

Math21b

Review to second
midterm

Spring 2007

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Orthonormal basis

$\{ w_1, w_2, \dots, w_n \}$
orthonormal basis

$$A = \begin{bmatrix} | & | & | & -| \\ | & | & -| & | \\ | & -| & | & | \\ | & -| & -| & -| \end{bmatrix} / 2$$

orthogonal matrix

$$A^T A = I$$

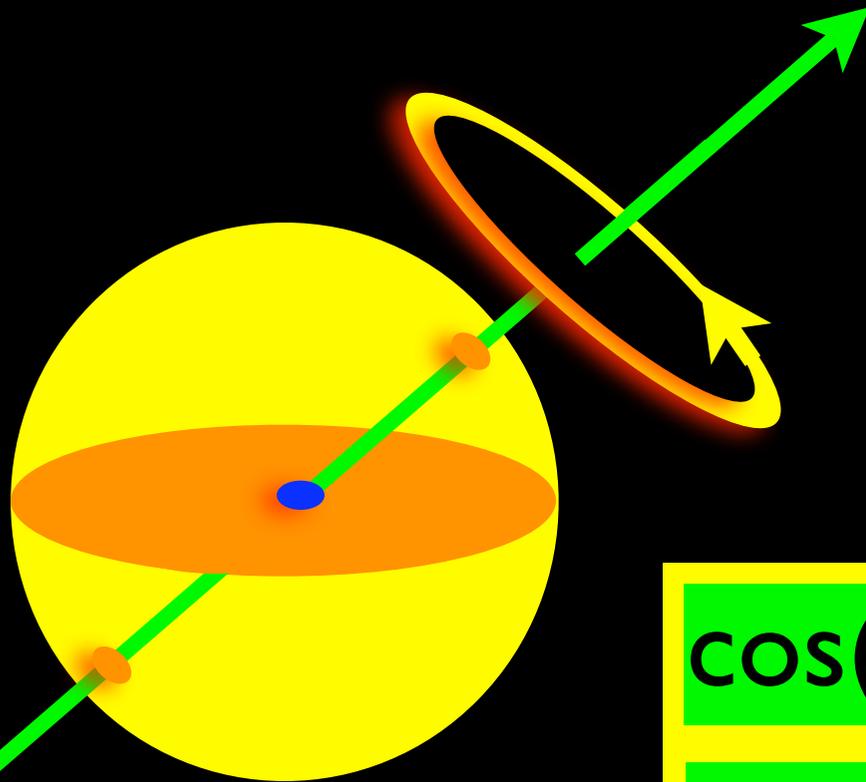
Orthogonal transformation

$$Q^T Q = I$$

- ✦ typically, reflections or rotations
- ✦ preserve length
- ✦ preserve angles
- ✦ column vectors of Q form orthonormal basis

Rotations

$$\det(Q) = 1$$



$$Q =$$

example:

$\cos(t)$	0	$-\sin(t)$
0	1	0
$\sin(t)$	0	$\cos(t)$

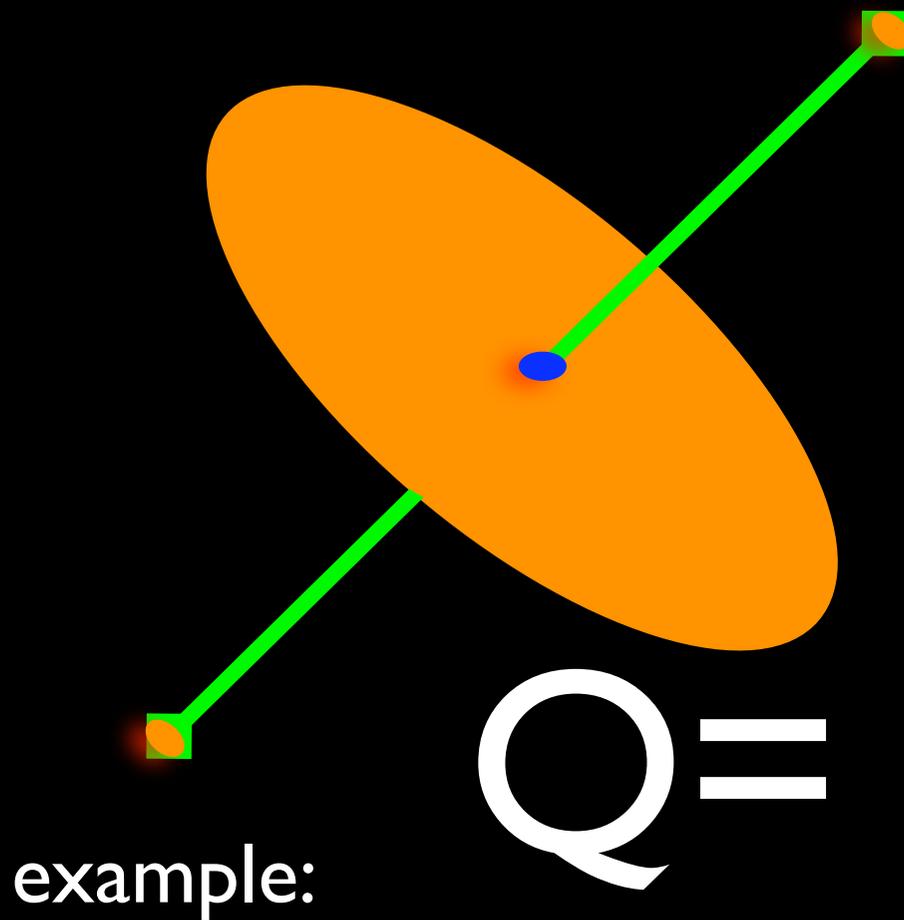
Reflections

$$\det(Q) = -1$$

if reflected at odd dimensional space

$$\det(Q) = +1$$

if reflected at even dimensional space



$$Q =$$

$$\cos(t)$$

$$0$$

$$\sin(t)$$

$$0$$

$$1$$

$$0$$

$$\sin(t)$$

$$0$$

$$-\cos(t)$$

don't confuse orthogonal transformations
with orthogonal projections
which satisfy for $n \times n$ matrices

$$A^2 = A$$

and are in general not
invertible.

Example:

$$A =$$

1	0	0
0	1	0
0	0	0

which is an orthogonal matrix?

1	1	-1	1
1	1	1	-1
1	-1	-1	-1
1	-1	1	1

$/2$

1	1	-1	-1
1	1	-1	1
1	-1	-1	-1
1	-1	-1	1

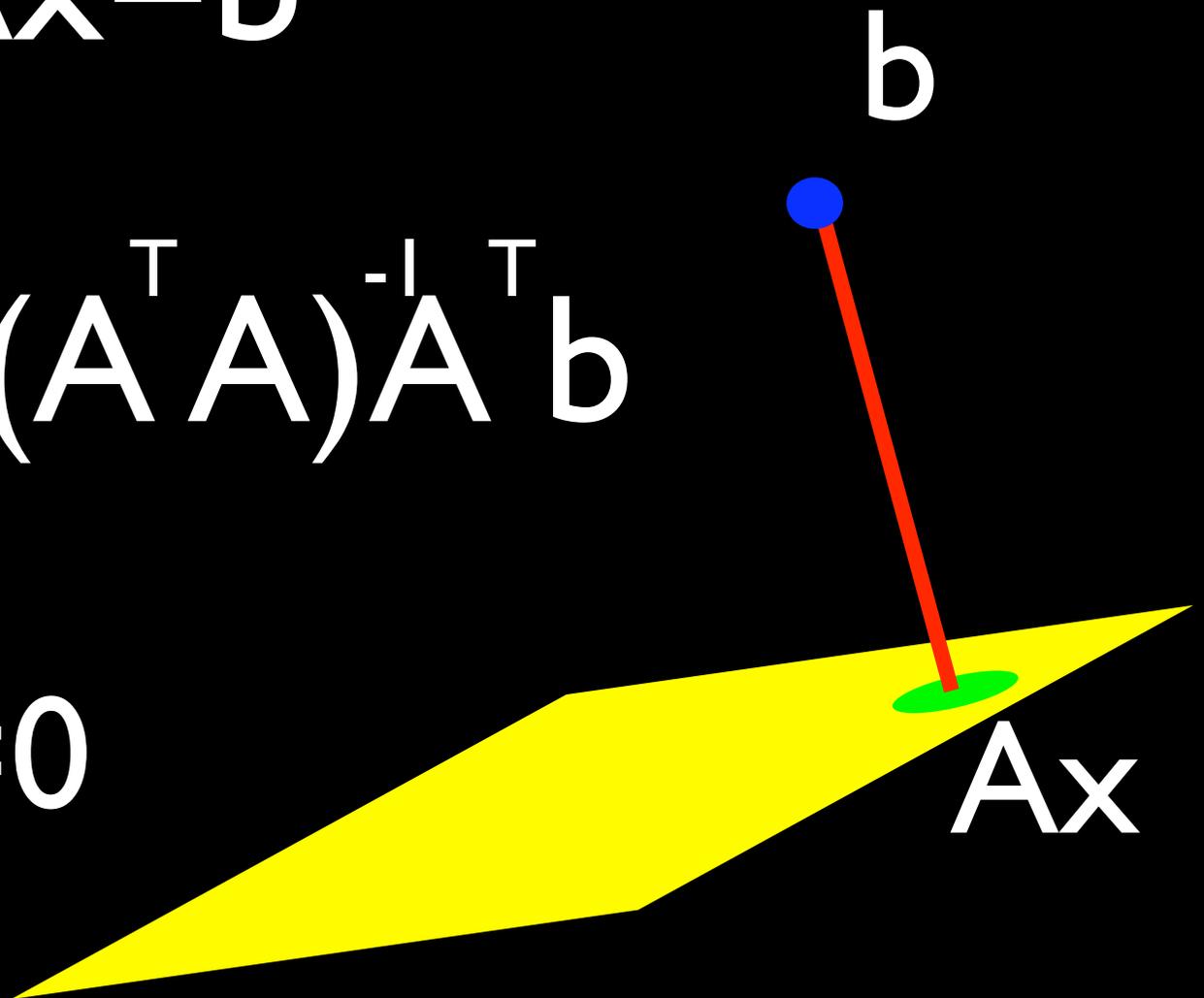
$/2$

Least Square Solution

$$Ax=b$$

$$x_* = (A^T A)^{-1} A^T b$$

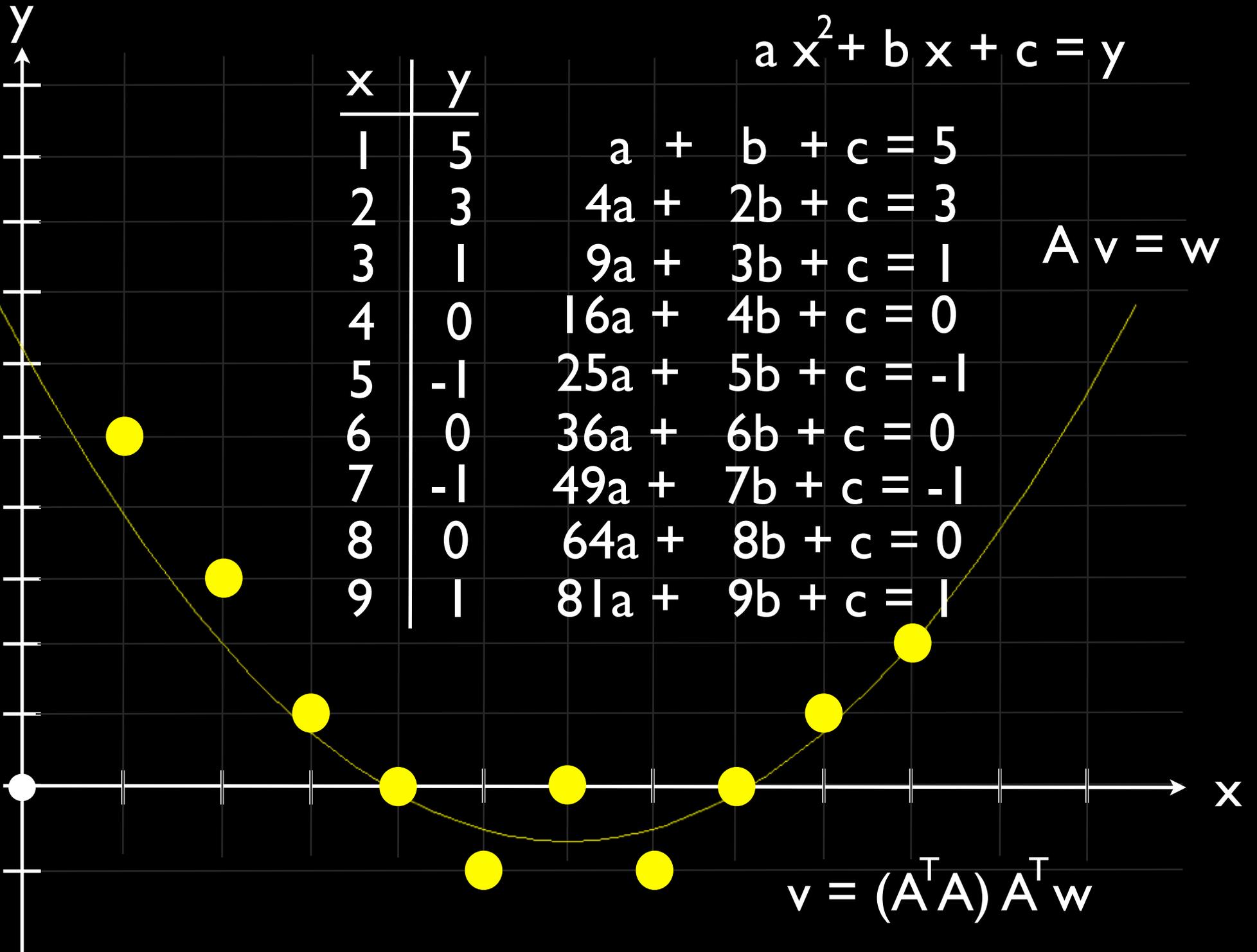
$$A^T (Ax-b)=0$$



Datafitting

To fit data with a set of functions, just plug in the data so that all data satisfy the equations.

