

# LINEAR ALGEBRA AND VECTOR ANALYSIS

MATH 22A

## Unit 19: Extrema

### LECTURE

**19.1.** All functions are assumed here to be in  $C^2$ . It all starts with an observation going back to Pierre de Fermat:

**Theorem:** If  $x_0$  is a maximum of  $f : \mathbb{R}^m \rightarrow \mathbb{R}$ , then  $\nabla f(x_0) = 0$ .

Proof. We prove by contradiction. Assume  $\nabla f(x_0) \neq 0$ , define the vector  $v = \nabla f(x_0)$  and look at  $g(t) = f(x_0 + tv)$ , which is a function of one variable. By the chain rule, it satisfies  $g'(0) = \nabla f(x_0 + 0v) \cdot v = |\nabla f|^2 > 0$ . This means that  $f(x_0 + tv) > f(x_0)$  for small  $t > 0$ . The point  $x_0$  can not have been maximal. This is a **contradiction**. QED.

**19.2.** A point  $x$  with  $\nabla f(x) = 0$  is called a **critical point** of  $f$ . By the Taylor formula, we have at a critical point  $x_0$  the quadratic approximation  $Q(x) = f(x_0) + (x - x_0)^T H(x_0)(x - x_0)/2$ , where  $H(x_0)$  is the **Hessian matrix**

$$H(x_0) = \begin{bmatrix} f_{x_1 x_1} & f_{x_1 x_2} & \cdots & f_{x_1 x_m} \\ f_{x_2 x_1} & f_{x_2 x_2} & \cdots & f_{x_2 x_m} \\ \cdots & \cdots & \cdots & \cdots \\ f_{x_m x_1} & f_{x_m x_2} & \cdots & f_{x_m x_m} \end{bmatrix}.$$

**19.3.** As in one dimension, having a critical point does not assure that a point is a local maximum or minimum. The second derivative test in single variable calculus assures that if  $f'(x_0) = 0$ ,  $f''(x_0) > 0$ , we have a local minimum and if  $f'(x_0) = 0$ ,  $f''(x_0) < 0$ , we have a local maximum. If  $f''(x_0) = 0$ , we can not say anything without looking at higher derivatives.

**19.4.** A matrix  $A$  is called **positive definite** if  $v \cdot Av > 0$  for all vectors  $v \neq 0$ . It is called **negative definite** if  $v \cdot Av < 0$  for all vectors  $v \neq 0$ . A diagonal matrix with positive diagonal entries is positive definite. In the following statements, we assume  $x_0$  is a critical point.

**19.5.** We say  $x_0$  is a **local maximum** of  $f$  if there exists  $r > 0$  such that  $f(x) \leq f(x_0)$  for all  $|x - x_0| < r$ . We say, it is a **local minimum** of  $f$  if  $f(x) \geq f(x_0)$  for all  $|x - x_0| < r$ . How can we check whether a point is a local maximum or minimum?

**Theorem:** Assume  $\nabla f(x_0) = 0$ . If  $H(x_0)$  is positive definite, then  $x_0$  is a local minimum. If  $H(x_0)$  is negative definite, then  $x_0$  is a local maximum.

**19.6.** Proof: as  $\nabla f(x_0) = 0$ , the quadratic approximation at  $x_0$  is  $Q(x) = f(x_0) + H(x_0)v \cdot v/2 > f(x_0)$  for small non-zero  $v = x - x_0$  and Hessian  $H$ . The analogue statement for the minimum can be deduced by replacing  $f$  with  $-f$ .

**19.7.** Let us look at the case, where  $f(x, y)$  is a function of two variables such that  $f_x(x_0, y_0) = 0$  and  $f_y(x_0, y_0) = 0$ . The Hessian matrix is

$$H(x_0, y_0) = \begin{bmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{bmatrix}.$$

In this two dimensional case, we can classify the critical points if the determinant  $D = \det(H) = f_{xx}f_{yy} - f_{xy}^2$  of  $H$  is non-zero. The number  $D$  is also called the **discriminant** at a critical point.

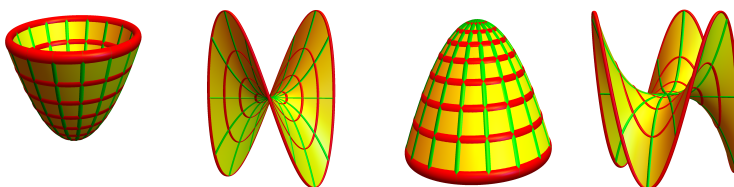


FIGURE 1.  $f = x^2 + y^2$  gives a minimum,  $f = -x^2 - y^2$  a maximum and  $f = x^2 - y^2$  a saddle. The case  $f = x^2y - yx^2$  is not Morse.

