

PROBABILITY THEORY

MATH 154

Unit 23: Conditional Expectation

23.1. Conditional probability $P[A|B]$ for events leads to **conditional expectation** for σ algebras: it is denoted $E[X|\mathcal{B}]$ if $\mathcal{B} \subset \mathcal{A}$ is a sub- σ -algebra.

Theorem 1 (Kolmogorov). *Given $X \in \mathcal{L}^1(\Omega, \mathcal{A}, P)$ and a sub σ -algebra $\mathcal{B} \subset \mathcal{A}$. There exists a random variable $Y \in \mathcal{L}^1(\Omega, \mathcal{B}, P)$ denoted $E[X|\mathcal{B}]$ satisfying $\int_A Y dP = \int_A X dP$ for all $A \in \mathcal{B}$. We call it $E[X|\mathcal{B}]$*

Proof. For $X = \sum_i a_i 1_{A_i} \in \mathcal{S}$ define $E[X; A] = \sum_i a_i 1_{A_i \cap A} / P[A]$. For $X \in \mathcal{L}^1$ define $E[X; A]$ as a limit. We also write $\int_A X dP$ for this conditional integration. Define the two measures $\tilde{P}[A] = P[A]$ and $P'[A] = \int_A X dP = E[X; A]$ on the measure space (Ω, \mathcal{B}) . Given a set $B \in \mathcal{B}$ with $\tilde{P}[B] = 0$, then $P'[B] = 0$ so that P' is absolutely continuous with respect to \tilde{P} . The **Radon-Nykodym** theorem from real analysis gives a random variable $Y \in \mathcal{L}^1(\mathcal{B})$ with $P'[A] = \int_A Y dP = \int_A X dP$. \square

23.2. Examples:

- if $\mathcal{B} = \{\emptyset, \Omega\}$, then $E[X|\mathcal{B}] = E[X]$.
- if $\mathcal{B} = \{\emptyset, \Omega, B, B^c\}$ then $E[X|\mathcal{B}]$ takes the value $\int_B X dP / P[B]$ on B and the value $\int_{B^c} X dP / P[B^c]$ on B^c .
- if $\mathcal{B} = \mathcal{A}$, then $E[X|\mathcal{B}] = X$.
- if $\mathcal{B} = \mathcal{A}_X$ is the σ algebra generated by X , then $E[X|\mathcal{B}] = X$.
- if $X(x, y)$ is a continuous function on the unit square $\Omega = [0, 1]^2$ with $P = dx dy$ as a probability measure and where $Y(x, y) = x$. In that case, $E[X|Y]$ is a function of x alone, given by $E[X|Y](x) = \int_0^1 f(x, y) dy$. It is called a **conditional integral**.

23.3. The map $X \in \mathcal{L}^1(\Omega, \mathcal{A}, P) \rightarrow E[X, \mathcal{B}] \in \mathcal{L}^1(\Omega, \mathcal{B}, P)$ is a **projection**. To see this geometrically, we work in the Hilbert space \mathcal{L}^2 :

Theorem 2. *Conditional expectation $X \mapsto E[X|\mathcal{B}]$ is the projection $\mathcal{L}^2(\mathcal{A}) \rightarrow \mathcal{L}^2(\mathcal{B})$.*

Proof. The space $\mathcal{L}^2(\mathcal{B})$ of square integrable \mathcal{B} -measurable functions is a linear subspace of $\mathcal{L}^2(\mathcal{A})$. When identifying functions which agree almost everywhere, then $\mathcal{L}^2(\mathcal{B})$ is a Hilbert space which is a linear subspace of the Hilbert space $\mathcal{L}^2(\mathcal{A})$. For any $X \in \mathcal{L}^2(\mathcal{A})$, there exists a unique projection $p(X) \in \mathcal{L}^2(\mathcal{B})$. The orthogonal complement $\mathcal{L}^2(\mathcal{B})^\perp$ is defined as

$$\mathcal{L}^2(\mathcal{B})^\perp = \{Z \in \mathcal{L}^2(\mathcal{A}) \mid (Z, Y) := E[Z \cdot Y] = 0 \text{ for all } Y \in \mathcal{L}^2(\mathcal{B})\} .$$

By the definition of the conditional expectation, we have for $A \in \mathcal{B}$

$$(X - E[X|\mathcal{B}], 1_A) = E[X - E[X|\mathcal{B}]; A] = 0 .$$

Therefore $X - E[X|\mathcal{B}] \in \mathcal{L}^2(\mathcal{B})^\perp$. Because the map $q(X) = E[X|\mathcal{B}]$ satisfies $q^2 = q$, it is linear and has the property that $(1 - q)(X)$ is perpendicular to $\mathcal{L}^2(\mathcal{B})$, the map q is a projection which must agree with p . \square