Here is an example with functions $1, x, x^2$

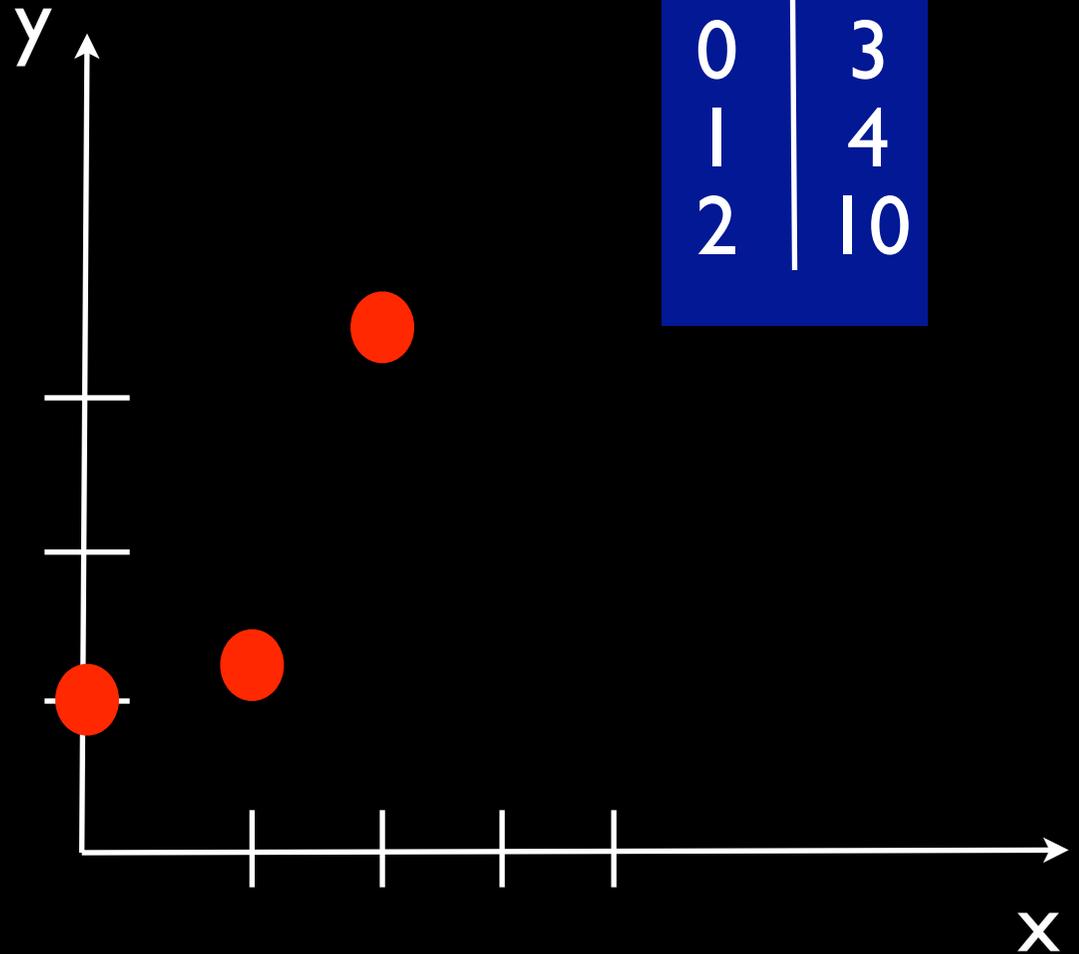




*blackboard
problem*

Fit the
following
data with
functions

$\cos(\pi x/2)$
 $x+1$



x	y
0	3
1	4
2	10

Solution:

x	y
0	3
1	4
2	10

$$a \cos(\pi x/2) + b(x+1) = y$$

$$a + b = 3$$

$$a + 2b = 4$$

$$a - 1 + 3b = 10$$

$$A^T = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 2 & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 2 \\ -1 & 3 \end{bmatrix}$$

$$A^T b = \begin{bmatrix} -7 \\ 41 \end{bmatrix}$$

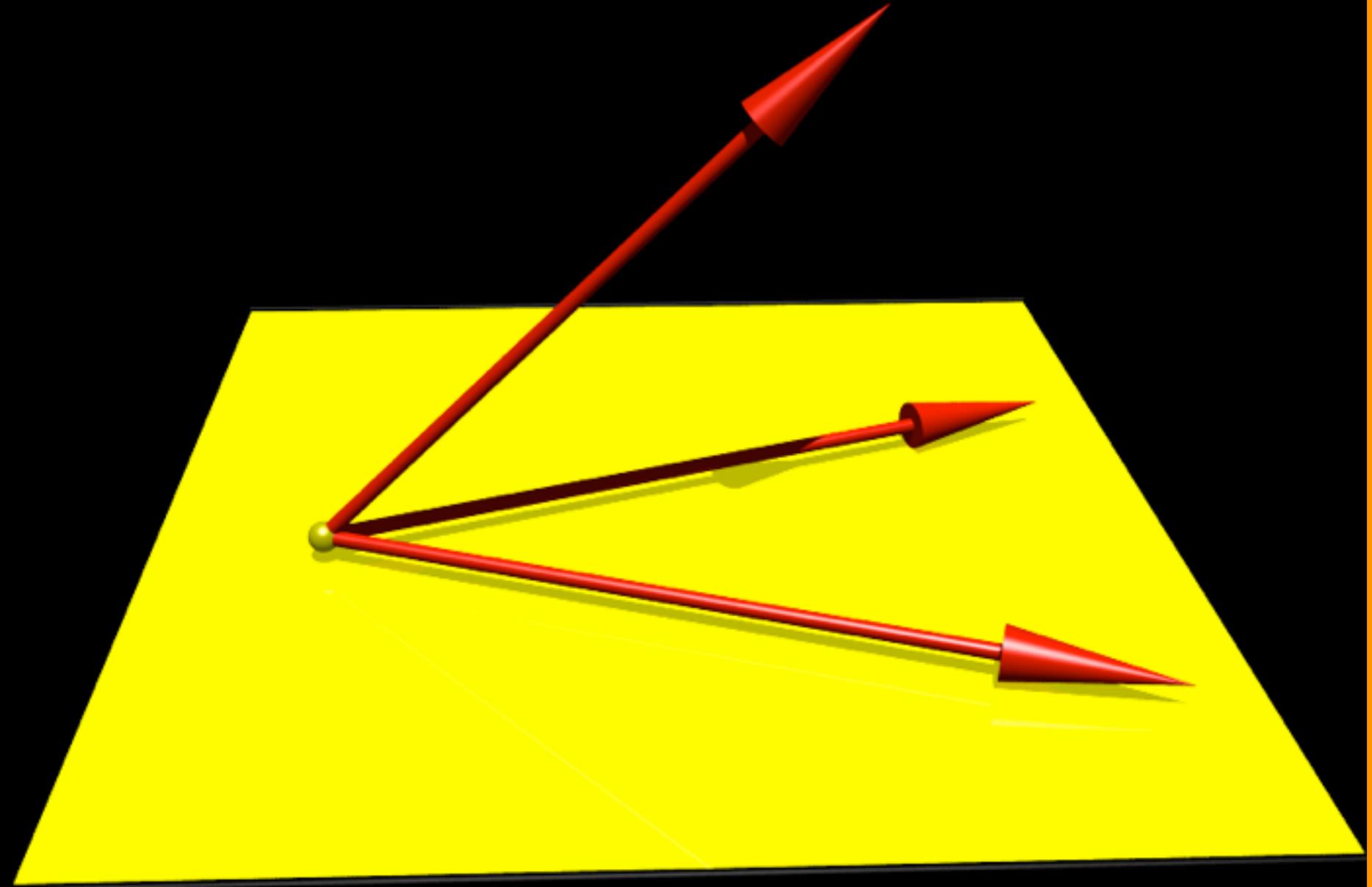
$$A^T A = \begin{bmatrix} 2 & -2 \\ -2 & 14 \end{bmatrix}$$

$$(A^T A)^{-1} = \begin{bmatrix} 7 & 1 \\ 1 & 1 \end{bmatrix}$$

$$(A^T A)^{-1} A^T b = \begin{bmatrix} -2/3 \\ 17/6 \end{bmatrix}$$

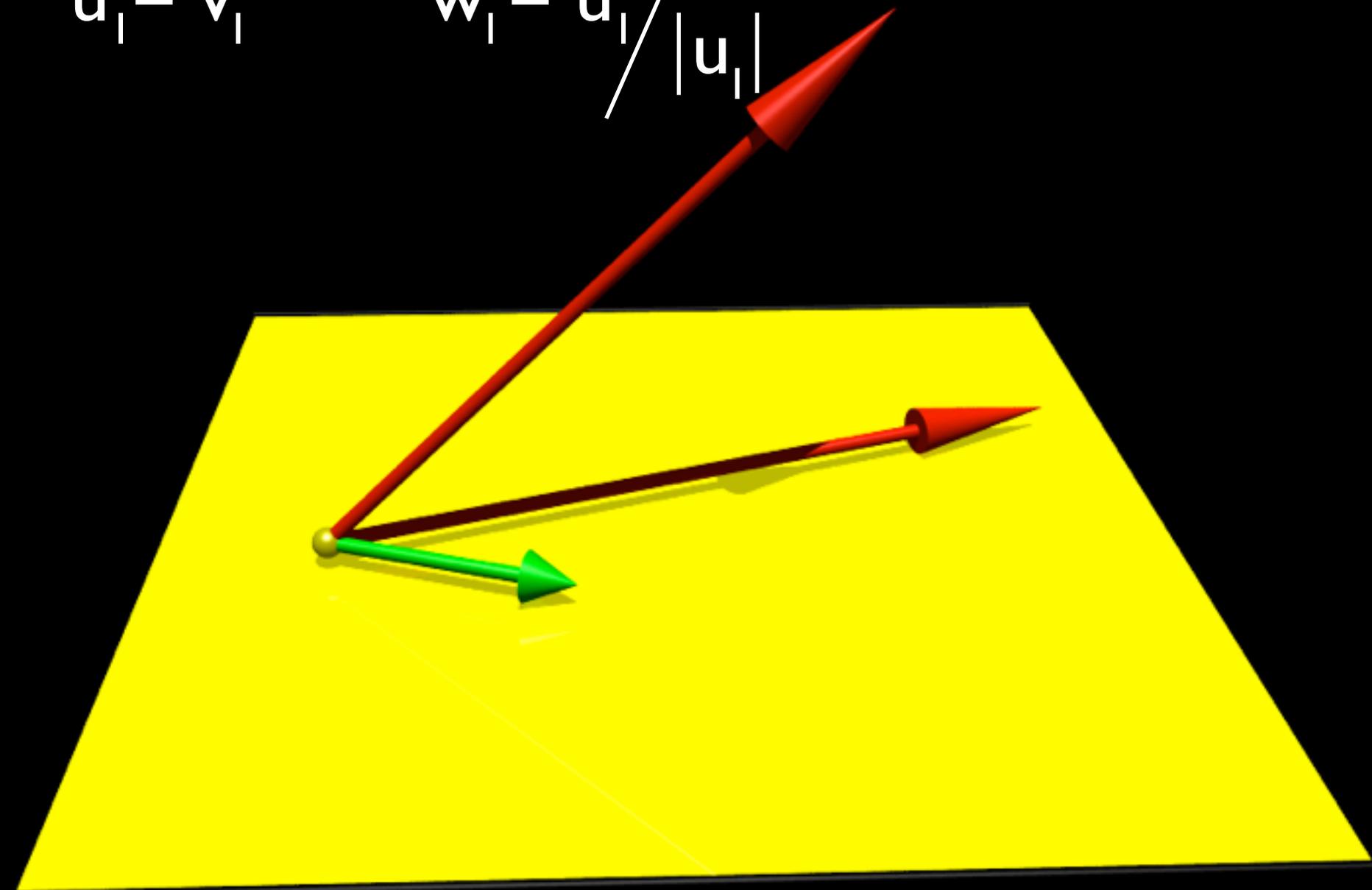
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Gram Schmidt +QR Decomposition