**19.8.** We say  $(x_0, y_0)$  is a **Morse point**, if  $(x_0, y_0)$  is a critical point and the determinant is non-zero. A  $C^2$  function is a **Morse function** if every critical point is Morse. Examples of Morse functions are  $f(x, y) = x^2 + y^2$ ,  $f(x, y) = -x^2 - y^2$  and  $f(x, y) = x^2 - y^2$ . The last case is called a **hyperbolic saddle**. In general, a critical point is a hyperbolic saddle if  $D \neq 0$  and if it is neither a maximum nor a minimum. Here is the **second derivative test** in dimension 2:

**Theorem:** Assume  $f \in C^2$  has a critical point  $(x_0, y_0)$  with  $D \neq 0$ .  
 If  $D > 0$  and  $f_{xx} > 0$  then  $(x_0, y_0)$  is a local minimum.  
 If  $D > 0$  and  $f_{xx} < 0$  then  $(x_0, y_0)$  is a local maximum.  
 If  $D < 0$  then  $(x_0, y_0)$  is a hyperbolic saddle.

**19.9.** Proof. After translation  $(x, y) \rightarrow (x - x_0, y - y_0)$  and replacing  $f$  with  $f - f(x_0, y_0)$ , we have  $(x_0, y_0) = (0, 0)$  and  $f(0, 0) = 0$ . At the critical point, the quadratic approximation is now

$$Q(x, y) = ax^2 + 2bxy + cy^2.$$

This can be rewritten as  $a(x + \frac{b}{a}y)^2 + (c - \frac{b^2}{a})y^2 = a(A^2 + DB^2)$  with  $A = (x + \frac{b}{a}y)$ ,  $B = b^2/a^2$  and discriminant  $D$ . If  $a = f_{xx} > 0$  and  $D > 0$  then  $c - b^2/a > 0$  and the function has positive values for all  $(x, y) \neq (0, 0)$ . The point  $(0, 0)$  is then a minimum. If  $a = f_{xx} < 0$  and  $D > 0$ , then  $c - b^2/a < 0$  and the function has negative values for all  $(x, y) \neq (0, 0)$  and the point  $(x, y)$  is a local maximum. If  $D < 0$ , then  $f$  takes both negative and positive values near  $(0, 0)$ . QED

**19.10.** One can ask, why  $f_{xx}$  and not  $f_{yy}$  is chosen. It does not matter, because if  $D > 0$ , then both  $f_{xx}$  and  $f_{yy}$  need to be non-zero and have the same sign. Instead of  $f_{xx}$ , one could also have pick the more natural **trace**  $\text{tr}(H)$ . It is invariant under coordinate changes similarly as the determinant  $D$ . The discriminant  $D$  happens also to be the **Gauss curvature** of the surface at the point.

**19.11.** In higher dimensions, the situation is described by the **Morse lemma**. It tells that near a critical point there is a coordinate change  $\phi$  such that  $g(x) = f(\phi(x))$  is a quadratic function  $f(x) = B(x - x_0) \cdot (x - x_0)$  where  $B$  is diagonal with entries  $+1$  or  $-1$ . Critical point can then be given a **Morse index**, the number of entries  $-1$  in  $B$ . The Morse lemma is actually a theorem (theorems are more important than lemmata=helper theorems)

**Theorem:** Near a Morse critical point  $x_0$  of a  $C^2$  function  $f$ , there is a coordinate change  $\phi : \mathbb{R}^m \rightarrow \mathbb{R}^m$  such that  $g(x) = f(\phi(x)) - f(x_0)$  is

