

Math 53 Homework 10 – Solutions

16.1 # 11: $\vec{F}(x, y) = \langle x, -y \rangle$ corresponds to graph IV. In the first quadrant all the vectors have positive x -components and negative y -components, in the second quadrant they have negative x - and y -components, etc. Also, the vectors get shorter as we approach the origin.

16.1 # 13: $\vec{F}(x, y) = \langle y, y + 2 \rangle$ corresponds to graph I since the vectors are independent of x (the vectors along horizontal lines are all identical) and, as y increases (towards the top of the diagram), both the x - and the y -components get larger.

16.1 # 18: $\vec{F}(x, y, z) = \langle x, y, z \rangle$ corresponds to graph II: each vector $\vec{F}(x, y, z)$ has the same length and direction as the position vector of the point (x, y, z) , and therefore the vectors all point directly away from the origin.

16.1 # 23: $\nabla f = \langle f_x, f_y, f_z \rangle = \left\langle \frac{x}{\sqrt{x^2 + y^2 + z^2}}, \frac{y}{\sqrt{x^2 + y^2 + z^2}}, \frac{z}{\sqrt{x^2 + y^2 + z^2}} \right\rangle = \langle x, y, z \rangle / \sqrt{x^2 + y^2 + z^2}$. This vector has the same direction as $\langle x, y, z \rangle$ (= position vector of the point (x, y, z)), so points directly away from the origin (“radially”); while its magnitude is $(x^2 + y^2 + z^2)^{-1/2} |\langle x, y, z \rangle| = 1$. So $\nabla f(x, y, z)$ is the unit vector in the direction of $\langle x, y, z \rangle$ (pointing directly away from the origin).

16.1 # 31: $f(x, y) = (x + y)^2 \Rightarrow \nabla f = \langle 2(x + y), 2(x + y) \rangle = 2(x + y)(\hat{i} + \hat{j})$. So all the vectors are parallel to $\hat{i} + \hat{j}$; they vanish on the line $x + y = 0$ (or $y = -x$), and their magnitude increases with the distance to that line. This corresponds to plot II.

16.2 # 1: $x = t^2$ and $y = 2t$, so $\int_C y \, ds = \int_0^3 2t \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt = \int_0^3 2t \sqrt{(2t)^2 + 2^2} dt = \int_0^3 4t \sqrt{t^2 + 1} dt = \left[\frac{4}{3} (t^2 + 1)^{3/2} \right]_0^3 = \frac{4}{3} (10^{3/2} - 1)$.

16.2 # 3: Parametric equations for C are $x = 4 \cos t$, $y = 4 \sin t$, $-\frac{\pi}{2} \leq t \leq \frac{\pi}{2}$. So $\int_C xy^4 \, ds = \int_{-\pi/2}^{\pi/2} (4 \cos t)(4 \sin t)^4 \sqrt{(-4 \sin t)^2 + (4 \cos t)^2} dt = \int_{-\pi/2}^{\pi/2} 4^6 \cos t \sin^4 t \, dt = 4^6 \left[\frac{1}{5} \sin^5 t \right]_{-\pi/2}^{\pi/2} = \frac{2}{5} 4^6 = \frac{2^{13}}{5} = \frac{8192}{5}$.

16.2 # 17: (a) Along the line $x = -3$, the vectors of \vec{F} have positive y -components; since the path goes upward, the integrand $\vec{F} \cdot \hat{T}$ is always positive. So $\int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot \hat{T} \, ds > 0$. (b) Along the circle C_2 , the field vectors are all pointing in the clockwise direction, i.e., opposite the direction of the path. So $\vec{F} \cdot \hat{T} < 0$, and therefore $\int_{C_2} \vec{F} \cdot d\vec{r} = \int_{C_2} \vec{F} \cdot \hat{T} \, ds < 0$.

16.2 # 20: $x = t^2$, $y = t^3$, $z = -2t$, so $dx = 2t \, dt$, $dy = 3t^2 \, dt$, $dz = -2 \, dt$. Hence

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C (x + y^2) dx + xz dy + (y + z) dz \\ &= \int_0^2 (t^2 + t^6)(2t) dt + (-2t^3)(3t^2) dt + (t^3 - 2t)(-2) dt \\ &= \int_0^2 (4t - 6t^5 + 2t^7) dt = \left[2t^2 - t^6 + \frac{1}{4}t^8 \right]_0^2 = 2^3 - 2^6 + \frac{1}{4}2^8 = 8. \end{aligned}$$

16.2 # 32: (a) We parametrize the circle C by: $x = 2 \cos t$, $y = 2 \sin t$, $0 \leq t \leq 2\pi$. So $dx = -2 \sin t \, dt$, $dy = 2 \cos t \, dt$, and

$$\begin{aligned}\int_C \vec{F} \cdot d\vec{r} &= \int_C x^2 dx + xy dy = \int_0^{2\pi} (2 \cos t)^2 (-2 \sin t) dt + (4 \cos t \sin t) (2 \cos t) dt \\ &= \int_0^{2\pi} (-8 \cos^2 t \sin t + 8 \cos^2 t \sin t) dt = \int_0^{2\pi} 0 dt = 0.\end{aligned}$$

