

## MATH 21b Practice Questions

### Problem 1.

Circle T if the given assertion is true, and circle F if it is false. There is no need to justify your answer.

- T F** a) Let  $A = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$  and  $B = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ . Then  $AB = BA$ .
- T F** b) Suppose  $\vec{u}$  is a non-zero vector in  $\mathbb{R}^n$ . The map of  $\mathbb{R}^n$  to itself that sends any given vector  $\vec{v}$  to  $T(\vec{v}) = \vec{v} + \vec{u}$  is a linear transformation.
- T F** c) For any square matrix  $A$ , the kernel of  $A^2$  is a subspace of the kernel of  $A^3$ .
- T F** d) If  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  and  $S: \mathbb{R}^m \rightarrow \mathbb{R}^n$  are linear transformations such that the kernel of  $S$  has dimension greater than zero, then the kernel of  $ST$  must have dimension greater than zero.
- T F** e) If a system of linear equations has more unknowns than equations, there are always an infinite number of solutions.
- T F** f) If the product of two matrices is 0, then one or the other must also be 0.
- T F** g) If  $A$  is a matrix, then  $\ker(A)$  must be the same subspace as  $\ker(\text{rref}(A))$ .
- T F** h) If  $A$  is a matrix, then  $\text{image}(A)$  must be the same as  $\text{image}(\text{rref}(A))$ .
- T F** i) If  $A$  is a square matrix with linearly independent columns, then the rows are also linearly independent vectors.
- T F** j) A linear transformation of  $\mathbb{R}^2$  cannot send  $\begin{pmatrix} 6 \\ -9 \end{pmatrix}$  to  $\begin{pmatrix} 2 \\ -3 \end{pmatrix}$  and  $\begin{pmatrix} -2 \\ 3 \end{pmatrix}$  to  $\begin{pmatrix} -2 \\ 1 \end{pmatrix}$ .

### Problem 2.

Let  $T$  denote a linear transformation of  $\mathbb{R}^2$  that sends  $\begin{pmatrix} 1 \\ -3 \end{pmatrix}$  to  $\begin{pmatrix} 1 \\ -2 \end{pmatrix}$  and  $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$  to  $\begin{pmatrix} 0 \\ -1 \end{pmatrix}$ .

- a) What are the coordinates of  $\begin{pmatrix} 0 \\ -1 \end{pmatrix}$  with respect to the basis  $\vec{v}_1 = \begin{pmatrix} 1 \\ -3 \end{pmatrix}$  and  $\vec{v}_2 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ .
- b) Write down the matrix of  $T$  with respect to the basis  $\vec{v}_1 = \begin{pmatrix} 1 \\ -3 \end{pmatrix}$  and  $\vec{v}_2 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$ .
- c) Write down the matrix of  $T$  with respect to the standard basis,  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ .

**Problem 3.**

Let A denote the matrix  $\begin{pmatrix} 1 & 2 & 0 & 2 & 5 \\ 1 & 2 & 1 & -1 & 0 \\ 2 & 4 & -1 & 1 & 3 \\ 3 & 6 & -1 & -1 & 0 \end{pmatrix}$ .

- a) Compute  $\text{rref}(A)$ .
- b) Give a basis for  $\text{kernel}(A)$ .
- c) Give a basis for  $\text{image}(A)$ .
- d) What is the dimension of  $\text{kernel}(A^T)$ ?

**Problem 4.**

Let A denote the matrix  $\begin{pmatrix} 1 & 2 \\ 0 & 1 \\ -1 & 0 \end{pmatrix}$ .

- a) Give an orthonormal basis for the image of A.
- b) Give the matrix T (with respect to the standard basis of  $\mathbb{R}^3$ ) that represents the orthogonal projection onto the image of A.
- c) Let  $\vec{v}_1, \vec{v}_2$  denote any orthonormal basis for  $\text{image}(A)$ , and let  $\vec{v}_3$  denote a unit length vector that is orthogonal to  $\text{image}(A)$ . Find the matrix with respect to the basis  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  for the orthogonal projection to  $\text{image}(A)$ .
- d) Write a non-zero vector that is orthogonal to  $\text{image}(A)$ .
- e) Write down the matrix (with respect to the standard basis of  $\mathbb{R}^3$ ) that represents the orthogonal projection onto the orthogonal complement of  $\text{image}(A)$ .

**Problem 5.**

Let  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  denote the linear transformation whose matrix with respect to the

standard basis of  $\mathbb{R}^3$  is  $A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 2 \\ 3 & 1 & 2 \end{pmatrix}$ . Meanwhile, let  $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix}$ ,  $\vec{v}_2 = \begin{pmatrix} 1 \\ 1 \\ 3 \end{pmatrix}$ ,  $\vec{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ .

- a) Compute  $A^2$ .
- b) Prove that  $\vec{v}_1, \vec{v}_2$ , and  $\vec{v}_3$  are a basis for  $\mathbb{R}^3$ .
- c) Write down the vector  $A\vec{v}_1$ .

## Answers

1. a) F b) F c) T d) F e) F f) F g) T h) F i) T j) T.

2. a)  $\bar{v}_1 + \bar{v}_2$  b)  $\begin{pmatrix} 0 & 1 \\ -1 & 1 \end{pmatrix}$  c)  $\begin{pmatrix} -2 & -1 \\ 7 & 3 \end{pmatrix}$ .

3. a)  $\begin{pmatrix} 1 & 2 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$  b)  $\begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ -1 \\ -2 \\ 1 \end{pmatrix}$  c) The last 3 columns of A span the image

d) Since the kernel of  $A^T$  is the orthogonal complement to the image of A, and the image of A has dimension 3, the kernel of  $A^T$  has dimension 2.

4. a)  $\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$  and  $\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ .

b)  $T = \frac{1}{6} \begin{pmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{pmatrix}$ .

c) The matrix is  $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ .

d)  $\bar{v} = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$ .

e) The matrix is  $\frac{1}{6} \begin{pmatrix} 1 & -2 & 1 \\ -2 & 4 & -2 \\ 1 & -2 & 1 \end{pmatrix}$

5. a)  $A^2 = \begin{pmatrix} 14 & 11 & 13 \\ 14 & 15 & 16 \\ 11 & 11 & 15 \end{pmatrix}.$

b) To prove that they are linearly independent, suppose  $c_1\vec{v}_1 + c_2\vec{v}_2 + c_3\vec{v}_3 = \mathbf{0}$ . The middle entry of vector on the left side is  $c_2 + c_3$ , so  $c_2 = -c_3$ . This means that the top entry of the vector on the left is  $c_1$  and so  $c_1 = 0$ . If  $c_1 = 0$  and if  $c_2 = -c_3$ , then the bottom entry on the left side is  $3c_2 - c_2 = 2c_2$ , so  $c_2 = 0$ . Thus  $c_3 = 0$  also.

c)  $A\vec{v}_1 = \begin{pmatrix} 7 \\ 6 \\ 7 \end{pmatrix}$