$$g(x) = -x_1^2 - \cdots - x_k^2 + x_{k+1}^2 + \cdots + x_m^2.$$

**19.12.** Proof. We use induction with respect to  $m$ . **(i) Induction foundation.** For  $m = 1$ , the result tells that for a Morse critical point, the function looks like  $y = x^2$  or  $y = -x^2$ . First show that if  $f(0) = f'(0) = 0, f''(0) \neq 0$ , then  $f(x) = x^2 h(x)$  or  $f(x) = -x^2 h(x)$  for some positive  $C^2$  function  $h$ . Proof. By a linear coordinate change we assume  $x_0 = 0$  and  $f(0) = 0$ . There exists then  $g(x)$  such that  $f(x) = xg(x)$ : it is  $g(x) = f(x)/x$  for  $x \neq 0$  and in the limit  $x \rightarrow 0$  the value of  $\lim_{x \rightarrow 0} (f(x) - f(0))/x = f'(0)$ . By the product rule,  $f'(x) = g(x) + xg'(x)$  with  $g(0) = 0$ . Because  $f'(0) = g(0) = 0$  can define  $f(x)/x^2$  for  $x \neq 0$  and take the limit  $x \rightarrow 0$ , because by applying Hôpital twice, the limit is  $f''(0)$ . The coordinate change is now given by a function  $y = \phi(x)$  satisfying  $g(x, y) = y\sqrt{h(y)} = x$ . Implicit differentiation gives  $g_y(0, 0) = \sqrt{h(y)} \neq 0$  so that by the implicit function theorem  $y(x)$  exists.

**(ii) Induction step  $m \rightarrow m+1$ :** we first note that Taylor for  $C^2$  with remainder term implies that  $f(x_1, \dots, x_n) = \sum_{i,j} x_i x_j h_{ij}(x_1, \dots, x_n)$  with some continuous functions  $h_{ij}$ . Furthermore, the function value  $h_{ij}(0) = f_{x_i x_j}(0) = H_{ij}(0)$  are the coordinates of the Hessian. Apply first a rotation so that  $h_{11} \neq 0$ . Now look at  $x_1$  and keep the other coordinates constant. As in (i), find a coordinate change  $\phi$  such that  $f(\phi(x)) = \pm x_1^2 + g(x_2, \dots, x_m)$ , where  $g$  inherits the properties of  $f$ <sup>1</sup>, but is of one dimension less. By induction assumption, there is a second coordinate change such that  $g(\psi(x)) = x_2^2 - \cdots - x_l^2 + x_{l+1}^2 + \cdots + x_m^2$ . Combining  $\phi$  and  $\psi$  produces the Morse normal form.

## EXAMPLES

**19.13.** Q: Classify the critical points of  $f(x, y) = x^3 - 3x - y^3 - 3y$ . A: As  $\nabla f(x, y) = [3x^2 - 3, -3y^2 + 3]^T$ , the critical points are  $(1, 1), (-1, 1), (1, -1)$  and  $(-1, -1)$ . We compute  $H(x, y) = \begin{bmatrix} 2x & 0 \\ 0 & -2y \end{bmatrix}$ . For  $(1, 1)$  and  $(-1, -1)$  we have  $D = -4$  and so saddle points. For  $(-1, 1)$ , we have  $D = 4, f_{xx} = -2$ , a local max. For  $(1, -1)$  where  $D = 4, f_{xx} = 2$  we have a local min.

<sup>1</sup>This will be more clear after having seen more linear algebra

# HOMEWORK

**Problem 19.1:** Classify the critical points of the **area 51** function

$$f(x, y) = x^{51} - 51x - y^{51} + 51y$$

using the second derivative test. This function is classified.

**Problem 19.2:** The function  $f(x, y) = 2x^3 + 2y^3 - 3x^2y^2$  is called the “happy function”. Find and classify its extrema.

This function is not Morse as for one of the critical points, the discriminant  $D$  is zero. We want you nevertheless to decide whether this point is a “local maximum” a “local minimum” or “neither of them”.

**Problem 19.3:** Where on the parametrized surface  $r(u, v) = [u^2, v^3, uv]$  is the temperature  $T(x, y, z) = 12x + y - 12z$  minimal. Classify all the critical points of the function  $f(u, v) = T(r(u, v))$ . [ If you have found the function  $f(u, v)$ , you can replace  $u, v$  again with  $x, y$  if you like to work with a function  $f(x, y)$ . ]

**Problem 19.4:** Find all the critical points of the function  $f(x, y, z) = (x - 1)^2 - y^2 + xz^2$ . In each of the cases, find the Hessian matrix. We have not talked about eigenvalues yet, but they are numbers  $\lambda$  such that  $Hv = \lambda v$  for some non-zero vector. One can find them by looking for the roots of the characteristic polynomial  $\chi_H(\lambda) = \det(L - \lambda)$ . You can calculate them on a computer. Find in each case the eigenvalues.

**Problem 19.5:** a) Find a function  $f(x, y)$  with 3 maxima and 3 saddle points and one minimum.

b) You see below a contour map of a function of two variables. How many critical points are there? Is the function a Morse function?

