

# DIFFERENTIAL GEOMETRY

MATH 136

## Lecture 7: Hopf Umlaufsatz

**7.1.** The theorem of today deals with **signed curvature**  $\kappa = \frac{r' \times r''}{|r'|^3}$  using the cross product in 2 dimensions.<sup>1</sup> We do not assume today that the curve is Frenet. The curvature is allowed to become zero. We assume however that the curve is regular, meaning that  $dr = r'$  is never zero, as well as closed. We have seen that there is then an arc length parametrization of the curve and  $|\kappa| = |r''|$  because  $r' \cdot r' = 1$  implies  $r''$  is perpendicular to  $r'$ . We deal with the last curvature and so torsion which always can have signs.

**7.2.** If the curve is parametrized on  $[a, b]$ , the **rotation index** is defined as  $\frac{1}{2\pi} \int_a^b \kappa(t) dt$ . In general, if the closed curve is not arc length parametrized, the rotation index is defined as  $\int_a^b \kappa(t) |r'(t)| dt$ .

**Theorem 1.** *The rotation index of a closed  $C^2$  curve is in  $\mathbb{Z}$ .*

*Proof.* Using arc length parametrization, write

$$r'(t) = [\cos(\alpha(t)), \sin(\alpha(t))]$$

then  $\kappa = \alpha'$  (we did that more detailed in class). Since the curve is closed, we have  $\alpha(b) - \alpha(a) = 2\pi n$ , where  $n$  is an integer.  $\square$

**7.3.** The case  $r(t) = [\cos(nt), \sin(nt)]$  with  $t \in [0, 2\pi]$  shows that the rotation index can take any integer value  $n$ . It is intuitively clear that if a curve has no self intersections, then the index must be either 1 or  $-1$ . This is not so obvious however. We do not want for example to refer to the Jordan curve theorem, telling that a continuous simple closed curve in the plane divides the plane into an inside and outside. Heinz Hopf found a nice argument which proves this "Umlaufsatz" (rotation angle theorem) in an elegant way using a deformation picture:

**Theorem 2** (Hopf Umlaufsatz). *A simple closed regular  $C^2$  curve has rotation index 1 or  $-1$ .*

*Proof.* We assume that  $r(t)$  is parametrized on  $[0, 1]$  and parametrized by arc-length. Define on the square  $Q = [0, 1] \times [0, 1]$  the function  $f : Q \rightarrow \mathbb{T} = \mathbb{R}/(2\pi\mathbb{Z})$  given by  $f(t, s) = \arg((r(t) - r(s))/|r(t) - r(s)|)$  for  $t \neq s$  and  $\alpha(t) = f(t, t) = \arg(r'(t)/|r'(t)|)$  for  $t = s$ . Because  $r \in C^1$ , the function  $f$  is continuous on  $Q = [0, 1] \times [0, 1]$ . Now comes

<sup>1</sup>The cross product in  $n$  dimensions has  $\binom{n}{2} = n(n-1)/2$  components. For  $n = 2$  it is a scalar

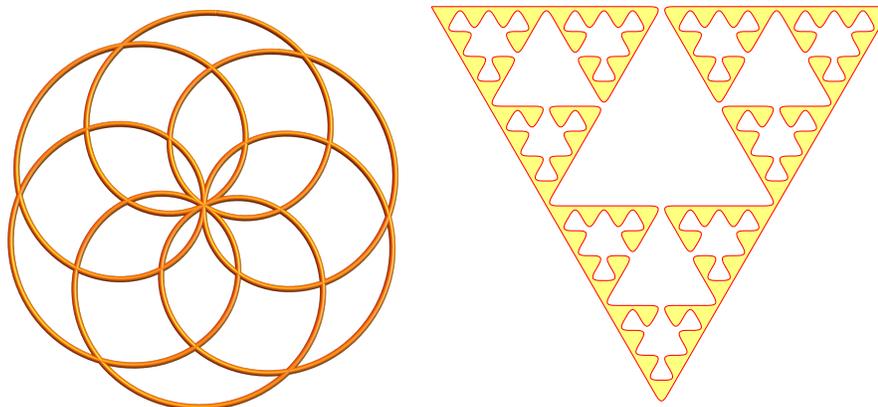


FIGURE 1. To the left, we see  $r(t) = [\cos(t)+\cos(7t), \sin(t)+\sin(7t)], t \in [0, 2\pi]$  which looks like the flower of life. Its rotation number is 7. We can compute  $\kappa(t)|r'(t)| = 4 + 72/(25 + 8 \cos(6t))$  which integrates on  $[0, 2\pi]$  up to  $14\pi$ . To the right, a simple closed smooth curve in the plane. What is its rotation number?

a **homotopy argument**. The index is  $[f(1, 1) - f(0, 0)]/(2\pi)$  and so an integer. If we move along the diagonal and look at  $\alpha(t) = f(t, t)$  we see a continuous curve which moves on the circle  $\mathbb{T}$ . If we deform the curve, the total change remains the same. We can continuously deform the parameter curve so that we first deform from  $(0, 0)$  straight to  $(0, 1)$  and then straight from  $(0, 1)$  to  $(1, 1)$ . Choose a coordinate system so that is in  $y \geq 0$  just touching the  $x$ -axes. If  $r'(0) = [a, 0]$  with positive  $a$  then  $f(t, s) \in [0, \pi]$  with  $f(0, 0) = 0$  and  $f(0, 1) = \pi$  and then  $f(1, 1) = 2\pi$ . If  $a < 0$ , then  $f(t, s) \in [-\pi, 0]$  with  $f(0, 0) = \pi$  and  $f(0, 1) = 0$  and then  $f(1, 1) = -\pi$ . In the former case,  $i = 1$  in the later  $i = -1$ .  $\square$

**7.4. Remarks:**

- 1) This is a Gauss-Bonnet type result for a flat 2-manifold with boundary.
- 2) The proof shows that this even works for  $C^1$  curves as  $f(t, t) - f(s, s)$  is just the angle change of the tangent. This works even if the curvature is not defined. In the homework you will push it to polygons. Most texts assume  $C^2$ .
- 3) Closed  $C^0$  curves are trickier: Jordan curve theorem, open peg problem of Toeplitz.

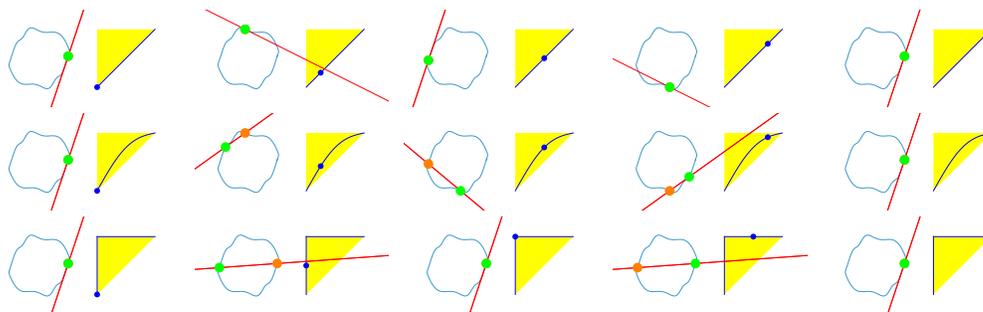


FIGURE 2. The deformation argument.