(b) The vector $\vec{F}(x, y) = x^2\hat{i} + xy\hat{j} = x(x\hat{i} + y\hat{j})$ is parallel to the position vector $x\hat{i} + y\hat{j}$ of the point (x, y) , so it always points in the radial direction (straight away from the origin if $x > 0$, towards the origin if $x < 0$). (This can be seen on a plot). So, at every point of the circle C , the vector $\vec{F}(x, y)$ is perpendicular to the circle, hence the field does no work on the moving particle. In other words, $\vec{F} \cdot \hat{T} = 0$ at any point along C , and so $\int_C \vec{F} \cdot d\vec{r} = 0$.

16.2 # 42: The line segment from $(2, 0, 0)$ to $(2, 1, 5)$ has parametric equations $x = 2$, $y = t$, $z = 5t$ for $0 \leq t \leq 1$; also, $\vec{F} = K\vec{r}/|\vec{r}|^3 = K(x^2 + y^2 + z^2)^{-3/2}\langle x, y, z \rangle$. So:

$$\begin{aligned}\int_C \vec{F} \cdot d\vec{r} &= \int_C K \frac{x dx + y dy + z dz}{(x^2 + y^2 + z^2)^{3/2}} = K \int_0^1 \frac{(2)(0) dt + (t)(1) dt + (5t)(5) dt}{(4 + t^2 + (5t)^2)^{3/2}} = \\ &= K \int_0^1 \frac{26t dt}{(4 + 26t^2)^{3/2}} = K \left[\frac{-1}{(4 + 26t^2)^{1/2}} \right]_0^1 = K \left(\frac{1}{2} - \frac{1}{\sqrt{30}} \right).\end{aligned}$$

Problem 1: $\int_C \vec{F} \cdot d\vec{r} = \int_C (x^2 y + \frac{1}{3} y^3) dx = \int_{x_1}^{x_2} \left(x^2 f(x) + \frac{1}{3} f(x)^3 \right) dx$, and

$$\begin{aligned}\iint_R (x^2 + y^2) dA &= \int_{x_1}^{x_2} \int_0^{f(x)} (x^2 + y^2) dy dx = \int_{x_1}^{x_2} \left[x^2 y + \frac{1}{3} y^3 \right]_0^{f(x)} dx \\ &= \int_{x_1}^{x_2} \left(x^2 f(x) + \frac{1}{3} f(x)^3 \right) dx.\end{aligned}$$

These two integrals are therefore equal.

16.3 # 7: $\frac{\partial}{\partial y}(ye^x + \sin y) = e^x + \cos y = \frac{\partial}{\partial x}(e^x + x \cos y)$, and \vec{F} is defined in the entire plane (simply connected), so \vec{F} is conservative. So there is a function f such that $\nabla f = \vec{F}$, i.e. $f_x = ye^x + \sin y$ and $f_y = e^x + x \cos y$.

Integrating with respect to x , $f_x(x, y) = ye^x + \sin y$ implies $f(x, y) = ye^x + x \sin y + g(y)$ for some function $g(y)$; differentiating both sides of this equation with respect to y gives $f_y = e^x + x \cos y + g'(y)$. Thus we should have $g'(y) = 0$, and $g(y) = c$ is a constant. Hence $f(x, y) = ye^x + x \sin y + c$.

16.3 # 15: a) $f_x(x, y, z) = yz$ implies $f(x, y, z) = xyz + g(y, z)$, and so $f_y(x, y, z) = xz + g_y(y, z)$. But $f_y(x, y, z) = xz$, so $g_y(y, z) = 0$, and (integrating with respect to y) $g(y, z) = h(z)$. Thus $f(x, y, z) = xyz + h(z)$, and $f_z(x, y, z) = xy + h'(z)$. But $f_z(x, y, z) = xy + 2z$, so $h'(z) = 2z$, and hence $h(z) = z^2 + c$. Thus (taking $c = 0$), one potential function is $f(x, y, z) = xyz + z^2$.

b) By the fundamental theorem, $\int_C \vec{F} \cdot d\vec{r} = f(4, 6, 3) - f(1, 0, -2) = 81 - 4 = 77$.

16.3 # 19: $\frac{\partial}{\partial y}(2xe^{-y}) = -2xe^{-y} = \frac{\partial}{\partial x}(2y - x^2e^{-y})$, and these quantities are continuously differentiable in the whole plane (simply connected). Thus the line integral $\int_C 2xe^{-y} dx + (2y - x^2e^{-y}) dy$ is path-independent and can be computed using the fundamental theorem for line integrals. We first determine a potential function f such that $\nabla f = \langle 2xe^{-y}, 2y - x^2e^{-y} \rangle$.

