

Name:

MWF9 George Boxer

MWF10 Omar Antolin

MWF10 Hector Pasten

MWF11 Oliver Knill

MWF12 Gabriel Bujokas

MWF12 Cheng-Chiang Tsai

TThu10 Simon Schieder

TThu11 Arul Shankar

- Start by writing your name in the above box and check your section in the box to the left.
- Try to answer each question on the same page as the question is asked. If needed, use the back or the next empty page for work. If you need additional paper, write your name on it.
- Do not detach pages from this exam packet or unstaple the packet.
- Please write neatly and except for problems 1-3, give details. Answers which are illegible for the grader can not be given credit.
- No notes, books, calculators, computers, or other electronic aids can be allowed.
- You have 90 minutes time to complete your work.

1		20
2		10
3		10
4		10
5		10
6		10
7		10
8		10
9		10
10		10
Total:		110

- | | | |
|-----|---|---|
| 1) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | The plane $x + y + z - 1 = 0$ is the kernel of a linear transformation T . |
| 2) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | For any matrix A the identity $\text{im}(A^2) = \text{im}(\text{rref}(A^2))$ holds. |
| 3) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | For any matrix A , one has $\ker(A) = \ker(\text{rref}(A))$. |
| 4) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | There is a 4×8 matrix whose kernel is 3-dimensional. |
| 5) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | There is a 2×2 matrix for which $A^2 = -I_2$. |
| 6) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If three vectors v_1, v_2 , and v_3 are in a plane, they are independent. |
| 7) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If S and A are invertible $n \times n$ matrices, then $(SAS^{-1})^{-1} = S^{-1}A^{-1}S$. |
| 8) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If all entries of a 2×2 matrix A are nonzero, then the inverse of A exists. |
| 9) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | For any square matrix A , the image of A^7 is contained in the image of A . |
| 10) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If A is a matrix, let B be the matrix for which the order of the columns are reversed. Then $\text{rref}(A) = \text{rref}(B)$. |
| 11) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If the columns of a $n \times n$ matrix form a basis in $\mathbb{R}^n$, then the rows also form a basis in $\mathbb{R}^n$. |
| 12) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If $B^2 = A$, then B is called the square root of A . Every 2×2 matrix A has either 0 or 1 or 2 square roots. |
| 13) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If A is an invertible 2×2 matrix and $\mathcal{B}$ is the basis of the column vectors, then $[A]_{\mathcal{B}}$ is diagonal. |
| 14) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | There exists a linear transformation whose image consists of exactly 6 distinct points. |
| 15) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | $\mathcal{B} = \{2e_1, 2e_2\}$ is a basis of $\mathbb{R}^2$ for which $[v]_{\mathcal{B}} = v$ for any v . |
| 16) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | The dimension of the image of a matrix A is equal to the dimension of the image of the matrix $\text{rref}(A)$. |
| 17) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | There exists an invertible $n \times n$ matrix whose inverse has rank $n - 1$. |
| 18) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If A is the reflection about a line L and B is the reflection about the plane $V = L^\perp$ perpendicular to L , then $A = -B$. |
| 19) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | The set of vectors in space satisfying $x + y + z = 1$ form a linear space of dimension 2. |
| 20) | <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">T</div> <div style="display: inline-block; border: 1px solid black; padding: 2px 5px; margin: 0 5px;">F</div> | If A, B are given $n \times n$ matrices, then there is a unique $n \times n$ matrix X satisfying $(A + X)B = A$ if B is invertible. |

	Total
--	-------

Problem 2) (10 points)

Match the matrices to their rref, enter R, U, V, W in the right order below:

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad R = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad U = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad D = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad V = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad W = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

rref(A) =	rref(B) =	rref(C) =	rref(D) =

b) Find the projection matrix onto the space spanned by the vectors $\vec{v} = \begin{bmatrix} 1 \\ 1 \\ -1 \\ 1 \end{bmatrix} / 2$, $\vec{w} = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} / 2$.