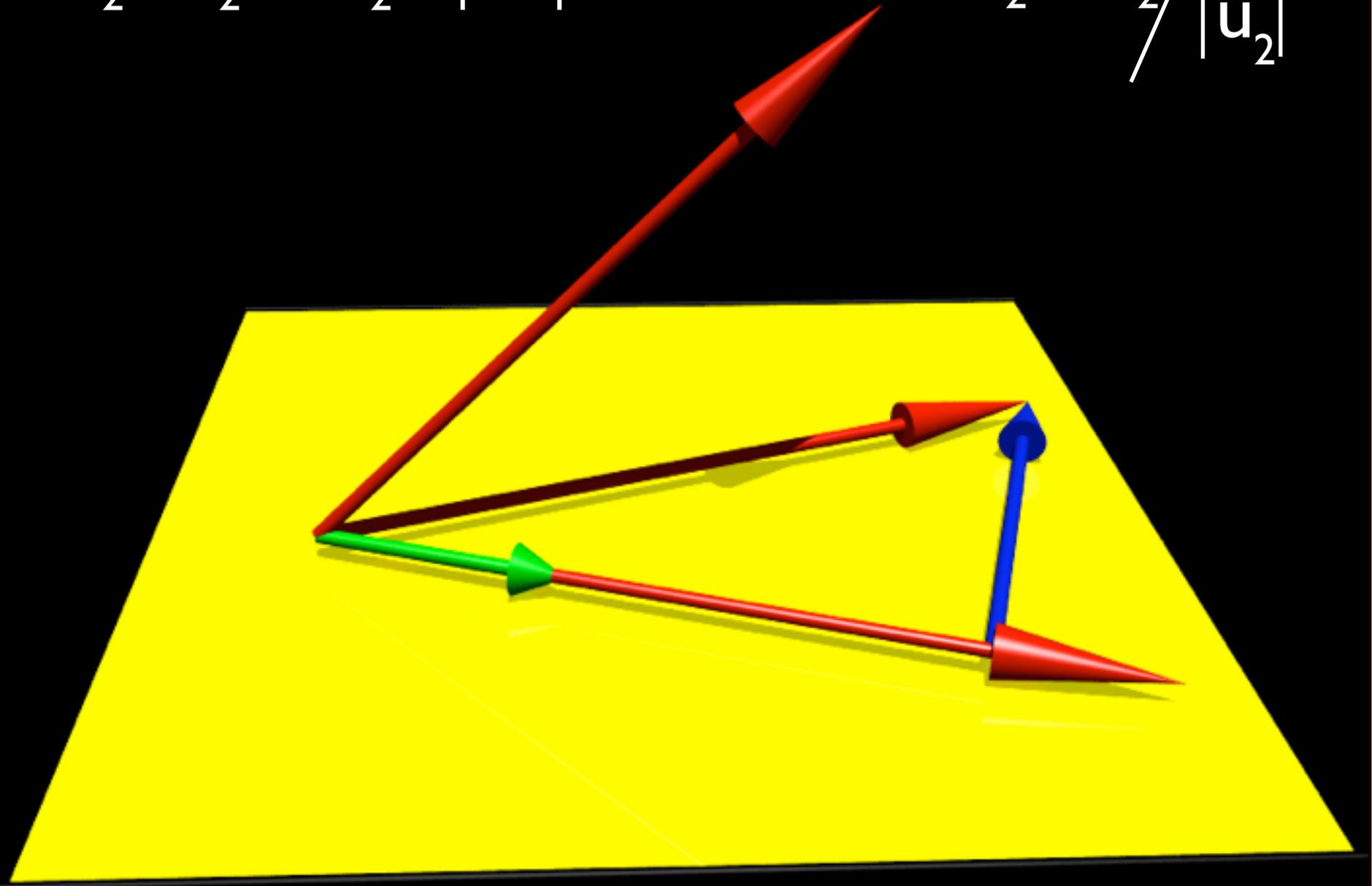
$$u_1 = v_1$$

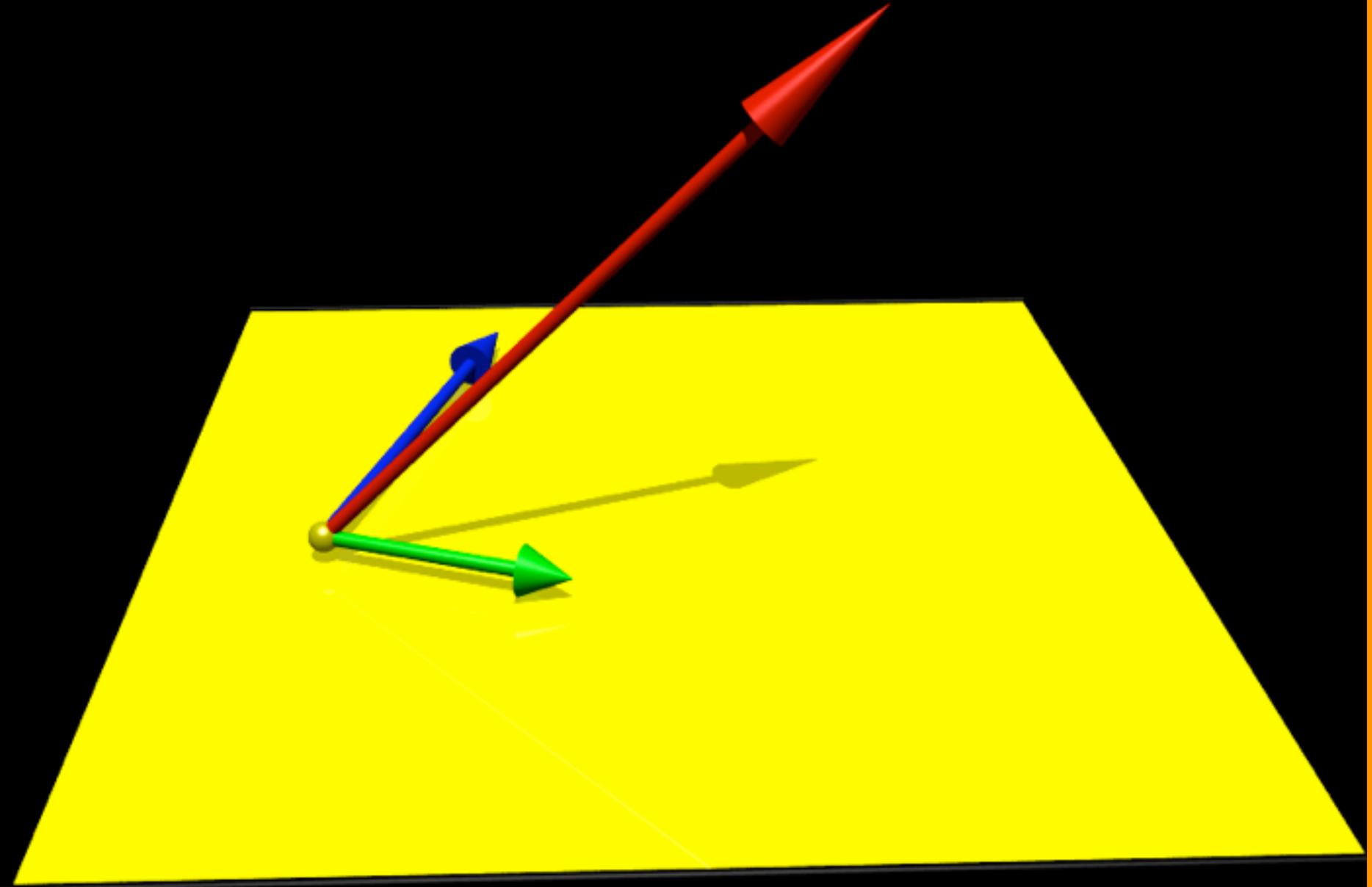
$$w_1 = u_1 / |u_1|$$



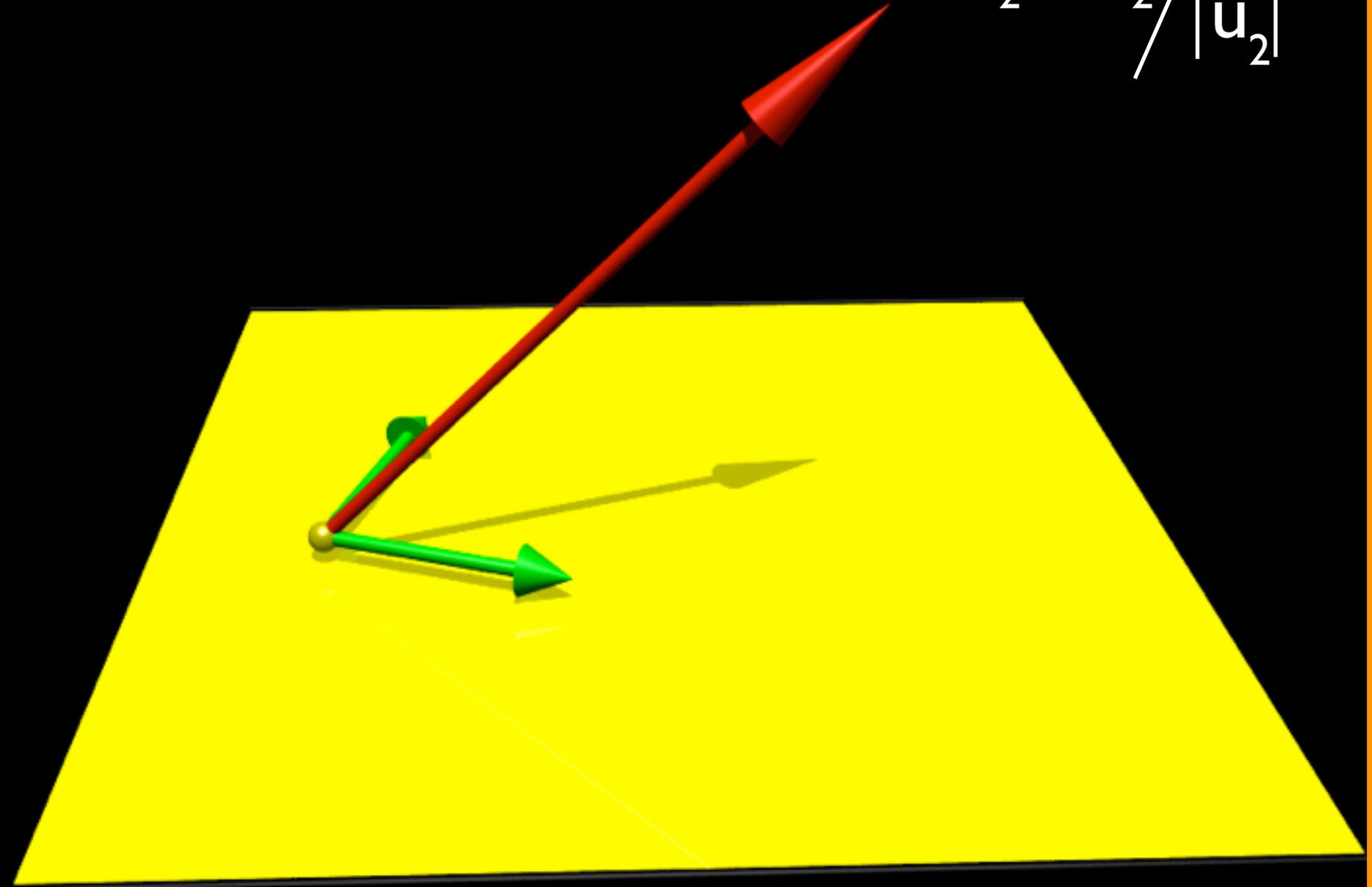
$$\mathbf{u}_2 = \mathbf{v}_2 - (\mathbf{v}_2 \cdot \mathbf{w}_1) \mathbf{w}_1$$

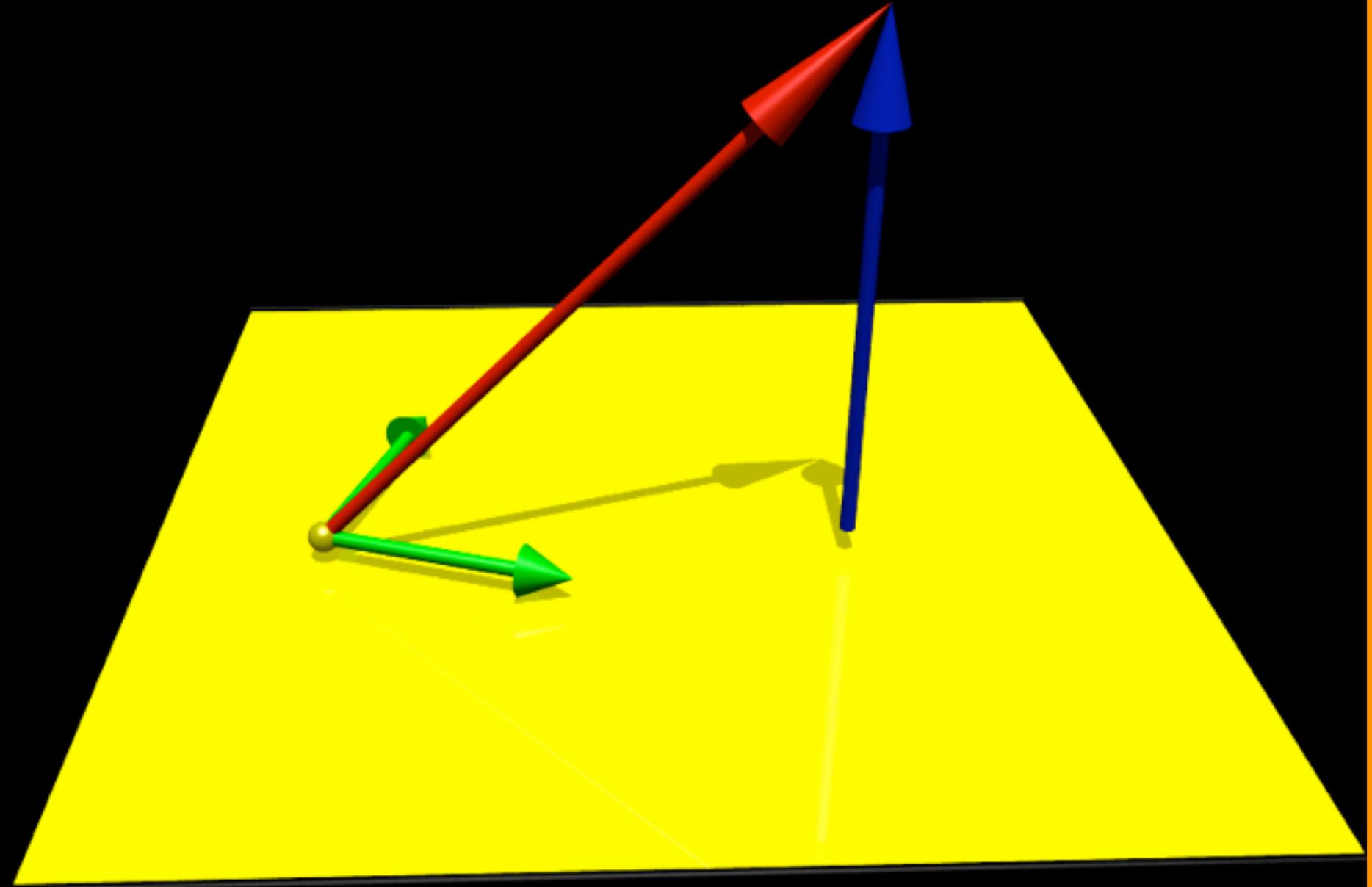
$$\mathbf{w}_2 = \mathbf{u}_2 / |\mathbf{u}_2|$$





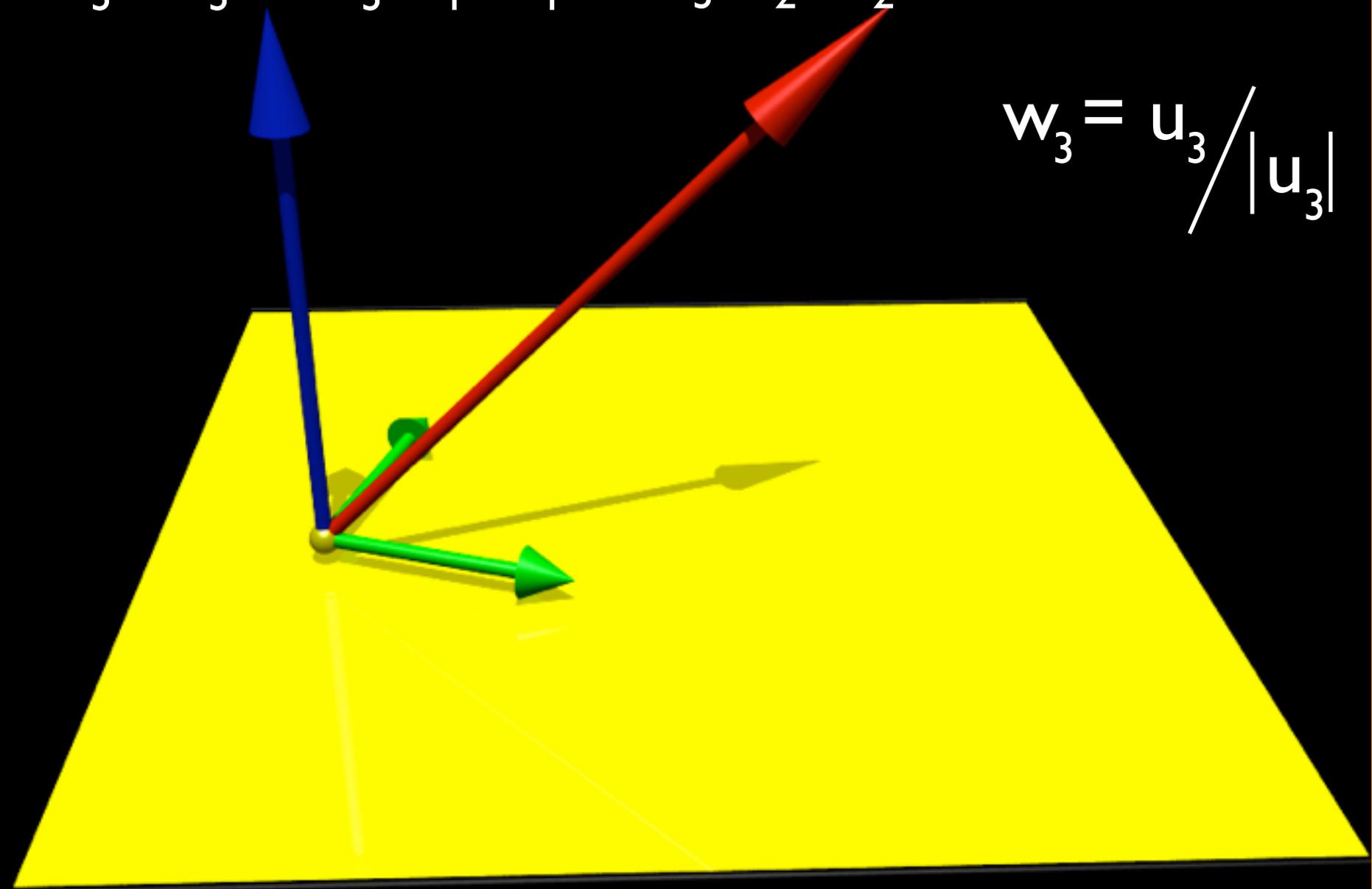
$$\mathbf{w}_2 = \mathbf{u}_2 / |\mathbf{u}_2|$$

