

# DIFFERENTIAL GEOMETRY

MATH 136

## Homework 7

This is the seventh homework. It is due Friday, October 31st:

**Problem 1:** Assume you make a trip and your effort is  $F(x, \dot{x}) = x^2 \dot{x}^2$  rather than the kinetic energy  $\dot{x}^2$  because things are easy initially but get harder later on. What is the best strategy to reach from  $x(0) = 0$  to  $x(1) = 1$ ? Go slow first or go fast first? In order to find the best way, solve the Euler-Lagrange problem to minimize the action

$$E(x) = \int_0^1 F(x, \dot{x}) dt$$

for  $F(x, \dot{x}) = x^2 \dot{x}^2$  with  $x(0) = 0, x(1) = 1$ .

**Problem 2:** Look at the paraboloid  $r(u, v) = [u, v, u^2 + v^2]$ .

a) Compute all the Christoffel symbols  $\Gamma_{ijk}$ . These are 8 terms. (Do this by hand). b) Now compute all the Christoffel symbols  $\Gamma_{ij}^k$ . (Also here, do this by hand. There is Mathematica code which can be used for the last problem).

**Problem 3:** A geodesic  $x(t)$  is called **closed**, if there exists  $L$  such that  $x(L) = x(0)$  and  $\dot{x}(L) = \dot{x}(0)$ . It is a closed curve on  $M$  for which also initial and end velocities agree. Note that the curve  $x$  does not have to be simple. Two closed geodesics  $x_1(t), x_2(t)$  are called **homotopic**, if one can deform them to each other on the manifold. Formally this means to parametrize both on  $[a, b] = [0, 1]$  and then give a continuous  $F(t, s)$  of two variables, such that  $F(t, 0) = x_1(t)$  and  $F(t, 1) = x_2(t)$  and  $t \rightarrow x_s(t) = F(t, s)$  is on the manifold. We verify here that on any torus, there are infinitely many geodesics that are pairwise not homotopic to each other.

- Invent and then define a “winding vector”  $(n, m) \in \mathbb{Z}^2$ .
- Verify that this number is the same for two closed curves that are homotopic.
- Draw a torus and a geodesic for winding number  $(4, 5)$ .
- Verify that there each homotopy class is not empty by telling how to write one.
- Argue why there is at least one geodesic in each homotopy class.

**Problem 4:** We draw some wave fronts  $W_r(p)$  on the flat Clifford torus  $\mathbb{R}^2/\mathbb{Z}^2$  (Pac-Man square). This manifold can be realized as all point  $(x, y)$  in  $\mathbb{R}^2$ , where points  $(x, y), (x + n, x + m)$  identified if  $n, m \in \mathbb{Z}$ . Work with the point  $p = (1/2, 1/2)$ .

- Draw the wave front  $W_{1/2}(p)$ .
- Draw the wave front  $W_1(p)$ .
- Draw the wave front  $W_5(p)$ .

You are welcome to become physical part c and use scissor, ruler and compass to do that).

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**Problem 5:** The torus

$$r(u, v) = ((a + b \cos(v)) \cos(u), (a + b \cos(v)) \sin(u), b \sin(v)) ,$$

has the metric

$$\begin{aligned} g_{11} &= (a + b \cos(v))^2 \\ g_{22} &= b^2 \\ g_{12} &= g_{21} = 0 \end{aligned}$$

Use the following example code (done for the sphere) to compute all the Christoffel symbols  $\Gamma_{ij}^k$ . Make sure to simplify.

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r={Sin [v] Cos [u] , Sin [v] Sin [u] , Cos [v] } ;
ru=D[r , u] ;          rv=D[r , v] ;
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<sup>1</sup>See a project done with Emily Kang during Summer 2024

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n=Cross[ru,rv]; n=n/Sqrt[n.n];
nu=D[n,u]; nv=D[n,v];
drT={ru,rv}; dr=Transpose[drT];
g=drT.dr; gi=Inverse[g];
dnT={nu,nv}; dn=Transpose[dnT];
h=-dnT.dr; e=dnT.dn;
K=Det[h]/Det[g];
X={u,v}; d=2;
c[i_,j_,k_-]:=(D[g[[j,k]],X[[i]]]
+D[g[[k,i]],X[[j]]]
-D[g[[i,j]],X[[k]]])/2;
Christoffel[i_,j_,k_-]:=Sum[gi[[k,l]]*c[i,j,l],{l,d}];
S=Table[Simplify[Christoffel[i,j,k]],{i,d},{j,d},{k,d}];
TableForm[S]

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