

# PROBABILITY THEORY

MATH 154

## Unit 22: Markov Chains

**22.1.** A discrete time **Markov process** is a stochastic process  $X_i$  such that the outcome of  $X_{n+1}$  given the past only depends on  $X_n$  for every  $n$ . This can be rephrased also in Martingale language. For now we look at an important simple case, where the random variables  $X_i$  take only finitely many values  $S$ , the set of **states**. A **Markov chain** is a stochastic process with values in  $S$  such that the conditional probability  $P[X_{n+1} = x_{n+1} | X_1 = x_1, \dots, X_n = x_n]$  is  $P[X_{n+1} = x_{n+1} | X_n = x_n]$ . If the probabilities  $P[X_{n+1} = a | P[X_n = b]$  are independent of  $n$ , we talk about a **time homogeneous Markov chain**.

**22.2.** It follows from the definition of a Markov process that  $X_n$  satisfies the **elementary Markov property**: for  $n > k$ ,

$$P[X_n \in B | X_1, \dots, X_k] = P[X_n \in B | X_k].$$

This means that the probability distribution of  $X_n$  is determined by knowing the probability distribution of  $X_{n-1}$ . The future depends only on the present and not on the past. In the time homogeneous case, the stochastic process defines a transformation  $T$  on a probability space  $(S^{\mathbb{N}}, \mathcal{A} = \mathcal{B}^{\mathbb{N}})$ , where  $\mathcal{B}$  is the set of all subsets of  $S$ . As we will see, there are often measures  $\pi$  on  $S$  such that  $P = \pi^{\mathbb{N}}$  is invariant. We want to understand such equilibria.

**22.3.** We now look at a homogeneous Markov chain on a finite state space  $S$  with  $s$  elements. Probability measures on  $S$  are vectors  $p$  with entries  $p_i \geq 0$  such that  $\sum_i p_i = 1$ . The Markov chain is now determined by the left stochastic  $s \times s$  matrix  $M_{ij} = P[X_{n+1} = j | X_n = x_i]$ .<sup>1</sup> The matrix  $M^T$  has the eigenvalue 1 with eigenvector  $[1, \dots, 1]$ . Therefore,  $M$  has also an eigenvalues 1. Its eigenvector is a **stationary measure** describing a stable probability distribution. As Oskar Perron in 1907 and Georg Frobenius in 1908 have shown there is one if  $M$  has positive entries:

**Theorem 1** (Perron-Frobenius). *If all entries of a left stochastic  $n \times n$  matrix  $A$  are positive, there is a unique eigenvector to the eigenvalue 1.*

*Proof.* The set  $X = \{\sum_i x_i^2 = 1, x_1 \geq 0, \dots, x_n \geq 0\}$  is closed and bounded. If the entries of  $A$  are non-negative, the map  $T(v) = Av/|Av|$  maps  $X$  to itself. The Brouwer fixed point theorem gives then already fixed point and so an eigenvector to the eigenvalue 1. If  $A$  has positive entries then  $TX$  is even contained in the interior

<sup>1</sup>Sometimes, right stochastic matrices are used. Matrix multiplication is applied to the right to row vectors.

of  $X$ . This fixed point is unique because the map is a **contraction**: There exists  $0 < \lambda(x) < 1$  such that  $d(Tx, Ty) \leq \lambda d(x, y)$ , where  $d$  is the geodesic sphere distance. If there was a contraction with a uniform  $\lambda$  we could have used the Banach fixed point theorem. We do not need it: assume  $T(x) = x$  and  $T(y) = y$  are both fixed points, then the contraction property gives  $d(x, y) = d(Tx, Ty) \leq \lambda(x)d(x, y) < d(x, y)$  a contradiction. We have now a unique fixed point  $Av = \lambda v$  provided  $v$  has non-negative entries. Assume  $Aw = w$  and  $w$  has some negative entry and  $\|w\| = 1$ . Write  $|w|$  for the vector with coordinates  $|w_j|$ . The computation

$$|w|_i = |w_i| = \left| \sum_j A_{ij} w_j \right| \leq \sum_j |A_{ij}| |w_j| = \sum_j A_{ij} |w_j| = (A|w|)_i$$

shows that  $(A|w|)$  is a vector with norm smaller or equal than 1. For any  $i$  with  $w_i < 0$  we have an inequality so that  $\|Aw\| < 1$  contradicting  $\|w\| = 1$ . The only eigenvectors to the eigenvalue 1 must be in  $X$  where we had a unique one.  $\square$

**22.4.**  $T$  is a true contraction with respect to the **Hilbert metric** on  $X$ . One can then use directly the **Banach fixed point theorem**. There is also a connection to ergodic theory. Given an initial measure  $\mu_1$  on  $S$ , the map  $M$  defines measures  $\mu_k$  on  $S$ .

**Theorem 2.** *A Markov chain defines a measure preserving map  $T$  on the product probability space  $(\Omega, \mathcal{A}) = (S^{\mathbb{N}}, \mathcal{B}^{\mathbb{N}}, \prod_k \mu_k)$ .*

*Proof.* The product space  $(\Omega, \mathcal{A}) = (S^{\mathbb{N}}, \mathcal{B}^{\mathbb{N}})$  has the  $\pi$ -system  $\mathcal{C}$  consisting of cylinder-sets  $\prod_{n \in \mathbb{N}} B_n$  given by a sequence  $B_n \in \mathcal{B}$  such that  $B_n = S$  except for finitely many  $n$ . The  $P = P_\mu$  on  $(\Omega, \mathcal{C})$  is the product measure. This measure has a unique extension to the  $\sigma$ -algebra  $\mathcal{A}$ . The shift map  $T$  on  $\Omega$  is measure preserving.  $\square$

**22.5.** If  $M$  has positive entries and  $\mu$  is the stable distribution, then  $T$  is the shift on  $(S^{\mathbb{N}}, \mathcal{B}^{\mathbb{N}}, \mu^{\mathbb{N}})$  and the random variables  $X_i(x) = x_i$  are independent.

**22.6.** For a countable state space  $S$  one is in a random walk situation. The transition matrix  $M_{ij}$  then now a bounded linear operator on  $l^2(S)$ . We have seen in the last lecture that if  $S = \mathbb{Z}^d$  and  $M$  is a scaled version of the adjacency matrix one could use Fourier theory to understand recurrence. In the infinite case like  $S = \mathbb{Z}$ , there is no equilibrium measure. The probability distribution of the walker diffuses like a solution of the heat equation. We can still look at  $M^n \mu$ , where  $\mu$  is an initial probability measure and study its dynamics. On a translational invariant lattice the walk is also a sum of IID random variables  $S_n = X_1 + X_2 + \dots + X_n$ , where  $X_i$  take finitely many values. Since by the central limit theorem, the variance of  $S_n$  grows linearly in time  $n$ , the standard deviation grows like  $\sqrt{n}$ .

**22.7.** Given a finite stochastic matrix  $M$  and a point  $x \in S$ , the measures  $P(x, \cdot)$  are the probability vectors, which are the columns of  $M$ . It is also denoted **Markov field**. We have  $P^n(x, B) = \sum_{y \in B} P^n(x, y)$ . We can see the transition probability functions also as elements in  $\mathcal{L}(S, M_1(S))$ , by thinking about each column as a probability measure in the set  $M_1(S)$  of Borel probability measures on  $S$ . This point of view is often taken in economics.