_{i+1} : 1 \leq i \leq b, i \neq \ell\} \cup \{ze_{b+1}\})) \geq \varepsilon_{z,b}, \quad (14)$$

where $\varepsilon_{z,m} \geq ||z|^2 - 1|^{1/2}$ if $|z| > 1$ and $\varepsilon_{z,m} \geq |z|^{b+1}|1 - |z|^2|^{1/2}$ if $|z| < 1$.

To prove (13), we orthogonalize $\{ze_i + e_{i+1} : 1 \leq i \leq b\}$ the basis $\{w_1, \dots, w_b\}$ with the form in Lemma 22 (letting $\ell = b + 1$). The distance from ze_{b+1} to $\text{Span}\{ze_i + e_{i+1} : 1 \leq i \leq b\}$ is thus the length of the vector

$$\begin{aligned} v &:= ze_{b+1} - \langle ze_{b+1}, w_b \rangle \frac{w_b}{\|w_b\|_2^2} \\ &= ze_{b+1} - z \frac{\sum_{i=0}^{b-1} |z|^{2i}}{\sum_{j=0}^b |z|^{2j}} \left(e_{b+1} + \frac{z}{\sum_{i=0}^{b-1} |z|^{2i}} \left(\sum_{j=0}^{b-1} (-z)^{b-1-j} |z|^{2j} e_{j+1} \right) \right) \\ &= \frac{z}{\sum_{i=0}^b |z|^{2i}} \left(\sum_{j=0}^b (-z)^{b-j} |z|^{2j} e_{j+1} \right). \end{aligned}$$

Thus we have

$$\|v\|_2^2 = \frac{|z|^{2(b+1)}}{\sum_{i=0}^b |z|^{2i}} = |z|^{2(b+1)} \frac{1 - |z|^2}{1 - |z|^{2(b+1)}},$$

assuming $|z| \neq 1$. If $|z| > 1$, then $\|v\|_2 \geq ||z|^2 - 1|^{1/2}$; and if $|z| < 1$, then $\|v\|_2 \geq |z|^{b+1}|1 - |z|^2|^{1/2}$.

To prove (14), we will orthogonalize $\{ze_i + e_{i+1} : 1 \leq i \leq b, i \neq \ell\} \cup \{ze_{b+1}\}$ in two parts. The set $\{ze_i + e_{i+1} : 1 \leq i \leq \ell - 1\}$ has an orthogonal basis $\{w_1, \dots, w_{\ell-1}\}$ with the form in Lemma 22, and, as we will show below, the remaining vectors have an orthogonal basis that is as rescaling of the standard basis.

Lemma 24. *The vectors $\{ze_i + e_{i+1} : \ell + 1 \leq i \leq b\} \cup \{ze_{b+1}\}$, where e_i is the i th standard basis vector, have an orthogonal basis $\{ze_i : \ell + 1 \leq i \leq b + 1\}$, which is a rescaling of the standard basis.*

Proof. Let the orthogonal basis be $w_1, \dots, w_{b+1}$. We orthogonalize starting with the vector $w_{b+1} = ze_{b+1}$. Let $k < b + 1$ be an integer, and assume by induction that $w_j = ze_j$ for $k + 1 \leq j \leq b + 1$. Then

$$w_k = ze_k + e_{k+1} - \langle ze_k + e_{k+1}, w_{k+1} \rangle \frac{w_{k+1}}{\|w_{k+1}\|_2^2} = ze_k,$$

completing the proof by induction. □

We will now compute the distance on the left side of (14) explicitly using the orthogonal basis $\{w_1, \dots, w_{\ell-1}, ze_{\ell+1}, ze_{\ell+2}, \dots, ze_{b+1}\}$, where the w_i have the form described in Lemma 22. The distance is the length of the vector v where

$$\begin{aligned} v &= ze_\ell + e_{\ell+1} - \langle ze_\ell + e_{\ell+1}, ze_{\ell+1} \rangle \frac{ze_{\ell+1}}{|z|^2} - \langle ze_\ell + e_{\ell+1}, w_{\ell-1} \rangle \frac{w_{\ell-1}}{\|w_{\ell-1}\|_2^2} \\ &= ze_\ell - \langle ze_\ell, w_{\ell-1} \rangle \frac{w_{\ell-1}}{\|w_{\ell-1}\|_2^2} \\ &= \frac{z}{\sum_{i=0}^{\ell-1} |z|^{2i}} \left(\sum_{j=0}^b (-z)^{\ell-1-j} |z|^{2j} e_{j+1} \right). \end{aligned}$$

Thus we have

$$\|v\|_2^2 = \frac{|z|^{2\ell}}{\sum_{i=0}^b |z|^{2i}} = |z|^{2\ell} \frac{1 - |z|^2}{1 - |z|^{2\ell}},$$

assuming $|z| \neq 1$. If $|z| > 1$, then $\|v\|_2 \geq ||z|^2 - 1|^{1/2}$; and if $|z| < 1$, then $\|v\|_2 \geq |z|^\ell |1 - |z|^2|^{1/2}$. Since $\ell < b$ by assumption, we have proved (14).

Finally, note that in case where $b + 1$ does not evenly divide n , there is a last diagonal block in $T_{b,n} + zI$ equal to $T_k + zI_k$ where $k \leq b$. The arguments above apply to this block as well, with $b + 1$ being replaced by k , and we need only note that the final lower bounds on $\varepsilon_{z,k-1}$ are the same when $|z| \geq 1$ and slightly better when $|z| < 1$ than the corresponding bounds on $\varepsilon_{z,b}$. This completes the proof of Lemma 21.

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