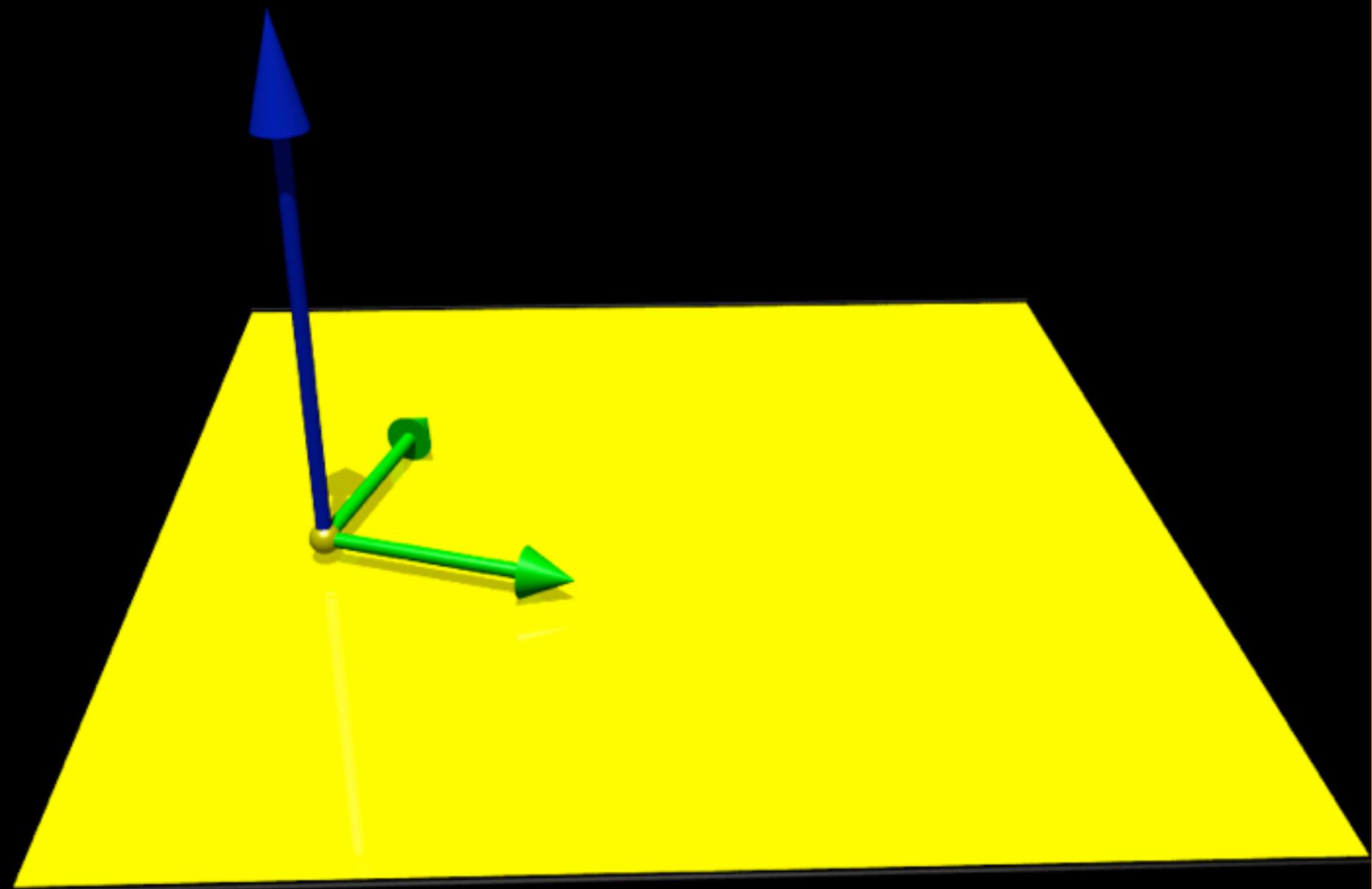


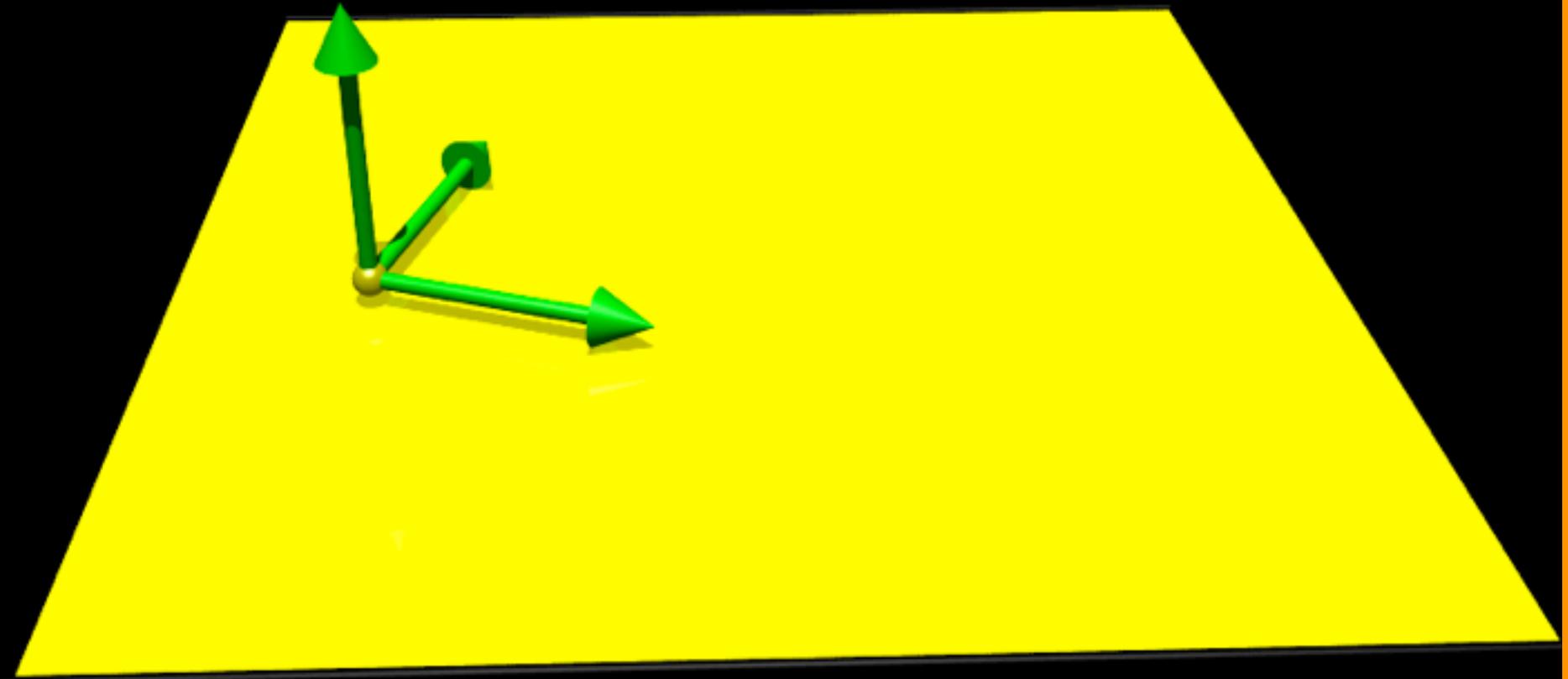


$$\mathbf{u}_3 = \mathbf{v}_3 - (\mathbf{v}_3 \cdot \mathbf{w}_1) \mathbf{w}_1 - (\mathbf{v}_3 \cdot \mathbf{w}_2) \mathbf{w}_2$$

$$\mathbf{w}_3 = \mathbf{u}_3 / |\mathbf{u}_3|$$







$$A = QR$$

$$r_{ii} = |u_i| \quad r_{ij} = (w_i \cdot v_j)$$





blackboard
problem

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$$

Apply Gram-Schmidt to
this basis and do QR
decomposition.

Determinants

$$\det\left(\begin{array}{|c|} \hline a \\ \hline \end{array}\right) = a$$

$$\det\left(\begin{array}{|c|c|} \hline a & b \\ \hline c & d \\ \hline \end{array}\right) = ad - bc$$

$$\det\left(\begin{array}{|c|c|c|} \hline a & b & c \\ \hline d & e & f \\ \hline g & h & i \\ \hline \end{array}\right) =$$

$$+ \begin{array}{|c|c|c|} \hline a & b & c \\ \hline d & e & f \\ \hline g & h & i \\ \hline \end{array} - \begin{array}{|c|c|c|} \hline a & b & c \\ \hline d & e & f \\ \hline g & h & i \\ \hline \end{array}$$

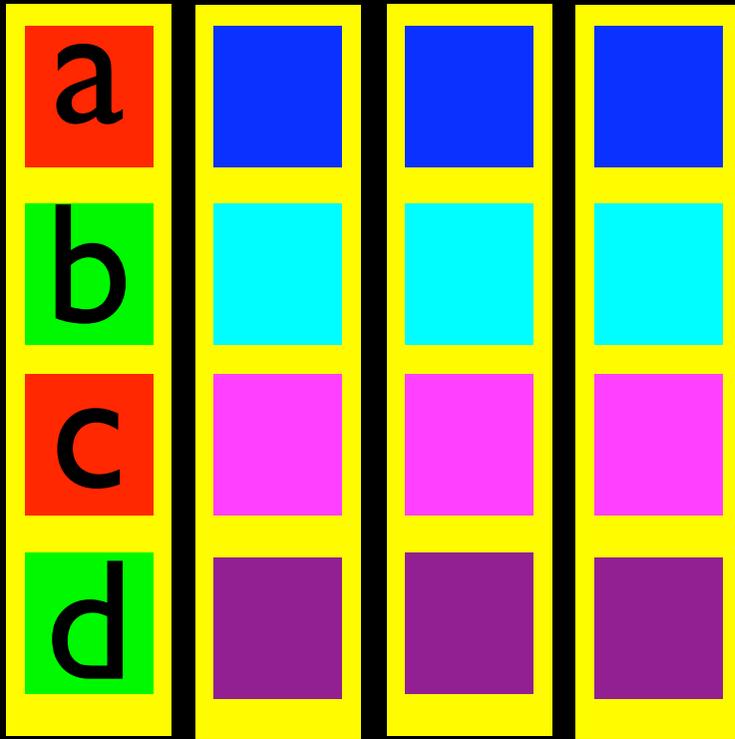
$$aei + bfg + cdh - bdi + ceg + ahf$$

which by the way can be remembered much better
with the following poem:

$$\text{det} \left(\begin{array}{|c|c|c|} \hline a & e & u \\ \hline n & g & l \\ \hline i & o & k \\ \hline \end{array} \right) =$$

gak+onu+lie - alo-ken-gui

det

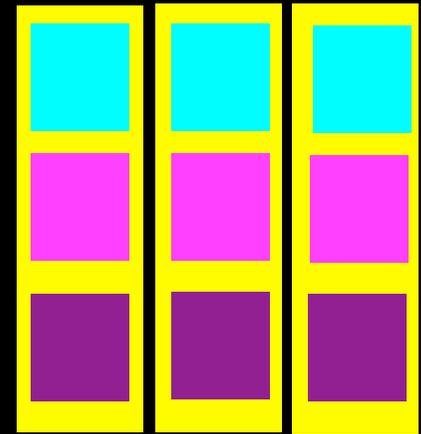


Laplace expansion

=

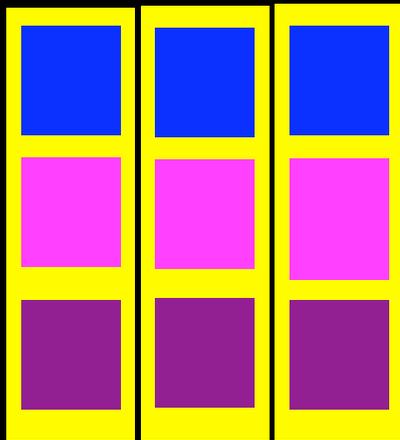
a

det



- b

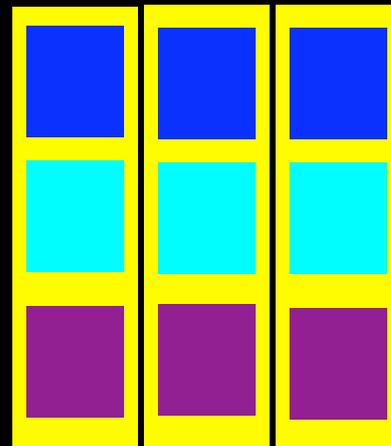
det



+

c

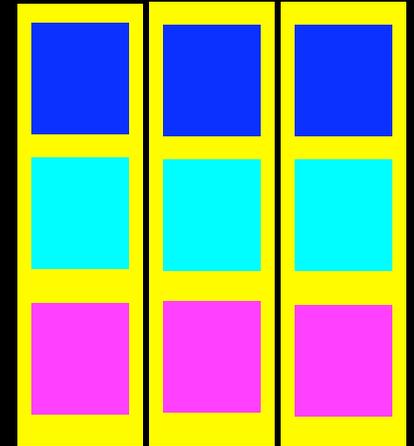
det



-

d

det

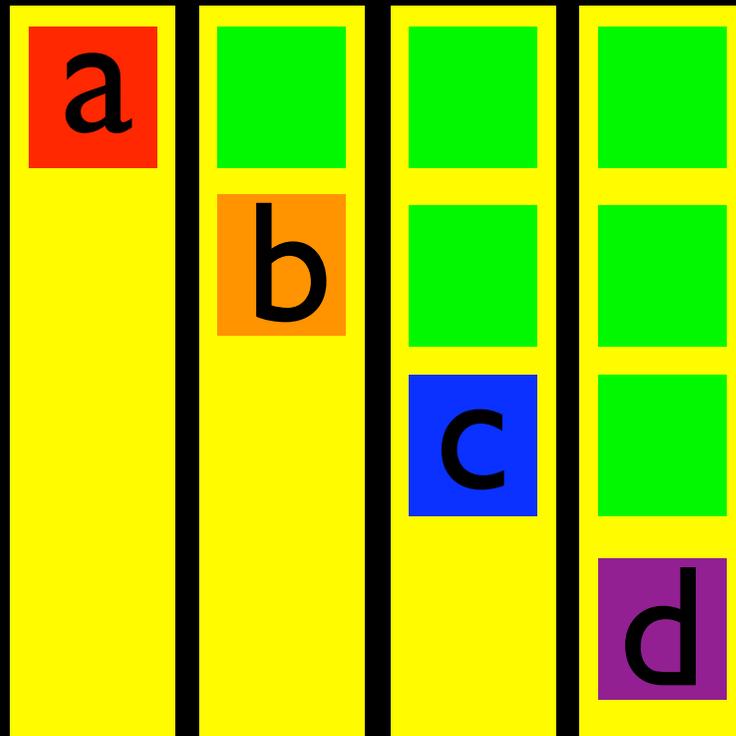


$$\det\left(\begin{array}{cc} \boxed{A} & \boxed{C} \\ \boxed{0} & \boxed{B} \end{array}\right) =$$