Theorem 3 (Properties). *For all $X, X_n, Y \in \mathcal{L}^1$:*

- (1) *Linearity: The map $X \mapsto E[X|\mathcal{B}]$ is linear.*
- (2) *Positivity: $X \geq 0 \Rightarrow E[X|\mathcal{B}] \geq 0$.*
- (3) *Tower property: $\mathcal{C} \subset \mathcal{B} \subset \mathcal{A} \Rightarrow E[E[X|\mathcal{B}]|\mathcal{C}] = E[X|\mathcal{C}]$.*
- (4) *Cond. Fatou: $|X_n| \leq X, E[\liminf_{n \rightarrow \infty} X_n|\mathcal{B}] \leq \liminf_{n \rightarrow \infty} E[X_n|\mathcal{B}]$.*
- (5) *Cond. dominated convergence: $|X_n| \leq X, X_n \rightarrow X$ a.e. $\Rightarrow E[X_n|\mathcal{B}] \rightarrow E[X|\mathcal{B}]$ a.e.*
- (6) *Cond. Jensen: if h is convex, then $E[h(X)|\mathcal{B}] \geq h(E[X|\mathcal{B}])$.*
- (7) *Especially $\|E[X|\mathcal{B}]\|_p \leq \|X\|_p$.*
- (9) *Extracting knowledge: For $Z \in \mathcal{L}^\infty(\mathcal{B})$, one has $E[ZX|\mathcal{B}] = ZE[X|\mathcal{B}]$.*
- (9) *Independence: if X is independent of \mathcal{C} , then $E[X|\mathcal{C}] = E[X]$.*

Proof. (1) The conditional expectation is a projection by the previous theorem so linear.

(2) If $Y = E[X|\mathcal{B}]$ would be negative on a set of positive measure, then $A = Y^{-1}((-\infty, -1/n]) \in \mathcal{B}$ would have positive probability for some n . This would lead to the contradiction $0 \leq E[1_A X] = E[1_A Y] \leq -n^{-1}m(A) < 0$.

(3) Use that $P'' \ll P' \ll P$ implies $P'' = Y'P' = Y'YP$ and $P'' \ll P$ gives $P'' = ZP$ so that $Z = Y'Y$ almost everywhere.

This is especially useful when applied to the algebra $\mathcal{C}_Y = \{\emptyset, Y, Y^c, \Omega\}$. Because $X \leq Y$ almost everywhere if and only if $E[X|\mathcal{C}_Y] \leq E[Y|\mathcal{C}_Y]$ for all $Y \in \mathcal{B}$.

(4)-(5) The conditional versions of the Fatou lemma or the dominated convergence theorem are true, if they are true conditioned with \mathcal{C}_Y for each $Y \in \mathcal{B}$. The tower property reduces these statements to versions with $\mathcal{B} = \mathcal{C}_Y$ which are then on each of the sets Y, Y^c the usual theorems.

(6) Chose a sequence $(a_n, b_n) \in \mathbb{R}^2$ such that $h(x) = \sup_n a_n x + b_n$ for all $x \in \mathbb{R}$. We get from $h(X) \geq a_n X + b_n$ that almost surely $E[h(X)|\mathcal{G}] \geq a_n E[X|\mathcal{G}] + b_n$. These inequalities hold therefore simultaneously for all n and we obtain almost surely

$$E[h(X)|\mathcal{G}] \geq \sup_n (a_n E[X|\mathcal{G}] + b_n) = h(E[X|\mathcal{G}]) .$$

(7) This is a special case of (6) using $h(x) = |x|^p$.

(8) It is enough to condition it to each algebra \mathcal{C}_Y for $Y \in \mathcal{B}$. The tower property reduces these statements to linearity.

(9) By linearity, we can assume $X \geq 0$. For $B \in \mathcal{B}$ and $C \in \mathcal{C}$, the random variables $X1_B$ and 1_C are independent so that $E[X1_{B \cap C}] = E[X1_B 1_C] = E[X1_B]P[C]$. The random variable $Y = E[X|\mathcal{B}]$ is \mathcal{B} measurable and because $Y1_B$ is independent of \mathcal{C} we get $E[(Y1_B)1_C] = E[Y1_B]P[C]$ so that $E[1_{B \cap C} X] = E[1_{B \cap C} Y]$. The measures on $\sigma(\mathcal{B}, \mathcal{C})$

$$\mu : A \mapsto E[1_A X], \nu : A \mapsto E[1_A Y]$$

agree therefore on the π -system of the form $B \cap C$ with $B \in \mathcal{B}$ and $C \in \mathcal{C}$ and consequently everywhere on $\sigma(\mathcal{B}, \mathcal{C})$. \square