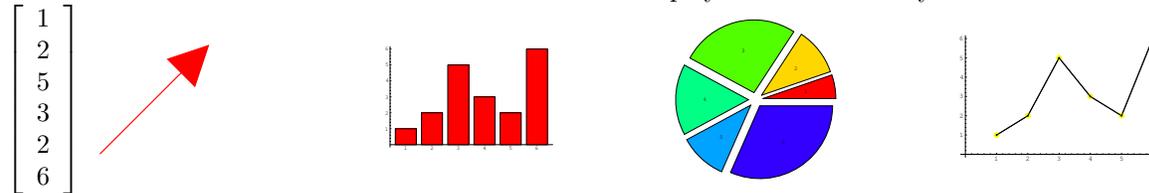


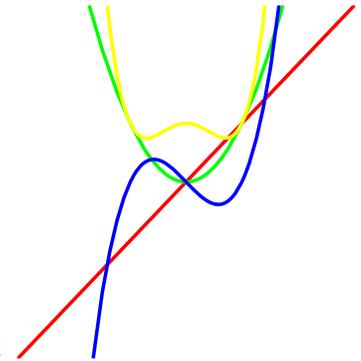
FROM VECTORS TO FUNCTIONS. Vectors can be displayed in different ways:



Listing the (i, \vec{v}_i) can also be interpreted as the graph of a **function** $f : 1, 2, 3, 4, 5, 6 \rightarrow \mathbf{R}$, where $f(i) = \vec{v}_i$.

LINEAR SPACES. A space X in which we can add, scalar multiplications and where basic laws like commutativity, distributivity and associativity hold is called a **linear space**. Examples:

- Lines, planes and more generally, the n -dimensional Euclidean space.
- P_n , the space of all polynomials of degree n .
- The space P of all polynomials.
- C^∞ , the space of all smooth functions on the line
- C^0 , the space of all continuous functions on the line.
- C^1 , the space of all differentiable functions on the line.
- $C^\infty(\mathbf{R}^3)$ the space of all smooth functions in space.
- L^2 the space of all functions on the line for which f^2 is integrable and $\int_{-\infty}^{\infty} f^2(x) dx < \infty$.



In all these function spaces, the function $f(x) = 0$ which is constantly 0 is the zero function.

WHICH OF THE FOLLOWING ARE LINEAR SPACES?



The space X of all polynomials of the form $f(x) = ax^3 + bx^4 + cx^5$



The space X of all continuous functions on the unit interval $[-1, 1]$ which vanish at -1 and 1 . It contains for example $f(x) = x^2 - |x|$.



The space X of all smooth periodic functions $f(x+1) = f(x)$. Example $f(x) = \sin(2\pi x) + \cos(6\pi x)$.



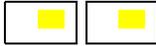
The space $X = \sin(x) + C^\infty(\mathbf{R})$ of all smooth functions $f(x) = \sin(x) + g$, where g is a smooth function.



The space X of all trigonometric polynomials $f(x) = a_0 + a_1 \sin(x) + a_2 \sin(2x) + \dots + a_n \sin(nx)$.



The space X of all smooth functions on \mathbf{R} which satisfy $f(1) = 1$. It contains for example $f(x) = 1 + \sin(x) + x$.



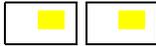
The space X of all continuous functions on \mathbf{R} which satisfy $f(2) = 0$ and $f(10) = 0$.



The space X of all smooth functions on \mathbf{R} which satisfy $\lim_{|x| \rightarrow \infty} f(x) = 0$.



The space X of all continuous functions on \mathbf{R} which satisfy $\lim_{|x| \rightarrow \infty} f(x) = 1$.



The space X of all smooth functions on \mathbf{R} of compact support: for every f , there exists an interval I such that $f(x) = 0$ outside that interval.

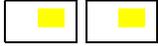


The space X of all smooth functions on \mathbf{R}^2 .