$$\det(\boxed{A}) \det(\boxed{B})$$

upper or lower triangular matrices

det

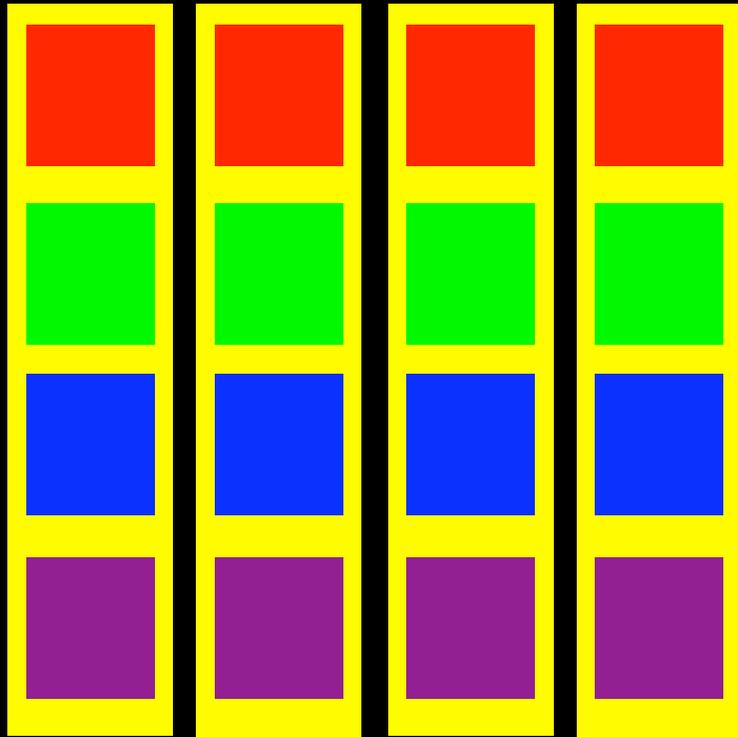


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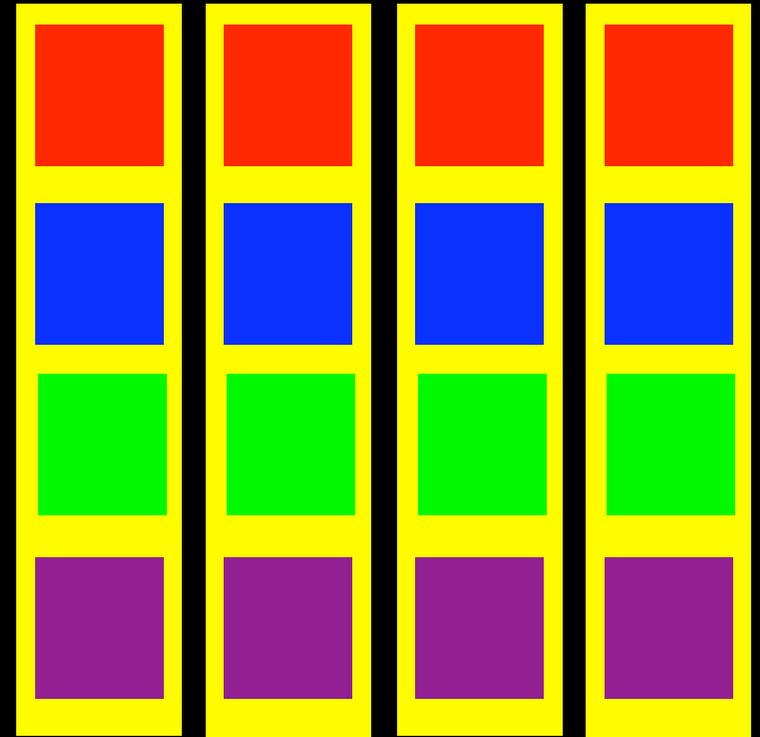


row reduction: swap

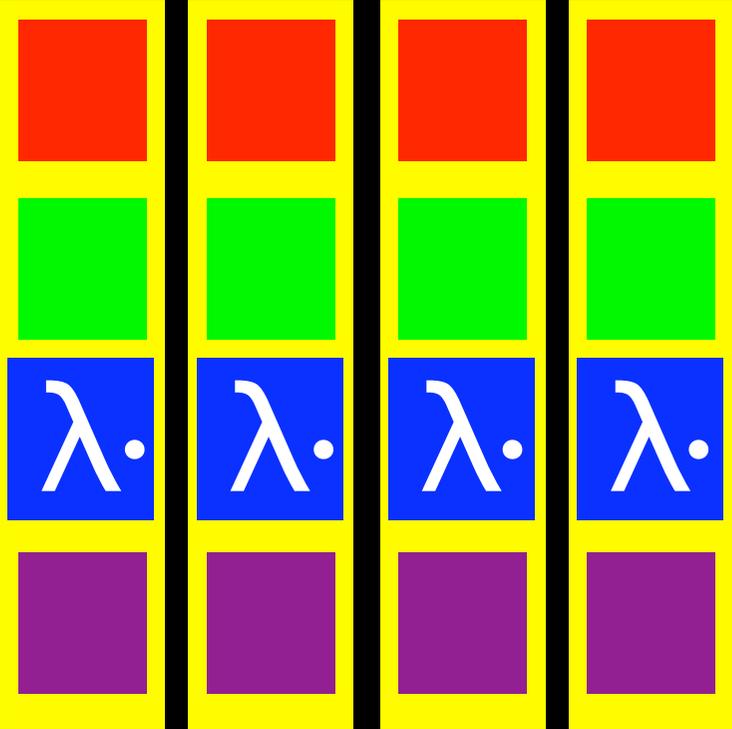
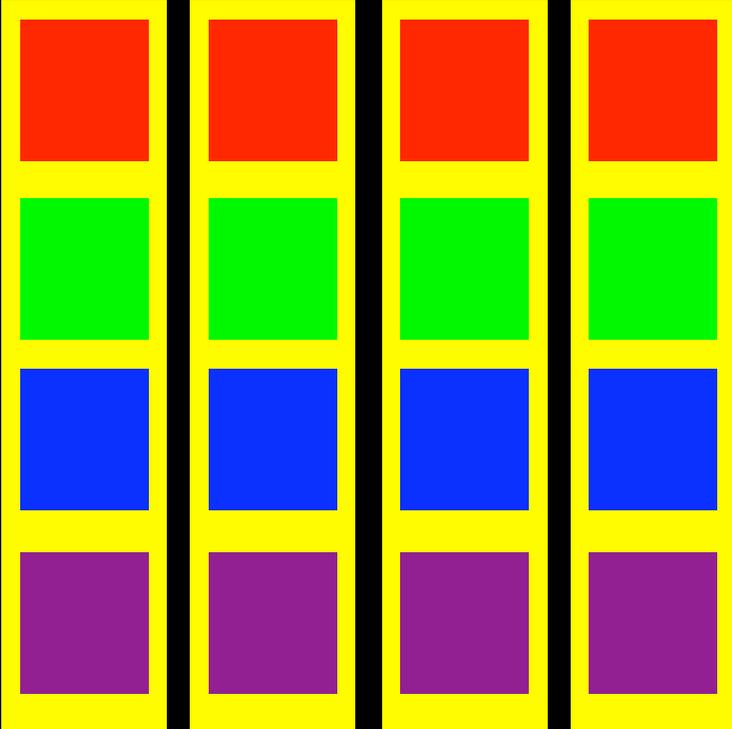
det



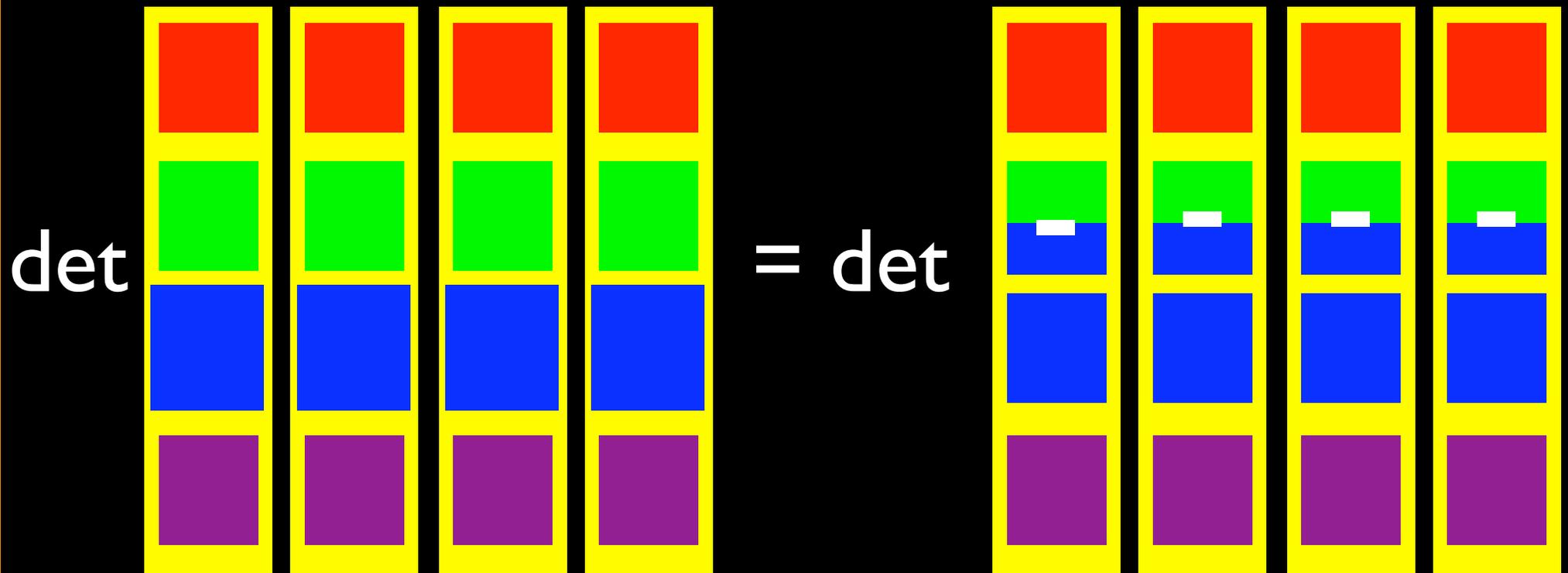
= -det



row reduction: scale

det  = λ det 

row reduction: subtract





*blackboard
problem*

What is the
determinant of

2	0	3	4	5	2
1	2	3	3	4	3
4	0	2	2	3	4
0	0	0	3	1	1
0	0	0	2	2	1
0	0	0	1	2	1



DVD
to win

Its not the famous Monty Python movie:



but a decent Hollywood adaption of the story



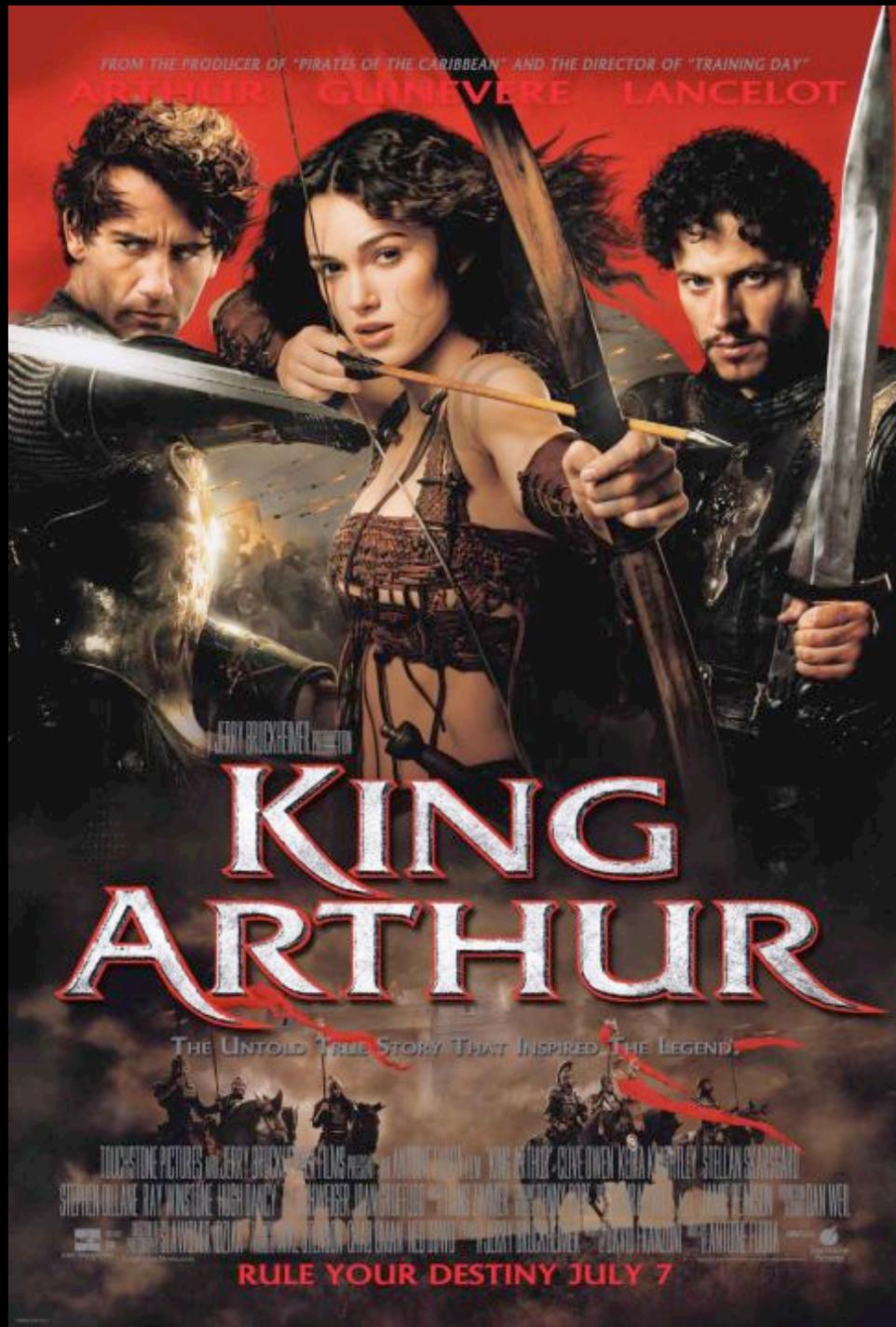
comparison

original
Monty
Python
battle



adaptation
of
Hollywood





ready?
the next slide
gives the
problem

THE PRODUCER OF "PIRATES OF THE CARIBBEAN"



What is the determinant of

2	2	0	0	0	0
3	2	2	0	0	0
4	3	3	2	0	0
4	3	3	3	2	0
3	2	2	2	2	2
2	0	0	0	0	0

PRODUCED BY JERRY BRUCKHEIMER FILMS PRESENTS AN ANTOINE FUQUA FILM KING ARTHUR COLIN DOVON KEIRA KNIGHTLEY STELLAN SKARSGÅRD STEPHEN DILLANE

Complex numbers

$$i = \sqrt{-1}$$

Complex numbers

$$i = \sqrt{-1}$$



Gauss in 1825 : “The true metaphysics of the square root of -1 is elusive”.

Euler Formula

$$\cos(\theta) + i \sin(\theta) = e^{i\theta}$$



Is the gateway to most secrets in complex numbers.