The equation $f_x = 2xe^{-y}$ implies that $f(x, y) = x^2e^{-y} + g(y)$ for some function $g(y)$. Hence $f_y = -x^2e^{-y} + g'(y) = 2y - x^2e^{-y}$, and so $g'(y) = 2y$, i.e. $g(y) = y^2 + c$. Thus $f(x, y) = x^2e^{-y} + y^2$ is a potential function. Therefore, given any path C from $(1,0)$ to $(2,1)$, the line integral is equal to $f(2,1) - f(1,0) = (4e^{-1} + 1) - 1 = 4e^{-1}$.

16.3 # 25: We know that if the vector field (call it \vec{F}) is conservative, then around any closed path C we must have $\int_C \vec{F} \cdot d\vec{r} = 0$. However, take C to be a circle centered at the origin, oriented counterclockwise. Then all of the field vectors along C point forward (have a positive tangential component), so $\int_C \vec{F} \cdot d\vec{r} > 0$. Therefore the field is not conservative.

Problem 2. a) For $\theta(x, y) = \tan^{-1}(y/x)$:

$$\frac{\partial \theta}{\partial x} = \frac{1}{1 + (y/x)^2} \frac{-y}{x^2} = -\frac{y}{x^2 + y^2}, \text{ and } \frac{\partial \theta}{\partial y} = \frac{1}{1 + (y/x)^2} \frac{1}{x} = \frac{x}{x^2 + y^2}; \text{ so } \nabla \theta = \vec{F}.$$

b) Because $\theta(x, y) = \tan^{-1}(y/x)$ is well-defined in the right half-plane ($x > 0$) and $\vec{F} = \nabla \theta$, the fundamental theorem for line integrals implies $\int_C \vec{F} \cdot d\vec{r} = \theta(x_2, y_2) - \theta(x_1, y_1) = \theta_2 - \theta_1$.

$$c) \int_{C_1} \vec{F} \cdot d\vec{r} = \int_{C_1} \frac{-y dx + x dy}{x^2 + y^2} = \int_0^\pi \frac{(-\sin \theta)(-\sin \theta) + \cos \theta \cos \theta}{\cos^2 \theta + \sin^2 \theta} d\theta = \int_0^\pi d\theta = \pi.$$

$$\text{Similarly, } \int_{C_2} \vec{F} \cdot d\vec{r} = \int_0^{-\pi} d\theta = -\int_{-\pi}^0 d\theta = -\pi.$$

(Or geometrically: $\text{length}(C_1) = \text{length}(C_2) = \pi$, $\vec{F} \cdot \hat{T} = 1$ on C_1 ; $\vec{F} \cdot \hat{T} = -1$ on C_2)

d) \vec{F} is defined everywhere except at the origin, but is not conservative over its entire domain of definition. Indeed, the two line integrals computed in (c) both run from $(1,0)$ to $(-1,0)$ but they are not equal, so path-independence fails. On the other hand, \vec{F} is conservative over the half-plane $x > 0$, where $\vec{F} = \nabla \theta$ and the fundamental theorem of calculus gives a formula for the line integral involving only the values of θ at the end points (as seen in (b)).

Note: even though $P_y = Q_x$ at every point where \vec{F} is defined, we cannot conclude that \vec{F} is the gradient of a well-defined potential function everywhere! This would only be true if \vec{F} were defined over the entire plane (or more generally, a *simply connected region*). In fact, we can find a potential function for \vec{F} over smaller regions such as the right half-plane $x > 0$ (namely, the polar angle θ). However, if we consider the entire plane with just the origin removed, the polar angle coordinate θ is not well-defined as a single-valued differentiable function: its value “jumps” by 2π as we go around the origin. This is what causes conservativeness to fail.

Problem 3: a) If $\vec{F} = r^n(x\hat{i} + y\hat{j}) = P\hat{i} + Q\hat{j}$ then

$$Q_x = \frac{\partial(yr^n)}{\partial x} = nyr^{n-1} \frac{x}{r}, \text{ while } P_y = \frac{\partial(xr^n)}{\partial y} = nxr^{n-1} \frac{y}{r}. \text{ So } P_y = Q_x.$$

(Recall $r = \sqrt{x^2 + y^2}$ gives $r_x = \frac{x}{\sqrt{x^2 + y^2}} = \frac{x}{r}$, and similarly $r_y = \frac{y}{r}$.)

b) If $g = g(r)$, then $g_x = g'(r) \frac{x}{r}$ and $g_y = g'(r) \frac{y}{r}$ (by the chain rule).

So $\nabla g = \frac{g'(r)}{r}(x\hat{i} + y\hat{j})$. We must find g such that $g'(r)/r = r^n$, i.e. $g'(r) = r^{n+1}$.

Two cases: $n \neq -2$: $g(r) = \frac{1}{n+2} r^{n+2}$. $n = -2$: $g(r) = \ln(r)$.