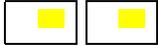
LINEAR TRANSFORMATIONS. A map T between linear spaces is called **linear** if $T(x + y) = T(x) + T(y), T(\lambda x) = \lambda T(x), T(0) = 0$. Examples:

- $Df(x) = f'(x)$ on C^∞
- $Tf(x) = \int_0^x f(x) dx$ on C^0
- $Tf(x) = (f(0), f(1), f(2), f(3))$ on C^∞ .
- $Tf(x) = \sin(x)f(x)$ on C^∞
- $Tf(x) = (\int_0^1 f(x)g(x) dx)g(x)$ on $C^0[0, 1]$.

WHICH OF THE FOLLOWING MAPS ARE LINEAR TRANSFORMATIONS?



The map $T(f) = f'(x)$ on $X = C^\infty(\mathbf{T})$.



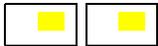
The map $T(f) = 1 + f'(x)$ on $X = C^\infty(\mathbf{R})$.



The map $T(f)(x) = \sin(x)f(x)$ on $X = C^\infty(\mathbf{R})$.



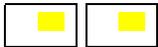
The map $T(f)(x) = f(x)/x$ on $X = C^\infty(\mathbf{R})$.



The map $T(f)(x) = \int_0^x f(x) dx$ on $X = C([0, 1])$.



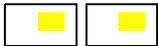
The map $T(f)(x) = f(x + \sqrt{2})$ on $X = C^\infty(\mathbf{R})$.



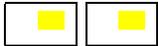
The map $T(f)(x) = \int_\infty^\infty f(x - s) \sin(s) ds$ on C^0 .



The map $T(f)(x) = f'(x) + f(2)$ on $C^\infty(\mathbf{R})$.



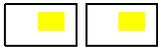
The map $T(f)(x) = f''(x) + f(2) + 1$ on $C^\infty(\mathbf{R})$.



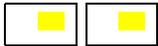
The map $T(f)(x, y, z) = f_{xx}(x, y, z) + f_{yy}(x, y, z) + f_{zz}(x, y, z) + 1/(|x|)f(x, y, z)$



The map $T(f)(x) = f(x^2)$.



The map $T(f)(x) = f''(x) - x^2 f(x)$.



The map $T(f)(x) = f^2(x)$ on $C^\infty(\mathbf{R})$.

EIGENVALUES, BASIS, KERNEL, IMAGE. Many concepts work also here.

X linear space	$f, g \in X, f + g \in X, \lambda f \in X, 0 \in X$.
T linear transformation	$T(f + g) = T(f) + T(g), T(\lambda f) = \lambda T(f), T(0) = 0$.
f_1, f_2, \dots, f_n linear independent	$\sum_i c_i f_i = 0$ implies $f_i = 0$.
f_1, f_2, \dots, f_n span X	Every f is of the form $\sum_i c_i f_i$.
f_1, f_2, \dots, f_n basis of X	linear independent and span.
T has eigenvalue λ	$Tf = \lambda f$
kernel of T	$\{Tf = 0\}$
image of T	$\{Tf f \in X\}$.

Some concepts do not work without modification. Example: $\det(T)$ or $\text{tr}(T)$ are not always defined for linear transformations in infinite dimensions. The concept of a basis in infinite dimensions has to be defined properly.

INNER PRODUCT. The analogue of the dot product $\sum_i f_i g_i$ for vectors $(f_1, f_2, \dots, f_n), (g_1, g_2, \dots, g_n)$ is the integral $\int_0^1 f(x)g(x) dx$ for functions on the interval $[0, 1]$. One writes (f, g) and $\|f\| = \sqrt{(f, f)}$. This inner product is defined on L^2 or $C^\infty([0, 1])$. Example: $(x^3, x^2) = \int_0^1 x^5 dx = 1/5$. Having an inner product allows to define "length", "angle" in infinite dimensions. One can use it to define projections, Gram-Schmidt orthogonalization etc.