Proof:

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \frac{x^5}{5!} + \dots$$

$$e^{ix} = 1 + \frac{ix}{1!} - \frac{x^2}{2!} - \frac{ix^3}{3!} + \frac{x^4}{4!} + \frac{ix^5}{5!} + \dots$$

$$\cos(x) = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} + \dots$$

$$\sin(x) = \frac{x}{1!} - \frac{x^3}{3!} + \frac{x^5}{5!} + \dots$$

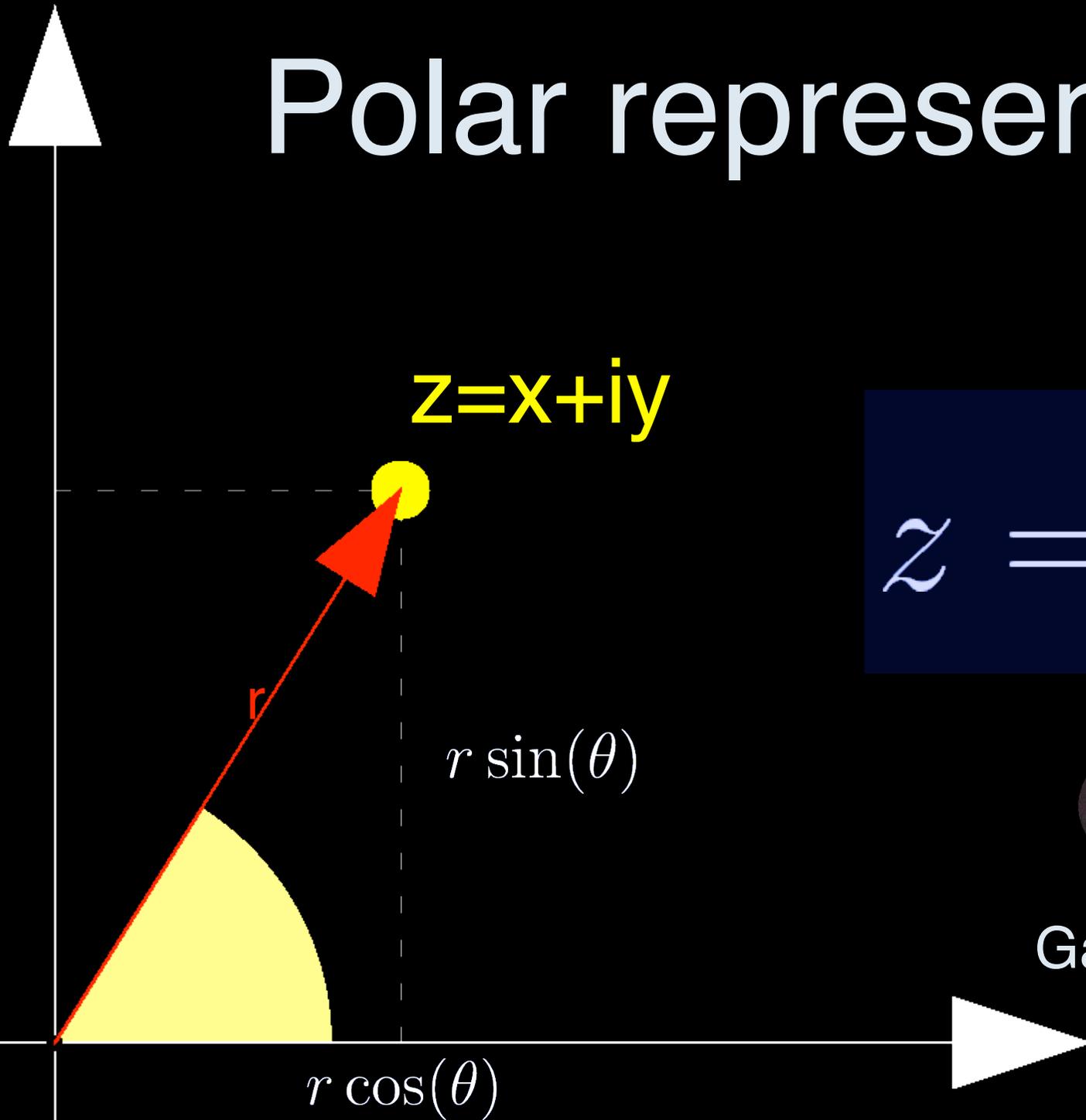
Polar representation

$$z = x + iy$$

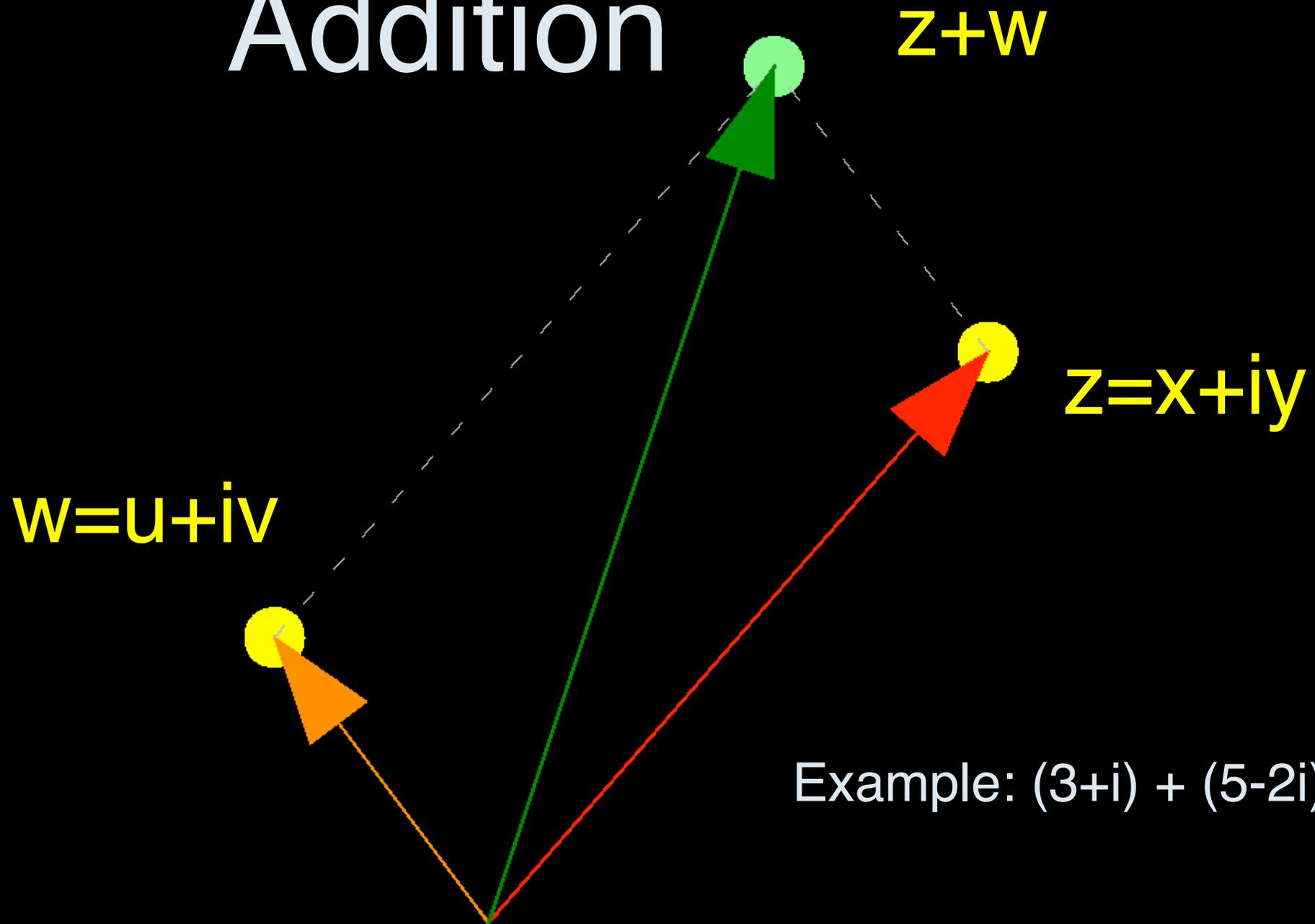
$$z = r e^{i\theta}$$



Gauss Plane

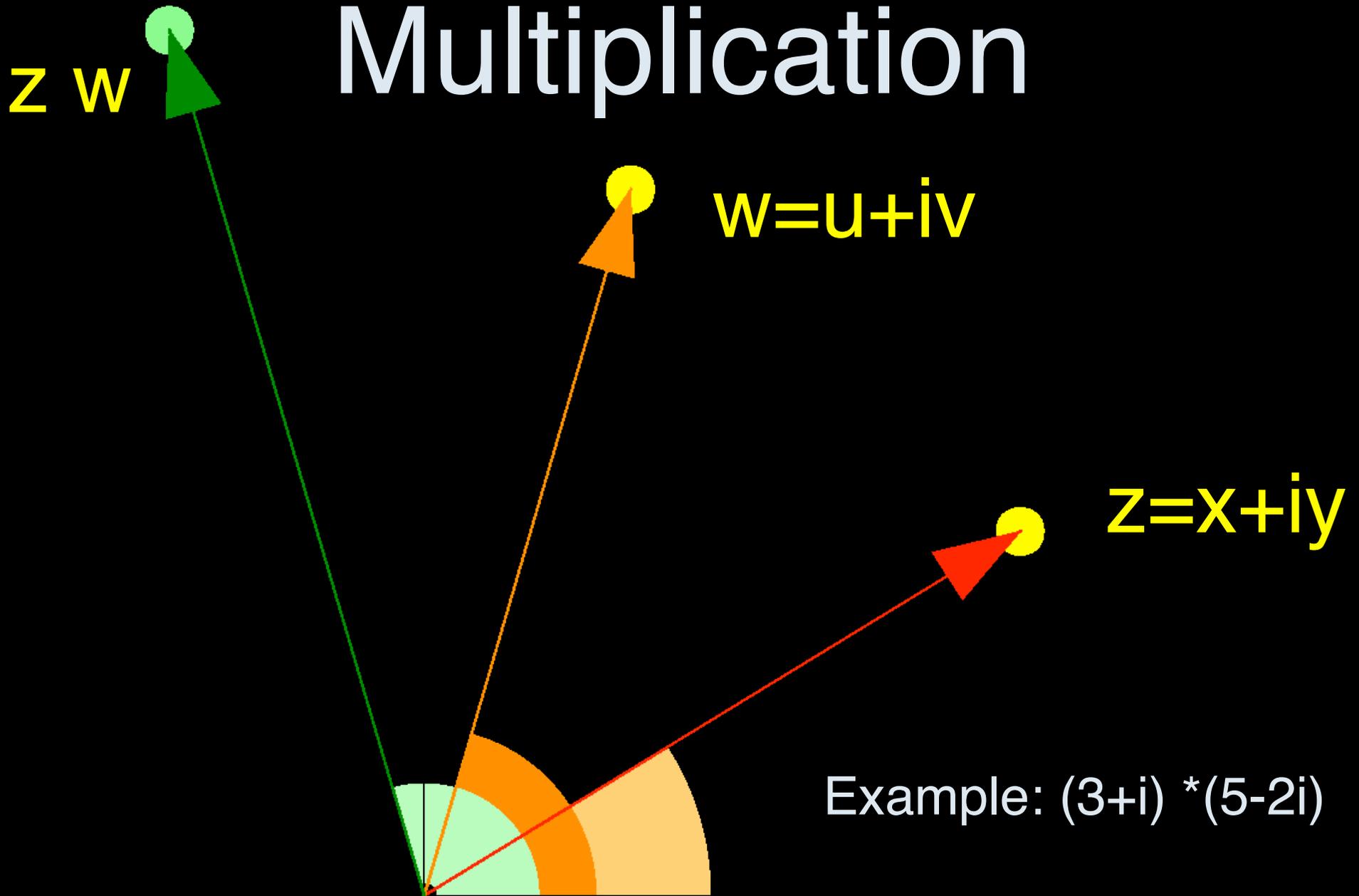


Addition



Example: $(3+i) + (5-2i)$

Multiplication

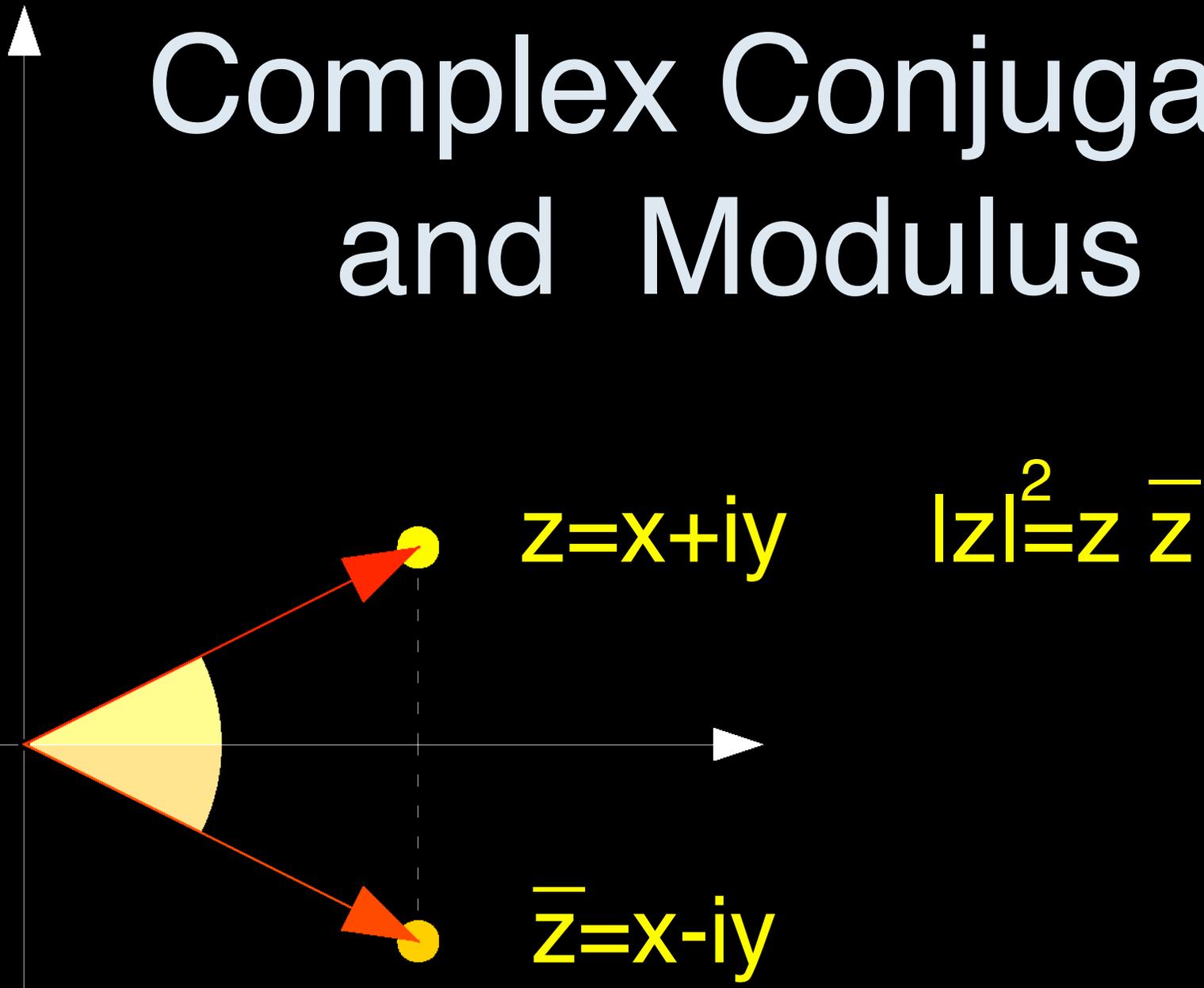


The most remarkable formula in math

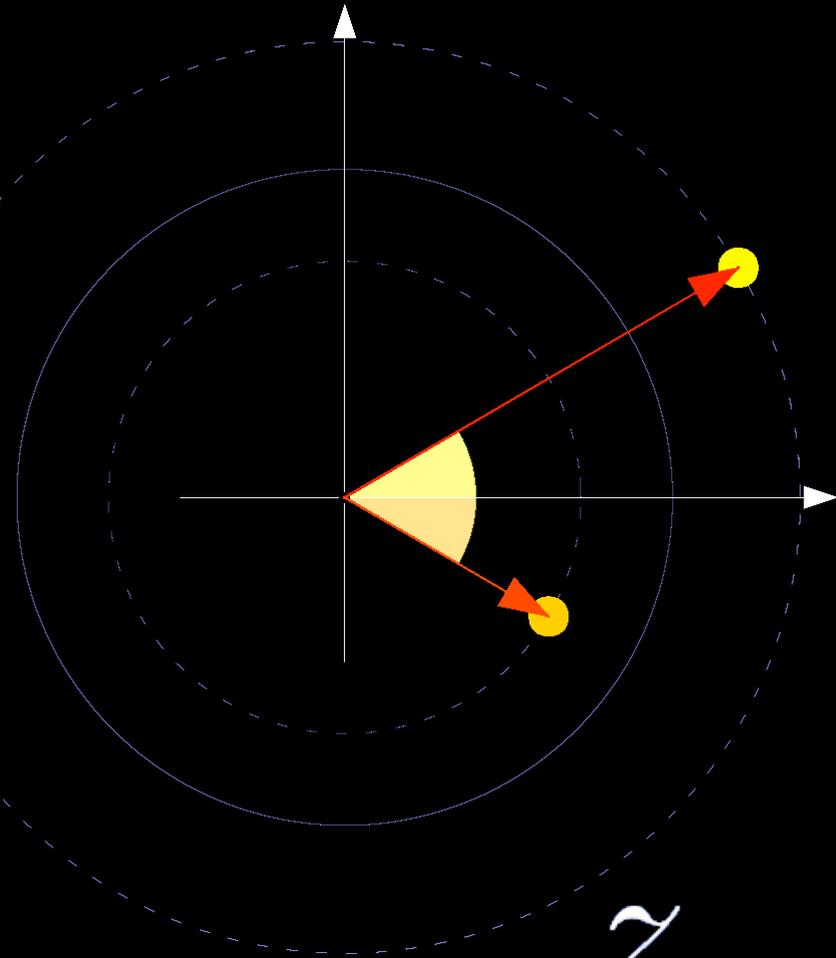


$$1 + e^{i\pi} = 0$$

Complex Conjugate and Modulus

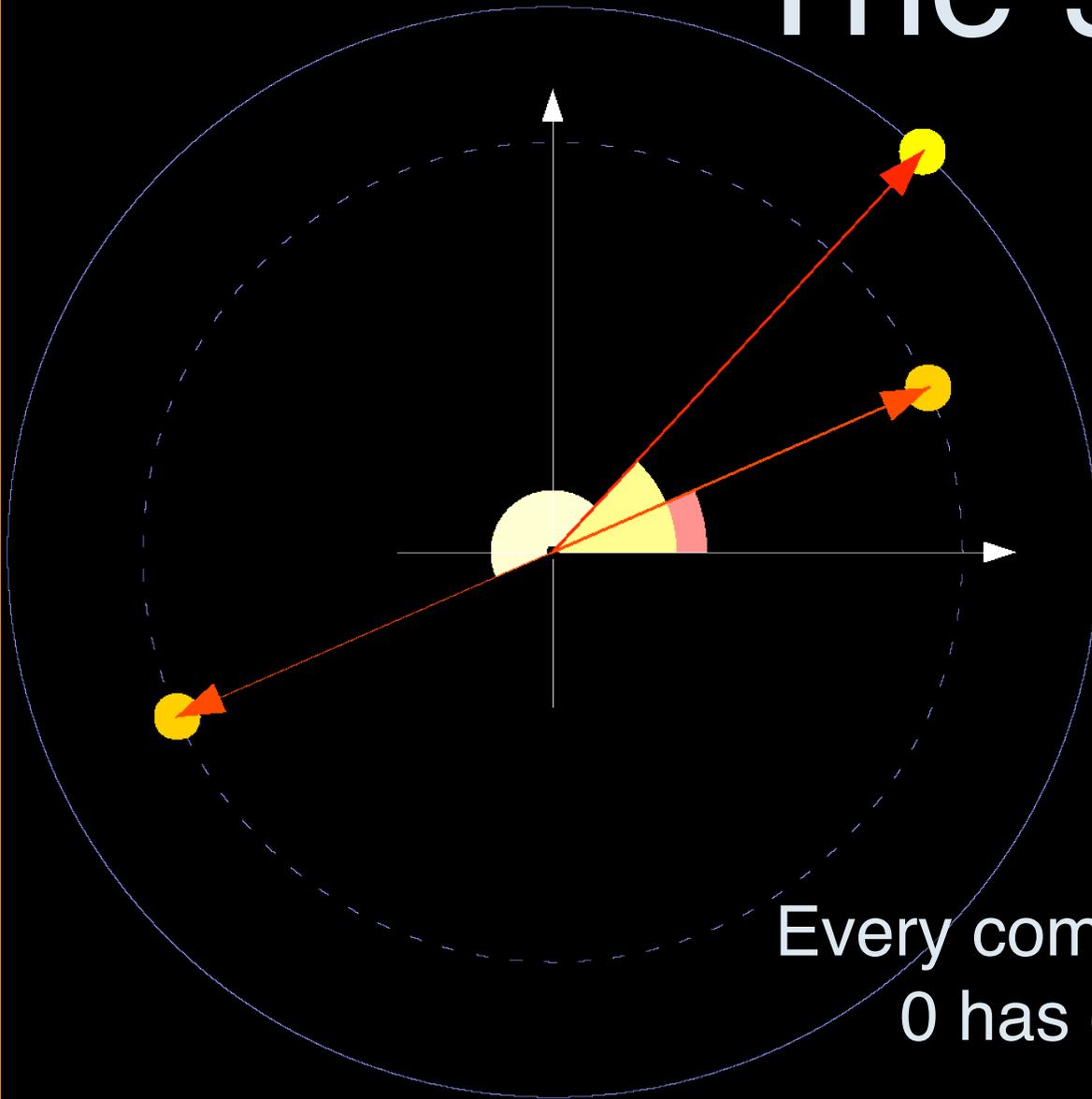


Division



$$\frac{z}{w} = \frac{z\overline{w}}{w\overline{w}} = \frac{z\overline{w}}{|w|^2}$$

The square root



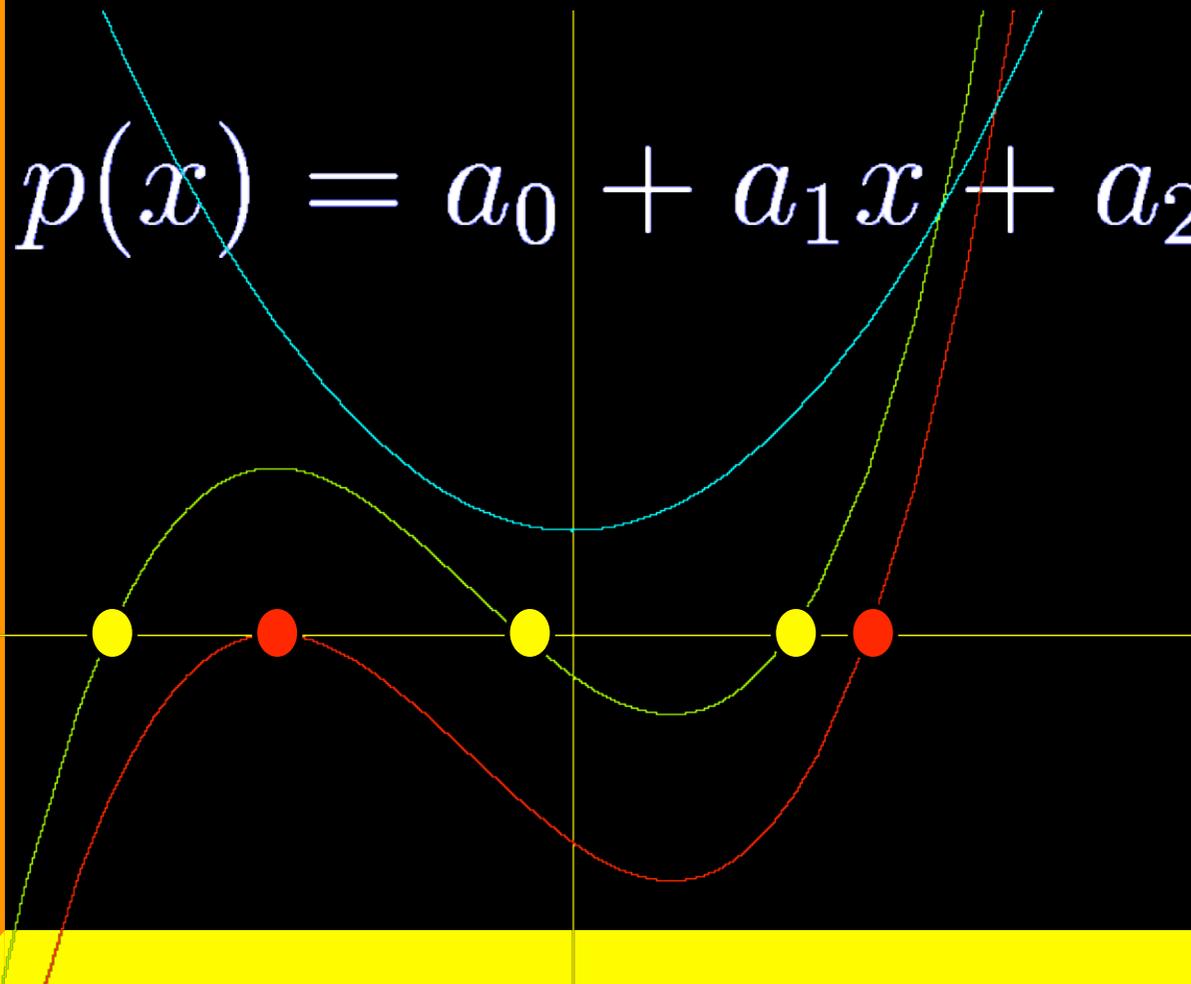
“Take square root of modulus and divide angle by 2”.

Every complex number different from 0 has exactly 2 square roots.

Fundamental theorem of algebra

$$p(x) = a_0 + a_1x + a_2x^2 + \dots + a_nx^n$$

A polynomial of degree n has exactly n roots $p(x) = 0$



Eigenvalues

$$A v = \lambda v$$

Examples:

$$\begin{aligned} A & \\ Q^T Q &= I \\ Q^2 &= I \end{aligned}$$

v is in the kernel

v is in the rotation axes

v is on the reflection space

Because $\det(\lambda - A) = 0$, eigenvalues are the roots of the characteristic polynomial