Problem 3) (10 points)

Each of the following matrices matches with a transformation below:

$$A = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ -1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ -\sqrt{2} & 1 \end{bmatrix} \quad C = \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$$

$$D = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix} \quad E = \begin{bmatrix} \sqrt{2} & -\sqrt{2} \\ \sqrt{2} & \sqrt{2} \end{bmatrix} \quad F = \begin{bmatrix} \sqrt{2} & 0 \\ 0 & \sqrt{2} \end{bmatrix}$$

rotation	dilation	rotation dilation	shear	projection	reflection

Each of the following spaces R, U, V, W below is equal to one of the spaces K, L, M, N . No justification is necessary.

$$R = \text{im} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \quad U = \text{im} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} \quad V = \text{im} \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 1 \end{bmatrix} \quad W = \text{im} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix}$$

$$K = \ker \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \end{bmatrix} \quad L = \ker \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$M = \ker \begin{bmatrix} 0 & 1 & -1 & 0 \\ 2 & -1 & -1 & 2 \end{bmatrix} \quad N = \ker \begin{bmatrix} 0 & 2 & -2 & 0 \\ 1 & -1 & 0 & 1 \end{bmatrix}$$

R =	U =	V =	W =

Problem 4) (10 points)

Solve the following system of linear equation by doing row reduction of the augmented matrix. In each step you have to use one of three basic row reduction steps. Write in each step, what you do:

$$\begin{array}{rrcr} x & & +z & = 1 \\ & y & +z & +q = 2 \\ x & & +z & +q = 2 \\ x & +y & & +q = 1 \end{array}$$

Problem 5) (10 points)

Two matrices A, B are called **similar** if there exists an invertible matrix S such that $B = S^{-1}AS$.

a) (2 points) Is it possible that the matrix $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$ be similar to a reflection about a line? Show your reasoning.

b) (3 points) What is the matrix A in the basis $\mathcal{B} = \{v_1, v_2, v_3\} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$?

c) (3 points) Find the inverse of the matrix S which contains the above basis as column vectors v_1, v_2, v_3 . Use row reduction to find the inverse.

d) (2 points) Express $\vec{v} = \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix}$ as a linear combination of v_1, v_2 and v_3 .

Problem 6) (10 points)

Here e_1, e_2, e_3 denote the standard basis vectors in $\mathbb{R}^n$.

a) (3 points) Find the 3×3 matrix A which is the reflection about the xz -plane.

b) (2 points) Find the 3×3 matrix B which maps e_1 to e_2 , e_2 to e_3 and e_3 to e_1 .

c) (2 points) Find the 3×3 matrix C which scales every vector by a factor 2.

d) (3 points) What is the transformation CBA which first reflects, then rotates and finally scales.

Problem 7) (10 points)

Find a basis for the image and the kernel of the following matrix:

$$A = \begin{bmatrix} 1 & 2 & 3 & 2 & 1 \\ 2 & 3 & 4 & 3 & 2 \\ 3 & 4 & 5 & 4 & 3 \\ 4 & 5 & 6 & 5 & 4 \\ 5 & 6 & 7 & 6 & 5 \end{bmatrix}.$$

Problem 8) (10 points)

We are given the rotation dilation matrix $A = \begin{bmatrix} 1 & -\sqrt{3} \\ \sqrt{3} & 1 \end{bmatrix}$.

- a) (3 points) Find a matrix B such that $B^2 = A$.
- b) (4 points) Write down the matrix B^{17} . We need a numerical result which can involve powers of numbers.
- c) (3 points) Can A be the product of a projection at a line L and a reflection Q at a second line K ?

Problem 9) (10 points)

Let A be a 3×3 matrix such that $A^3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$.

- a) (3 points) Why is $\text{im}(A^2)$ a subspace of $\text{ker}(A)$?
- b) (4 points) Find all possible values for $\text{rank}(A)$.
- c) (3 points) Give an example of such a matrix A for each possible rank.

Problem 10) (10 points)

Let A be a 3×3 matrix with $A^3 = 0$, the zero matrix.

- a) (3 points) Compare $\text{ker}(A)$ and $\text{im}(A)$ and $\text{im}(A^2)$. How are they related?
- b) (2 points) Is A invertible?
- c) (2 points) Is $A + I_3$ invertible where I_3 is the identity matrix? Hint. Look at $B = I_3 - A + A^2$.
- d) (3 points) Give examples of matrices A exhibiting all the relations you found in part a) and c).