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad f(\lambda) = \lambda^2 - \text{tr}(A)\lambda + \det(A)$$

$$\lambda_+ = \frac{\text{tr}(A) + \sqrt{\text{tr}(A)^2 - 4\det(A)}}{2}$$

$$\lambda_- = \frac{\text{tr}(A) - \sqrt{\text{tr}(A)^2 - 4\det(A)}}{2}$$

algebraic
multiplicity

number of simultaneous roots

geometric
multiplicity

dimension of $\ker(A-\lambda I)$

a	b
0	a

$$f_A(\lambda) = (\lambda - a)(\lambda - a)$$

algebraic multiplicity: 2

geometric multiplicity: 1

Some good things
to know

determinant

$$\det(A) = \lambda_1 \lambda_2 \dots \lambda_n$$

trace

$$\text{tr}(A) = \lambda_1 + \lambda_2 + \dots + \lambda_n$$

determinant of power

$$\det(A^k) = \lambda_1^k \lambda_2^k \dots \lambda_n^k$$

trace of power

$$\text{tr}(A^k) = \lambda_1^k + \lambda_2^k + \dots + \lambda_n^k$$



*blackboard
problem*

Find the eigenvalues of

$A =$

6	5	5	5	5	5
5	6	5	5	5	5
5	5	6	5	5	5
5	5	5	6	5	5
5	5	5	5	6	5
5	5	5	5	5	6

Eigenvectors

$$Av = \lambda v$$
$$(A - \lambda I)v = 0$$

v is in the
kernel of $A - \lambda I$

The eigenspace is a kernel. If all eigenvalues are different, we have one eigenvector for each eigenvalue.

Example:

$$A =$$

$$\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

$$\lambda_+ = a + ib$$

$$v_+ =$$

$$\begin{bmatrix} i \\ - \end{bmatrix}$$

$$\lambda_- = a - ib$$

$$v_- =$$

$$\begin{bmatrix} -i \\ - \end{bmatrix}$$

All you have to do to
find the eigenvalues is



compute kernels!



*blackboard
problem*

Find all
the
eigenvalues
and
eigenvectors
of

$A =$

2	-3	0	0
3	2	0	0
0	0	5	0
0	0	7	5

Discrete dynamical systems

$$\mathbf{x}(t+1) = A \mathbf{x}(t)$$

has solution:

$$\mathbf{x}(n) = A^n \mathbf{x}(0)$$

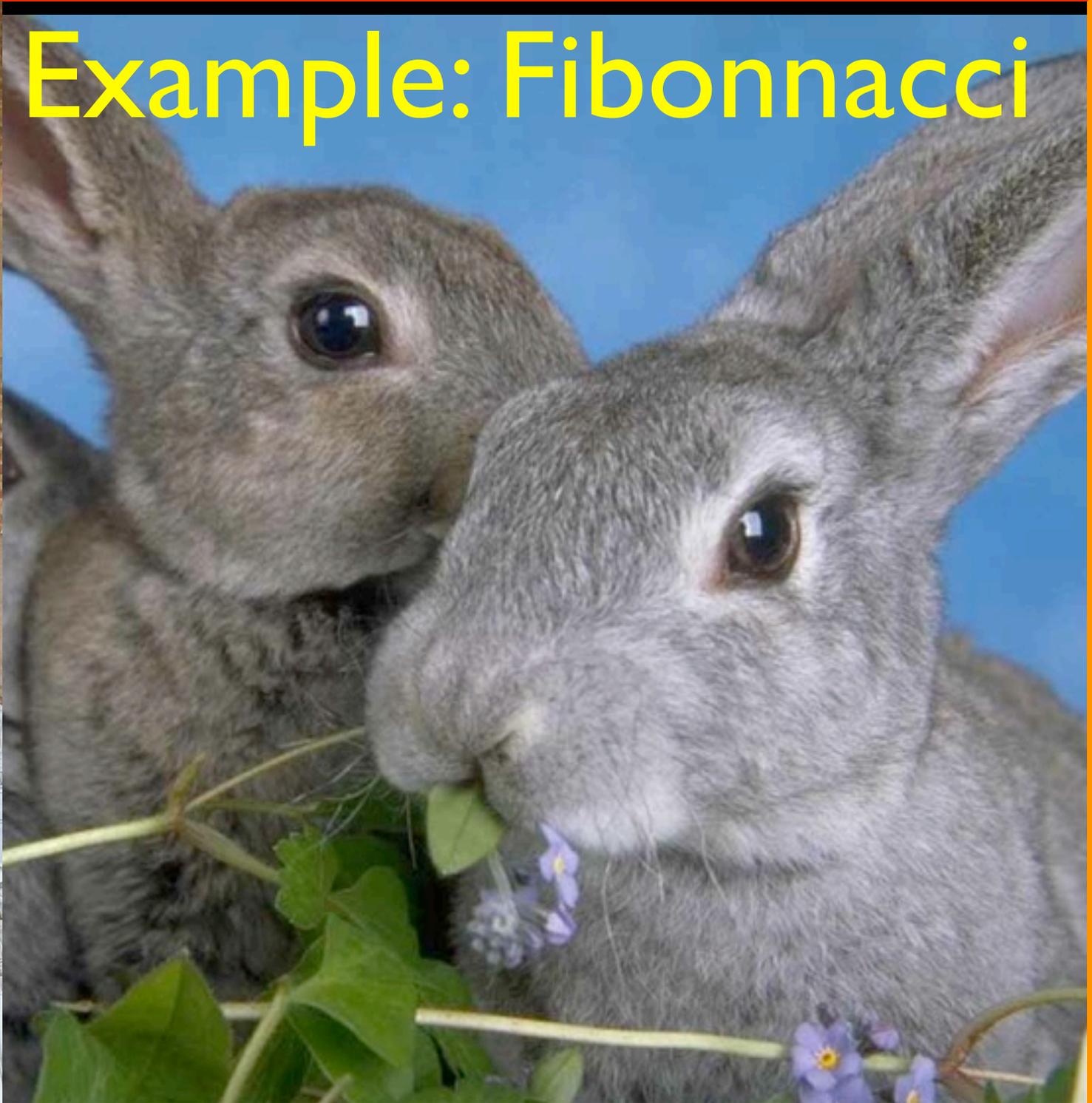
but this does not give any insight.

$$x(0) = a_1 v_1 + \dots + a_n v_n$$

$$A v_k = \lambda_k v_k$$

$$x(t) = a_1 \lambda_1^t v_1 + \dots + a_n \lambda_n^t v_n$$

Example: Fibonacci



$$x(n+1) = x(n) + x(n-1) \quad 1, 1, 2, 3, 5, 8, 13, 21, \dots$$

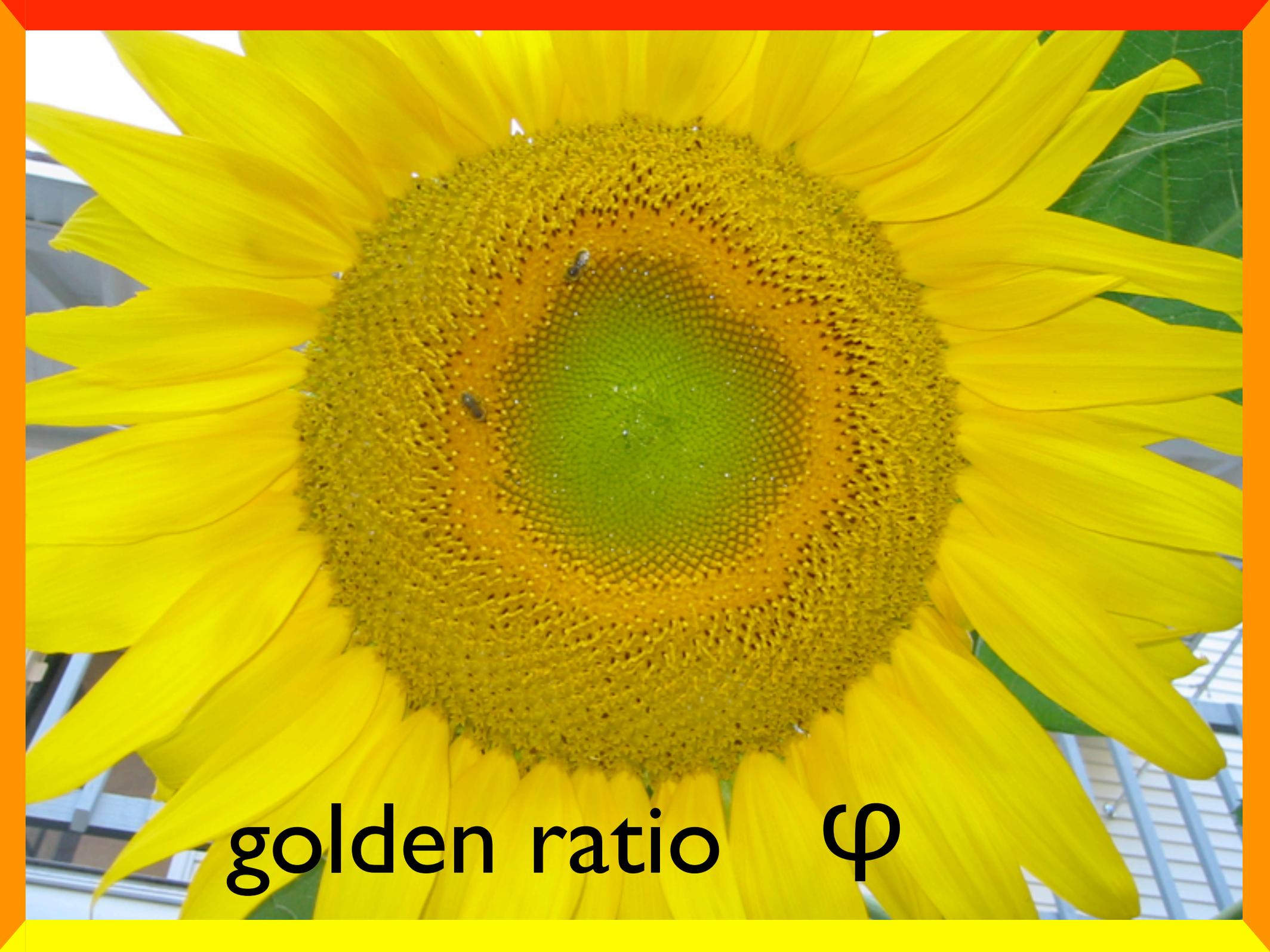
$$\begin{bmatrix} x(n+1) \\ x(n) \end{bmatrix} = \begin{bmatrix} x(n) + x(n-1) \\ x(n) \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x(n) \\ x(n-1) \end{bmatrix}$$

characteristic polynomial: $\lambda^2 - \lambda - 1 = f_A(\lambda)$

eigenvalues = $\varphi, 1/\varphi$ eigenvectors = $\begin{bmatrix} \varphi \\ 1 \end{bmatrix}, \begin{bmatrix} 1/\varphi \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \varphi \\ 1 \end{bmatrix} - \begin{bmatrix} 1/\varphi \\ 1 \end{bmatrix}$$

$$x(n) = (\varphi^n + 1/\varphi^n) / \sqrt{5}$$

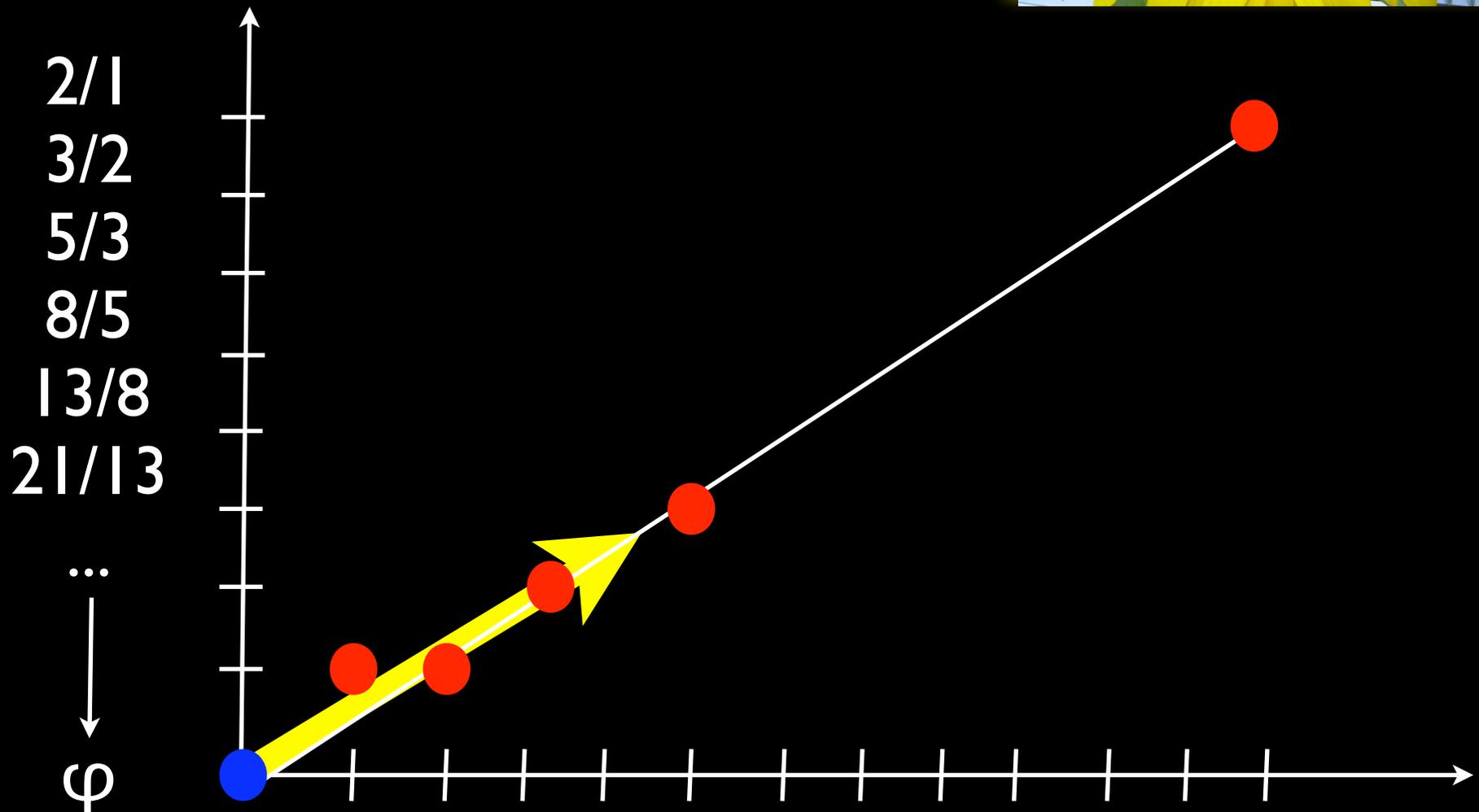


golden ratio φ

golden ratio

$$\varphi = \frac{\sqrt{5} + 1}{2} = 1.616\dots$$

$$1/\varphi = \varphi - 1 = 0.616\dots$$





*blackboard
problem*

The Lilac Bush problem

$$\begin{bmatrix} x_0 \\ y_0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \begin{array}{l} \text{new branches} \\ \text{old branches} \end{array}$$

$$\begin{bmatrix} x_{n+1} \\ y_{n+1} \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_n \\ y_n \end{bmatrix}$$



$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$



$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$



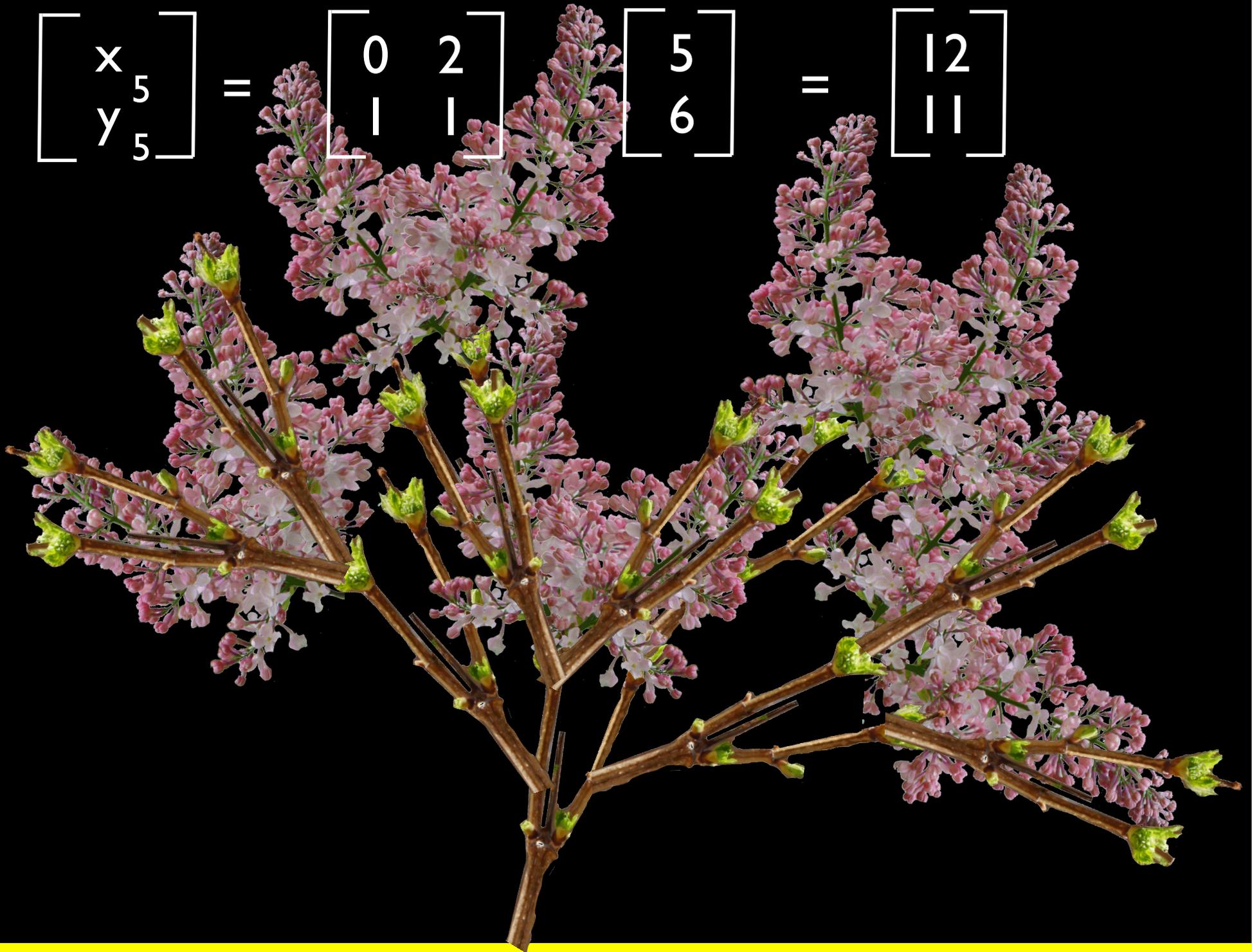
$$\begin{bmatrix} x_3 \\ y_3 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$



$$\begin{bmatrix} x_4 \\ y_4 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 5 \end{bmatrix}$$



$$\begin{bmatrix} x_5 \\ y_5 \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 6 \end{bmatrix} = \begin{bmatrix} 12 \\ 11 \end{bmatrix}$$



Questions?